

Data Quality and Inverse Problems

Bayesian Image Reconstruction Workshop
U. Manchester, UK:
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Data Quality

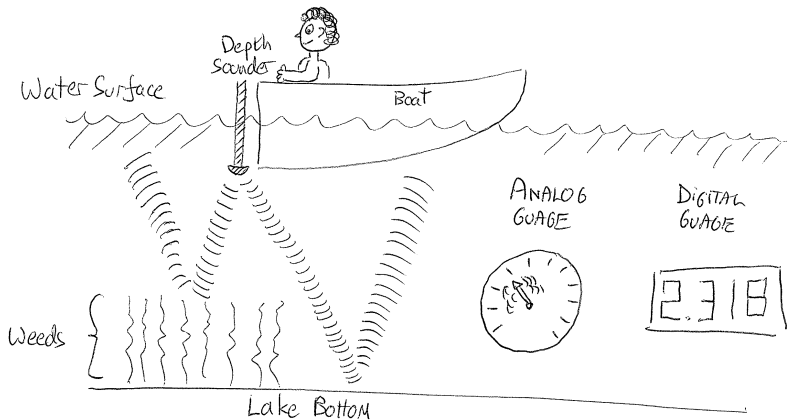
What is data quality?

- Wrong Data – Data Errors
- Uninformative Data
- Misinterpreted Data

Outline:

- Examples
- Bayesian Framework
- Electrode Errors
- Data Quality Measures
- Thoughts from Biometrics & Information Theory
- A way forward?

Example #1: Data Quality

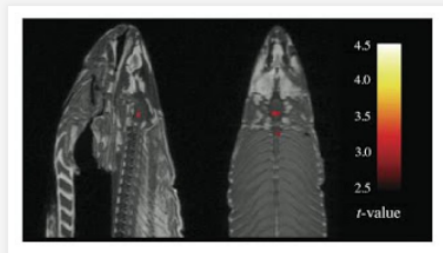


Depth Sounder – with analog and digital gauges

Example #2: Data Quality

neuroskeptic.blogspot.ca/2009/09/fmri-gets-slap-in-face-with-dead-fish.html

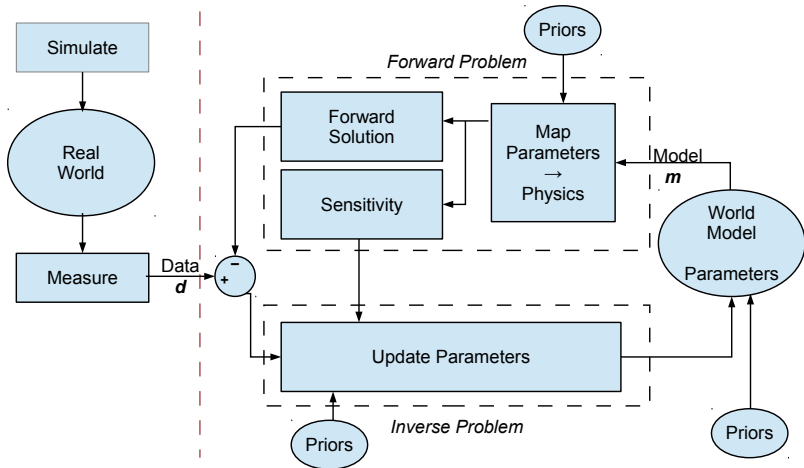
Neural correlates of interspecies perspective taking in the post-mortem Atlantic Salmon: An argument for multiple comparisons correction



This is a poster presented by Bennett and colleagues at this year's Human Brain Mapping conference. It's about **fMRI** scanning on a dead fish, specifically a salmon. They put the salmon in an MRI scanner and *"the salmon was shown a series of photographs depicting human individuals in social situations. The salmon was asked to determine what emotion the individual in the photo must have been experiencing."*

According to the authors, subject, "not alive at the time of scanning"

Inverse Problem Framework



Framework for inverse problems. *Note all the priors*

What's the problem?

With strong priors, algorithms give us pretty pictures, even when they are irrelevant.

Question:

- how can we know when to trust a pretty picture?
- how can we know when the data are junk?

