EIDORS VERSION 3.8

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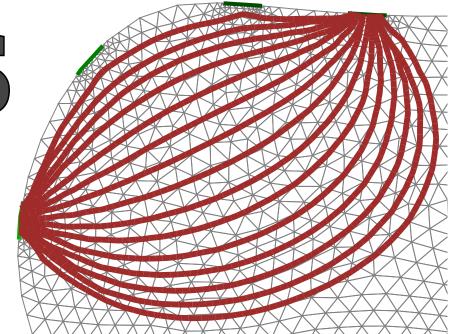
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NEW RELEASE

We are pleased to announce the release of EIDORS 3.8 [1]. The software is available at www.eidors.org licensed under the GNU GPLv2 (or GPLv3).

EIDORS version 2



EIDORS aims to provide free software algorithms for forward modelling and inverse solutions of Electrical Impedance and (to some extent) Diffusion-based Optical Tomography, in medical, industrial and geophysical settings and to share data and promote collaboration.

NEW FEATURES

Release 3.8 of EIDORS builds upon a strong foundation in reconstruction algorithms, adding and improving a number of aspects.

- More stable iterative absolute inverse solvers (both Gauss-Newton and Conjugate-Gradient).
- Greater flexibility in parametrization choices.
- Native handling of unit scaling $(10^x, e^x, \ln x, \log_{10} x)$, and arbitrary units. Natural limits for $\sigma > 0$.
- GREIT reconstructions in 3D
- Speed optimizations: improved Jacobian calculation, faster cache handling, and faster forward solutions.
- Improved interfaces to NetGen and visualization. Compound and point electrodes in NetGen.
- Analytic calculation of dual-mesh interpolations (coarse to fine)
- Support for second and third order mesh elements.
- Support for Dräger and Swisstom file formats
- Expanded shape library

REFERENCES

- [1] Adler A, Boyle A, Crabb MG et al, *EIDORS v3.8*, Zenodo, DOI:10.5281/zenodo.17559, 2015.
- [2] Vauhkonen M, Lionheart WRB, Heikkinen L et al, *Physiol Meas*, 22:107–111, 2001.
- [3] Polydorides N, Image Reconstruction Algorithms for Soft-Field Tomography, Ph.D. thesis, University of Manchester, UK, 2002.
- [4] Polydorides N, Lionheart WRB, Meas Sci and Tech, 13:1871–1883, 2002.
- [5] Adler A, Lionheart WRB, Physiol Meas, 27:S25–S42, 2006.

