# EIT Reconstruction Using *L*1 Norms for Data and Image Terms

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- Goal: reconstruct conductivity in  $\Omega$ .
- Problem: ill-conditioned problem, since measurements most sensitive to boundary
- Solution: use of regularization techniques to penalize un-realistic solutions

# Motivation

- The popular Gauss-Newton type reconstruction of EIT seeks Least Squares (L2 norm) solution
  - Smoothed edges

- Sensitive to measurement outliers

- L1 norm solution can increase edge sharpness
  - Sharpened edges
  - Robust against measurement outliers

## Forward Model (linearized)

 $\mathbf{y} = \mathbf{J}\mathbf{x}$ 



Least Squares (L2 norm) solution  $\hat{\mathbf{x}} = \operatorname{argmin} \|\mathbf{y} - \mathbf{J}\mathbf{x}\|_2^2 + \|\mathbf{x} - \mathbf{x}_0\|_2^2$  $\mathbf{X}$ 



# Total Variation (TV)



- 1-norm allows non-smooth images
- L1 norm is not differentiable,
- Several iterative techniques



Our proposed idea:

- Penalty 1-norm allows non-smooth images
- Data 1-norm gives reduced penalty for outliers

# A Generalized and Weighted Iterative Solution for L1/L2 norms minimization

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{J}\mathbf{x}\|_{\boldsymbol{\Sigma}_{\mathbf{n}}^{-1}}^{p_n} + \|\mathbf{x} - \mathbf{x}_0\|_{\boldsymbol{\Sigma}_{\mathbf{x}}^{-1}}^{p_x}$$

- $p_n$  and  $p_x$  are norm type: - 1 for L-1 norm; 2 for L-2 norm
- $\Sigma_n$  and  $\Sigma_x$  are covariance matrices:
  - $-\Sigma_n$  for measurement noise
  - $-\Sigma_x$  for image elements

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{J}\mathbf{x}\|_{\boldsymbol{\Sigma}_{\mathbf{n}}^{-1}}^{p_n} + \|\mathbf{x} - \mathbf{x}_0\|_{\boldsymbol{\Sigma}_{\mathbf{x}}^{-1}}^{p_x}$$

Reformulate as:

$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} \\ (\mathbf{y} - \mathbf{J}\mathbf{x})^{t} \mathbf{D}_{\mathbf{n}}^{t} \mathbf{\Sigma}_{\mathbf{n}}^{-1} \mathbf{D}_{\mathbf{n}} (\mathbf{y} - \mathbf{J}\mathbf{x})^{t} + \\ (\mathbf{x} - \mathbf{x}_{0})^{t} \mathbf{D}_{\mathbf{x}}^{t} \mathbf{\Sigma}_{\mathbf{x}}^{-1} \mathbf{D}_{\mathbf{x}} (\mathbf{x} - \mathbf{x}_{0})^{t}$$

Where:

$$\begin{bmatrix} \mathbf{D}_{\mathbf{n}} \end{bmatrix}_{i,i} = \left( \begin{bmatrix} |\mathbf{y} - \mathbf{J}\mathbf{x}| \end{bmatrix}_{i} + \beta \right)^{\frac{1}{2}p_{n}-1}$$
$$\begin{bmatrix} \mathbf{D}_{\mathbf{x}} \end{bmatrix}_{i,i} = \left( \begin{bmatrix} |\mathbf{x} - \mathbf{x}_{0}| \end{bmatrix}_{i} + \beta \right)^{\frac{1}{2}p_{x}-1}$$

# The General Iterative Solution

$$\hat{\mathbf{x}}^{k+1} = \hat{\mathbf{x}}^k + \left(\mathbf{J}^t \mathbf{W}(\hat{\mathbf{x}}^k)\mathbf{J} + \lambda^2 \mathbf{R}(\hat{\mathbf{x}}^k)\right)^{-1} \mathbf{J}^t \mathbf{W}(\hat{\mathbf{x}}^k) \underbrace{\left(\mathbf{y} - \mathbf{J}\hat{\mathbf{x}}^k\right)}_{\mathbf{y} = 1} \mathbf{J}^t \mathbf{W}(\hat{\mathbf{x}}^k) \mathbf{W}(\hat{\mathbf{x}}^k) \underbrace{\left(\mathbf{y} - \mathbf{J}\hat{\mathbf{x}}^k\right)}_{\mathbf{y} = 1} \mathbf{W}(\hat{\mathbf{x}}^k) \mathbf{W}(\hat{\mathbf{x}^k) \mathbf{W}(\hat{$$

#### Image update

#### Where:

$$\begin{split} \mathbf{W}(\mathbf{x}) &= \mathbf{D}_{\mathbf{n}}(\mathbf{x})^{t} \mathbf{\Sigma}_{\mathbf{n}}^{-1} \mathbf{D}_{\mathbf{n}}(\mathbf{x}) \\ \mathbf{R}(\mathbf{x}) &= \mathbf{D}_{\mathbf{x}}(\mathbf{x})^{t} \mathbf{\Sigma}_{\mathbf{x}}^{-1} \mathbf{D}_{\mathbf{x}}(\mathbf{x}) \end{split}$$

## Simulation: Forward Model



the forward model: finite element model with 576 elements. Electrodes are indicated by green dots. The background and inhomogeneities have conductivities 1.0 and 2.0, respectively.

## Simulation: Comparison -No data outliers



Observation : L1 *prior* norm gives fewer artefacts and clearer edges

# Simulation: Comparison --Data outliers added



Observation: L1 *data* norm gives more robust against meassurement errors.

# Conclusion

- L1 norm on data term gives robustness against data error
- L1 norm on the regularization term helps achieve low noise/artefacts
- The proposed method can flexibly choose L2/L1 norms on the data fidelity term and the regularization term