Temporal effects in EIT image reconstructions

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Introduction

- Introduction
- Methods
- Results
- Discussion and Conclusion

- Reconstruction Algs assume that:
 - Conductivity distribution does not change during acquisition of an EIT data frame;
 - Successive EIT frames are not correlated.
- However, in reality, frames are correlated
- Methods to account for temporal effects:
 - Kalman filter
 - Temporal EIT reconstruction
 - Interpolation of EIT measurements
- Our questions:
 - When do we need to worry about artefacts?
 - How much do algorithms help?

Frequency domain representation

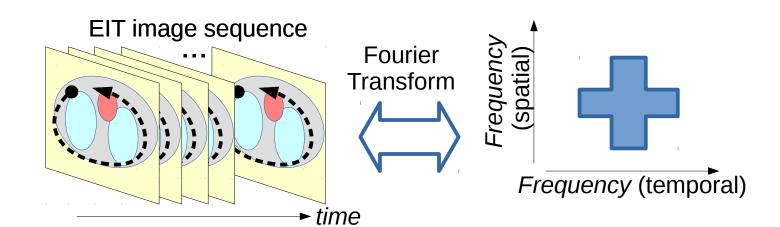




Methods

Results

Discussion and Conclusion



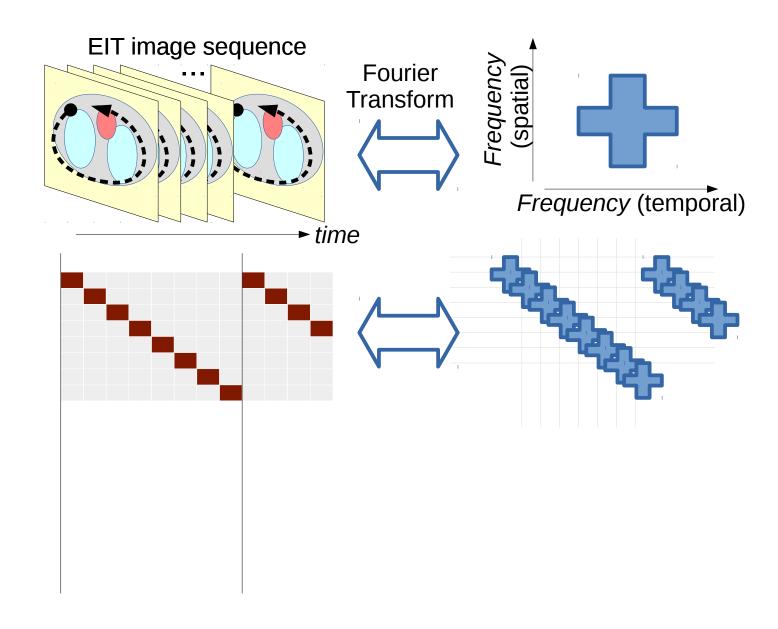
Frequency domain representation



Methods

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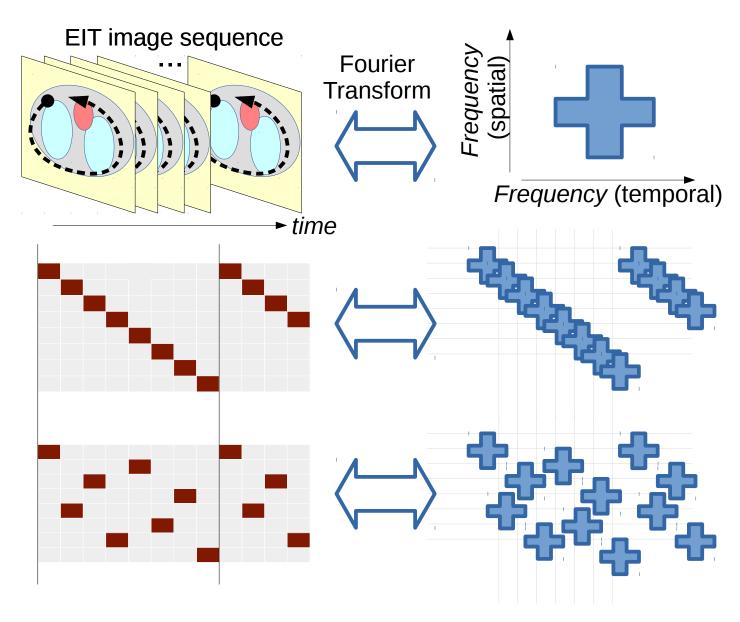
Frequency domain representation