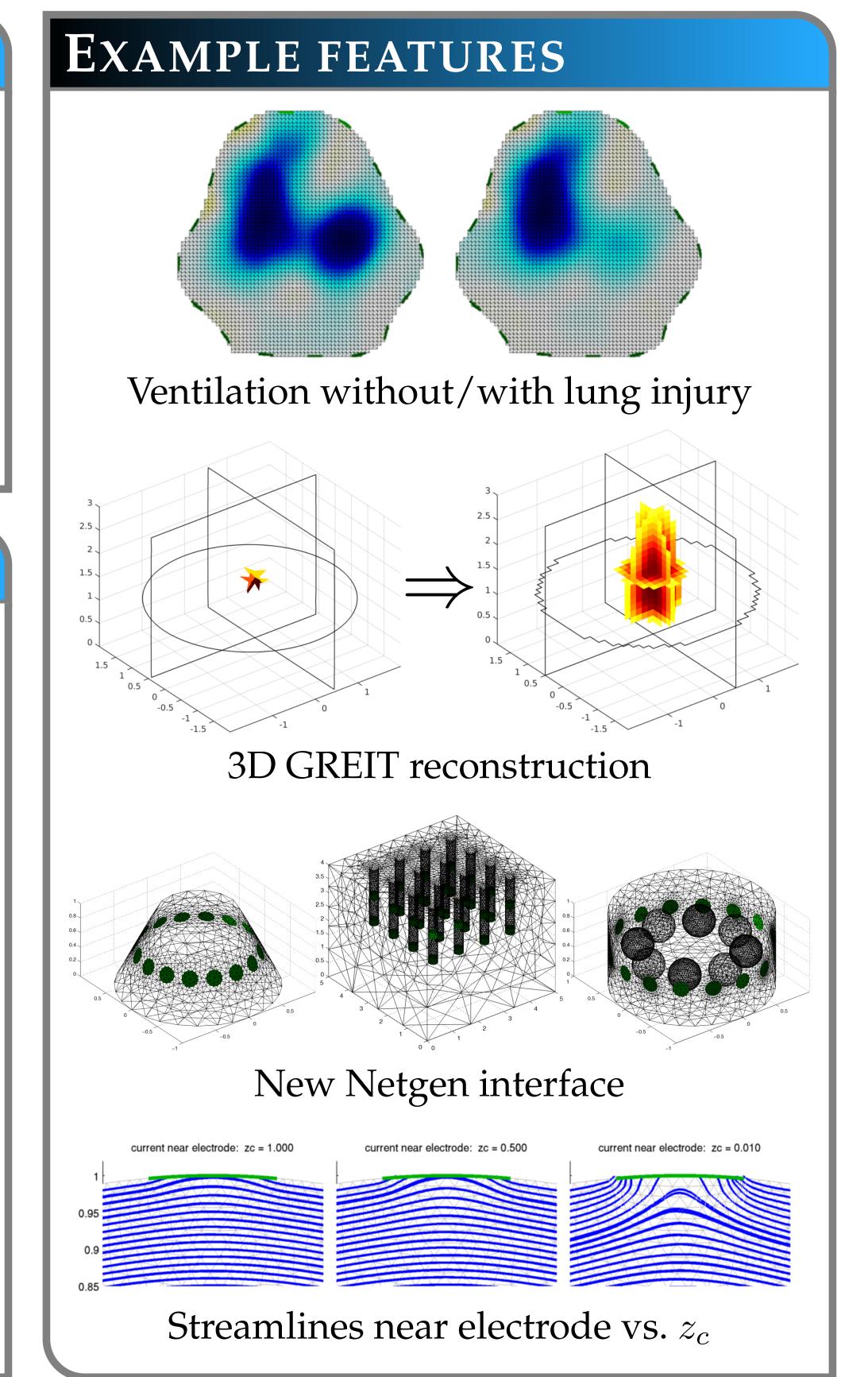
SUCCESSES

The structure of EIDORS has been relatively stable due, in part, to some early design choices: a modular framework and data structure, cross-platform support, integration of meshing, tutorials, and the contributed data repository. These aspects, along with an open source code-base, have enabled EIDORS to maintain research relevance.

CHALLENGES

A number of challenges inherent in the implementation of EIDORS as a Matlab-based toolkit continue to recur. There is no real Object Oriented framework: no reflection, protection, or automatic management of errors. Versions of Matlab frequently vary in confounding ways that make maintaining a toolkit across multiple Matlab versions difficult. This is particularly prevalent for Windows users and "mex" file compilation. The data structure and subfunction complexity in EIDORS are a source of confusion for beginners.

Despite these challenges, EIDORS continues to develop, grow and expand into new areas. Presenting version 3.8!



GROWTH

EIDORS-related citations continue to grow. Current citation results are shown in table 1. The EIDORS code-base is stable with significant effort being applied to improving test coverage, refining performance and implementing new features (fig. 1). In 2012, a dev staging area was created for contributions in progress.

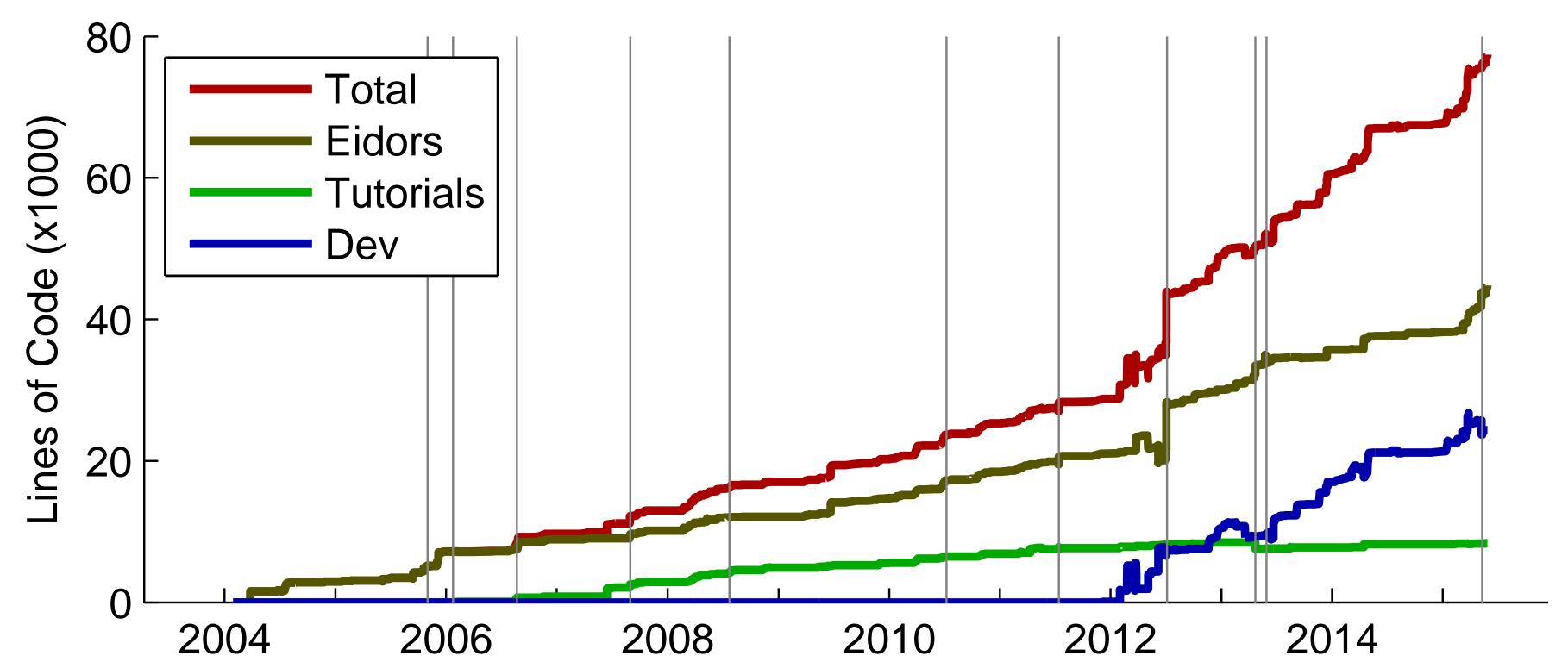


Figure 1: Lines of Code (LoC) in Matlab files in the EIDORS code-base vs. time; Total (red), Eidors (i.e. release branch, olive), Tutorials (green), development code (blue). Releases are indicated by gray bars.

Table 1: EIDORS Citations (May 2015, scholar.google.com).

Paper	Date Citations	
[2] A MATLAB package for the EIDORS project	2001	159
[3] Image reconstruction algorithms for	2002	88
[4] A Matlab toolkit for three-dimensional	2002	293
[5] Uses and abuses of EIDORS: An extensible	2006	184

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