Bayesian Formulation

- Forward Problem
(Data d , Parameters m , noise n)

$$d = F(m) + n$$

- Noise Model

$$n \sim \mathcal{N}(0, \Sigma_n)$$

- Data Posterior Probability

$$p(d|m) \propto \exp\left(-\frac{1}{2}\|d - F(m)\|_W^2\right), \quad W = \Sigma_n^{-1}$$

Bayesian Formulation

- Parameters Prior Probability

$$m \sim \mathcal{N}(m, \Sigma_m)$$
$$p(m) \propto \exp\left(-\frac{1}{2}\|m - m_0\|_P^2\right), \quad P = \Sigma_m^{-1}$$

- Posterior Probability

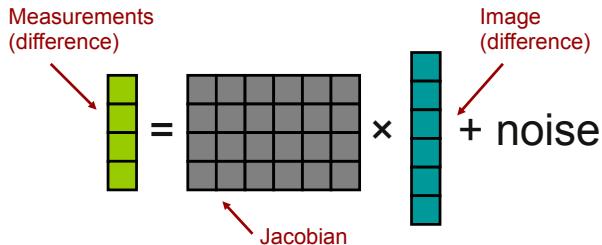
$$p(m|d) \propto p(d|m)p(m)$$
$$\propto \exp\left(-\frac{1}{2}\|d - F(m)\|_W^2 - \frac{1}{2}\|m - m_0\|_P^2\right)$$

- MAP solution minimizes norm

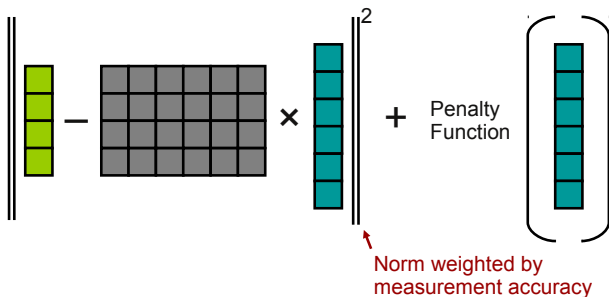
$$\|d - F(m)\|_W^2 + \|m - m_0\|_P^2$$

Reconstruction in Pictures

- Forward Problem

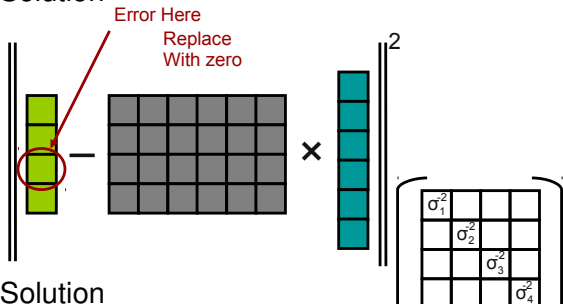


- MAP Solution Norm

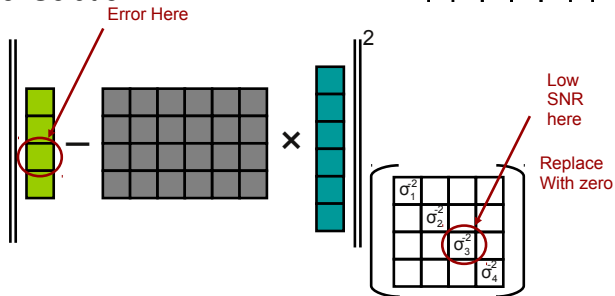


Reconstruction with Data Errors

- “Traditional” Solution

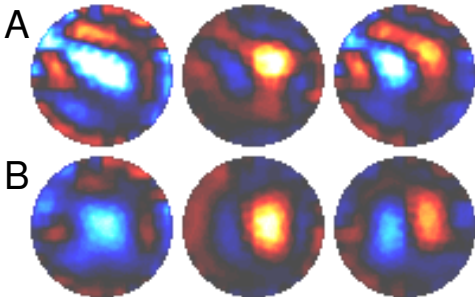


- Error Model Solution



Electrode Error compensation

- Offline compensation using “jack-knife” approach (2005)



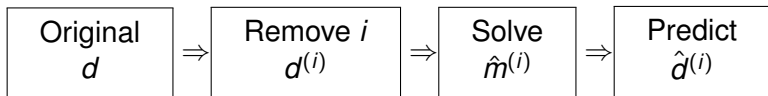
EIT images in anaesthetised, ventilated dog

A: uncompensated, *B*: compensated. *Left*: ventilation *Centre*: saline (right lung) *Right*: ventilation and saline

- Automatic detection (via reciprocity comparison) (2009)
- New work to speed online calculation & use data quality