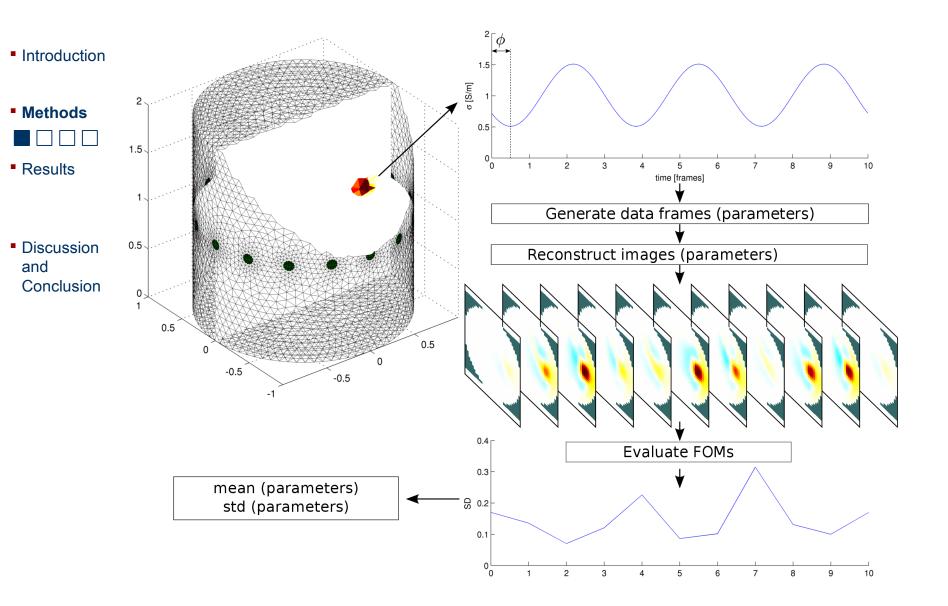
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Overview of the method



Types of EIT frames

- Introduction
- Perfect EIT frames:
- Methods
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- $v_{p}(nT_{f}) = \begin{bmatrix} f_{1}[\sigma(nT_{f})] \\ \vdots \\ f_{n_{m}}[\sigma(nT_{f})] \end{bmatrix}$
- Realistic EIT frames:

$$v_{\rm r}(nT_{\rm f}) = \begin{bmatrix} f_1[\sigma(nT_{\rm f})] \\ \vdots \\ f_{n_{\rm m}}[\sigma(nT_{\rm f} + (n_{\rm m} - 1)T_{\rm m})] \end{bmatrix}$$

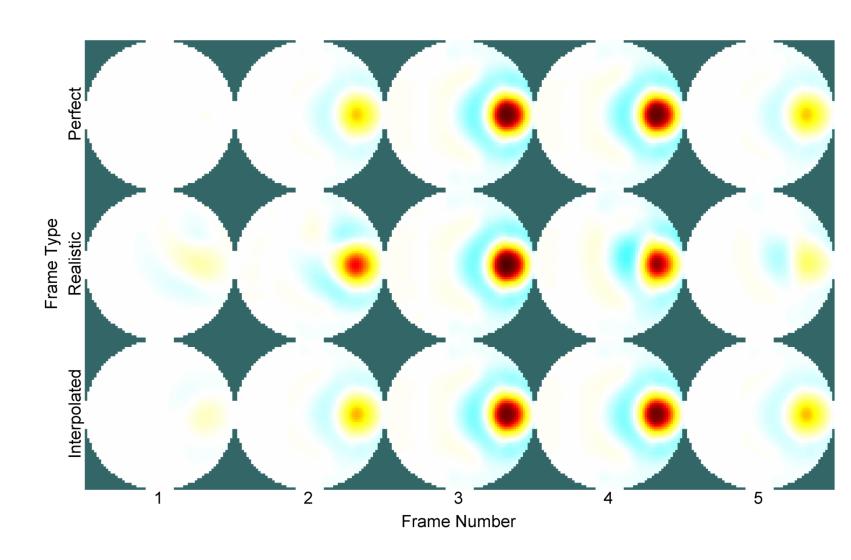
Interpolated EIT frames:

$$[v_{i}(nT_{f})]_{i} = \frac{(i-1)[v_{r}((n-1)T_{f})]_{i} + (n_{m}-i+1)[v_{r}(nT_{f})]_{i}}{n_{m}}$$

One cycle of conductivity variation

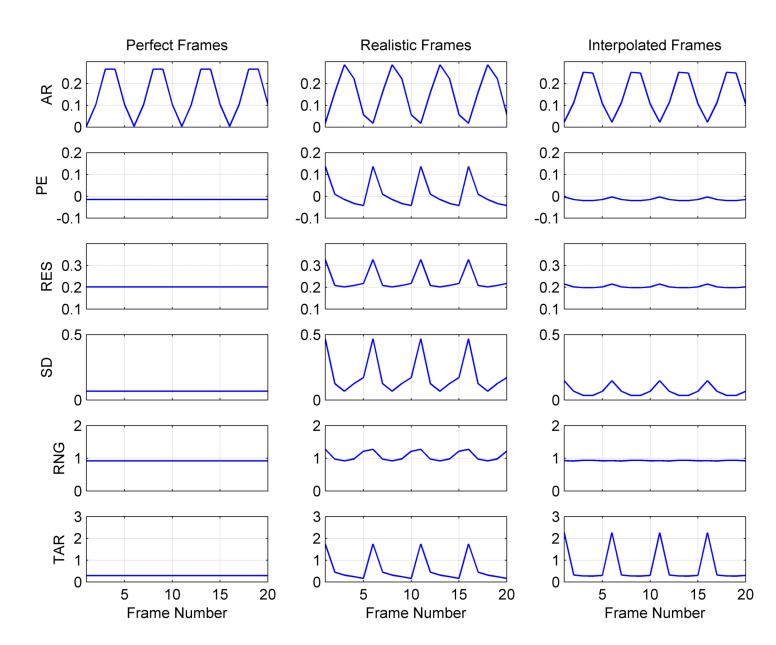


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FOM as a function of time

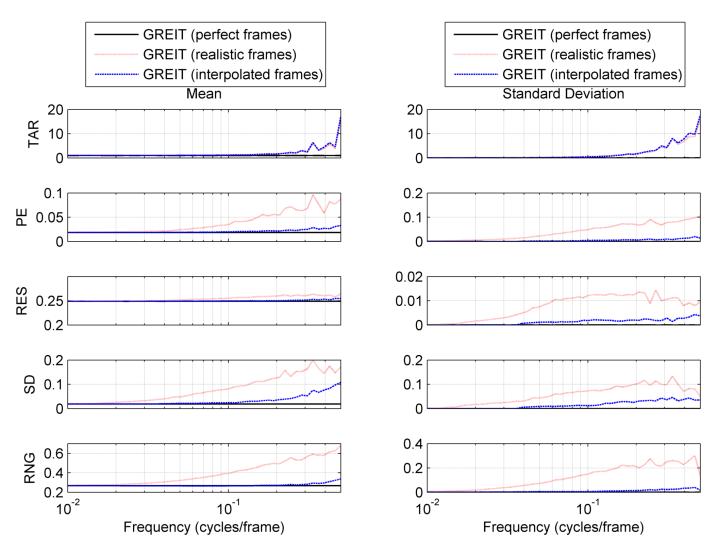
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FOM as a function of frequency

FOM as a function of frequency (cycles/frame)
Radius = 0.666667; Phase = 0; Number of cycles = 4; SNR = Inf;

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Conclusion

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- Temporal artefacts and FOM worsening observed as low as 50× below frame rate.
- No clear winner among the proposed techniques to account for temporal effects.
 - The performance of most algorithms could be optimized for particular scenarios.
- The proposed framework is useful for:
 - Observing temporal effects and artefacts;
 - Designing the next generation of algorithms accounting for temporal effects.

Thank you!

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