Data Quality Measure: Concept

- *Concept:* High Quality Data is Consistent
- *Idea:* Use IP to predict each data point from all others



- Calculate error

$$\epsilon_i = d_i - \hat{d}_i^{(i)}$$

Data Quality Measure: Linear Case

- ϵ from data d

$$\epsilon_j = d_j - \hat{d}_j^{(i)} \quad \text{where } \hat{d}^{(i)} \text{ is predicted without } i$$

$$\hat{d}^{(i)} = J\hat{m}^{(i)} = JRd$$

$$\hat{d}^{(i)} = JR^{(i)}d \quad \text{where } R^{(i)} \text{ is Rec. Matrix without } i$$

$$R = \Sigma_m J^t (J \Sigma_m J^t + \Sigma_n)^{-1}$$

$$R^{(i)} = \Sigma_m J^t \left(J \Sigma_m J^t + \alpha^2 I + \mu^2 \Xi^{(i)} \right)^{-1} \quad \text{where } \Xi^{(i)} \text{ is 1 at } (i, i)$$

$$\epsilon_j = [d - \hat{d}^{(i)}]_j = [d - JR^{(i)}d]_j = [I - JR^{(i)}]_j d$$

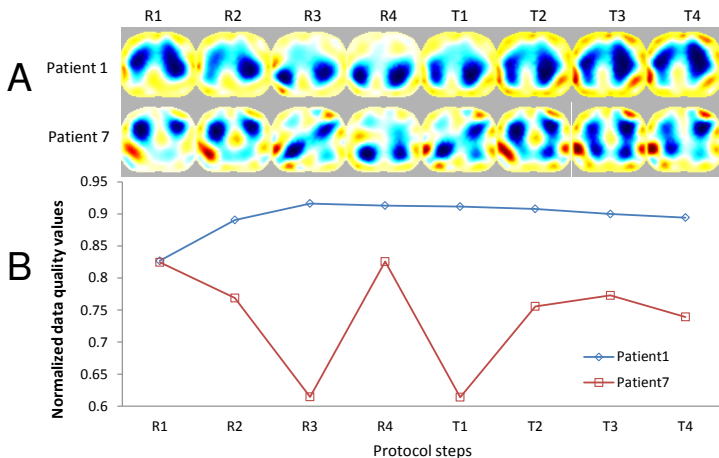
- Quality Matrix Q

$$\epsilon = Qd$$

$$\text{where } Q_j = I - J^t \Sigma_m J^t \left(J \Sigma_m J^t + \alpha^2 I + \mu^2 \Xi^{(i)} \right)^{-1}$$

- Q calculation can be optimized

Example: Data quality measures



Clinical data and data quality metric for each stage of the protocol (R1–R4 — recruitment: PEEP \uparrow , T1–T4 — titration: PEEP \downarrow).

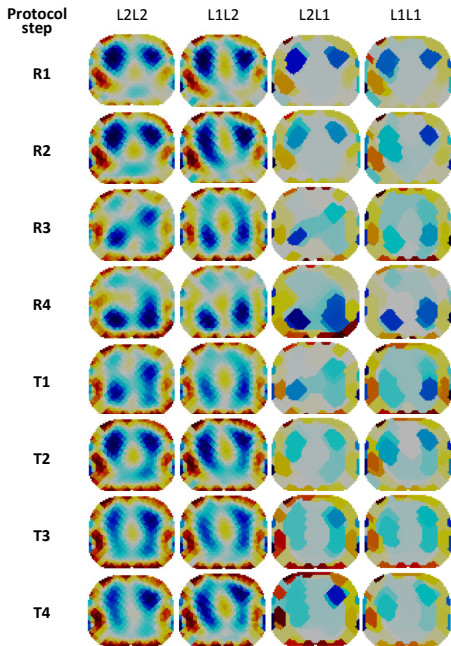
A: EIT images (one-step Gauss-Newton solver with a 2D forward model), B: Calculated data quality.

Example: Robust Algorithms

$$\|d - F(m)\|_{\ell_d} + \|m - m_0\|_{\ell_m}$$

- ℓ_1 norm for the image prior allows “blocky” reconstructions
- ℓ_1 norm for the data mismatch gives improved robustness to outliers

Figure: Reconstructions with mixed (data/image) norms for clinical data for each stage of the protocol
(R1–R4 — recruitment: PEEP \uparrow ,
T1–T4 — titration: PEEP \downarrow).



A way forward?

- Inverse Problems are hard; priors are useful; users like pretty pictures
⇒ the situation will get worse
- Complex systems fail in complex ways
- Very complex systems (human brains) fail in extremely sophisticated ways. These errors are carefully researched (psychology, neuroscience)
- Idea: we need a new research area — *inverse problem* problems IP^2
⇒ goal: understand/classify situations where IPs fail.

*Low Quality Data
are Less Informative:*

*Measuring Quality via
Information Content*

Andy Adler, Richard Youmaran
Carleton University, Ottawa, Canada

From: Presentation at NIST Biometric Biometric
Quality Workshop II, Nov 2007

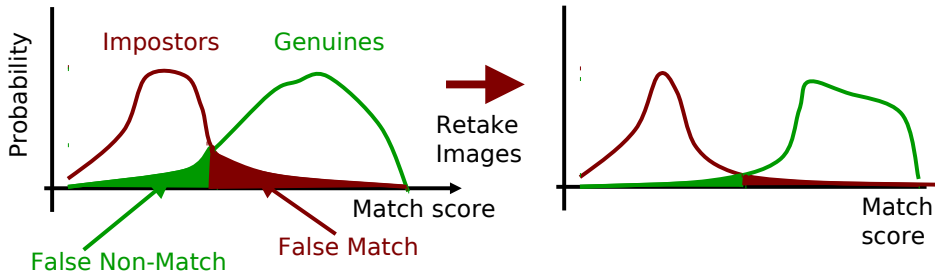
Biometric Sample Quality

Biometric Sample Quality measures:

- character
 - inherent features
- Fidelity
 - accuracy of features
- Utility
 - predicted system performance

INCITS, Biometric Sample Quality Standard Draft,
M1/06-0003

Utility Quality



Since the algorithm errors were less, the retaken images had higher quality

But, could we have done better with the first images?

Utility Quality

- The ability of the system to use the data to achieve low error rates
- Dependent on processing algorithm
- Doesn't measure "inherent" quality in the data

Character / Fidelity

Descriptions of “inherent” quality of a biometric sample

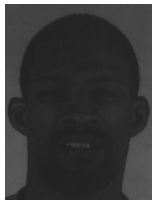
- Character Quality Problems
 - Blur
 - Shadows
 - Poor lighting
- Fidelity Quality Problems
 - A good image of the wrong part

Example: *Character Quality*

← Best Faces

Human Selections

Worst Faces →



Example: *Fidelity Quality*

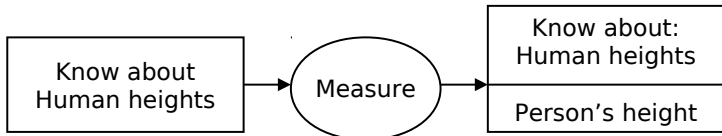


How can we measure character quality?

- Probing question:
Why do we worry about low quality data?
- Answer:
They have less information .

Definition: *MI* (Mutual Information) *Measurement Information:*

- the decrease in uncertainty about the identity of an individual based on a measurement of biometric features.



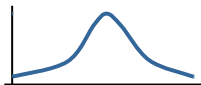
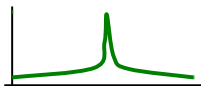
Prior: Uncertainty is 1:6 billion $q(y) \implies p(y)$ **Posterior:** Uncertainty is less

- Measure **KLD** (Kullback-Leibler divergence)
the “extra bits” of information needed to represent $p(y)$ wrt $q(y)$. Average over population to get MI (mutual information)

Example #1: measure *Height*

- **Measure #1** (at doctor's office, ie. accurate)
- **Measure #2** (via telescope, ie. inaccurate)

Individual
Variability
(+device errors)



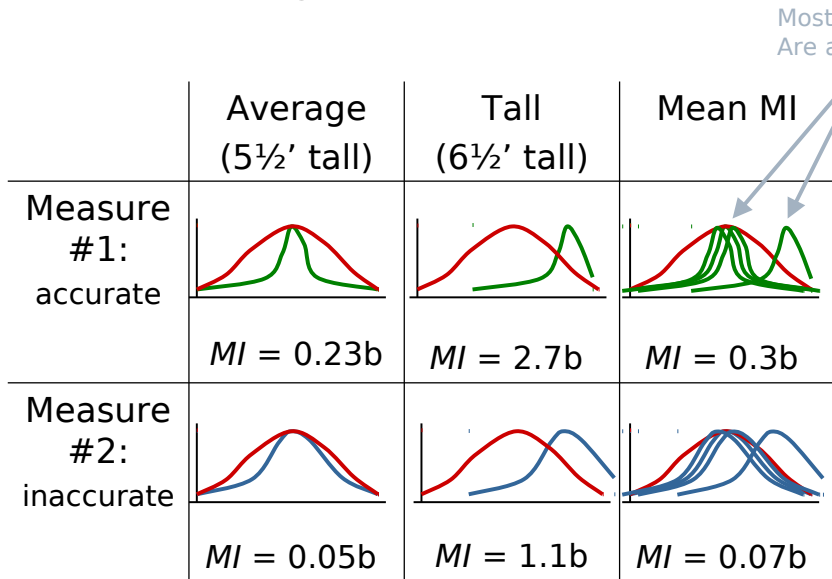
Population
Variability



Overall
Distribution

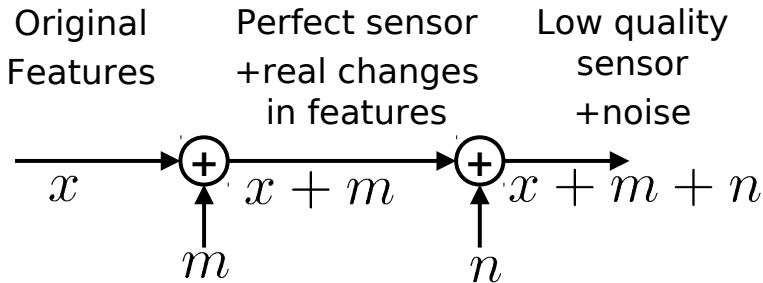


MI for height data

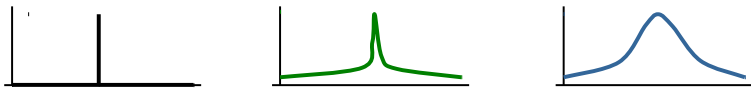


Most People
Are average

Quality Loss Model



Individuals



Population



Formula page ...

□ KLD:
$$D(p||q) = \int p(\mathbf{y}) \log_2 \frac{p(\mathbf{y})}{q(\mathbf{y})} d\mathbf{y}$$

□ MI:
$$= E_q [D(p||q)]$$

□ Gaussian Models:

$$= \frac{1}{2} \log_2 |\Sigma_q \Sigma_p^{-1}| + \text{tr}(\Sigma_p \Sigma_q^{-1})$$

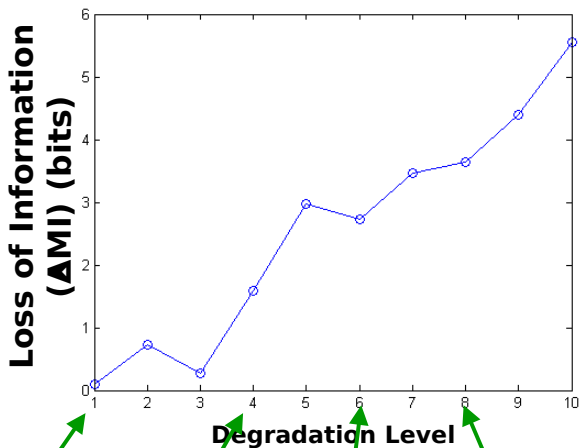
When signal > noise

When noise > signal,
ignore

□ With noise model:

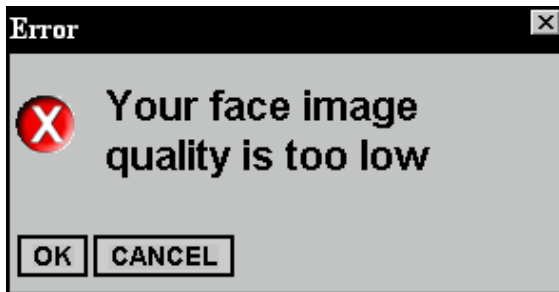
$$= \frac{1}{2} \log_2 |\Sigma_x (\Sigma_m + \Sigma_n)^{-1} + \mathbf{I}|$$

Results:
loss of
MI with
addition
of image
noise



Comment: *Quality*

- *Quality* is a value laden term
- Can we tell users this?



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