

Non-coherent Multi-Layer Constellaions for Unequal Error Protection

Speaker: Karim G. Seddik¹

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1 Overview

- Aim
- Set Partitioning

2 How to Measure the Distance between Constellation Points?

3 Design Approach

- Proposed Scheme
- Illustration

4 Selection Criterion of Step Parameter t

- Geometric Mean Approximation
- Polynomial Regression
- Examples

5 Simplified Decoder

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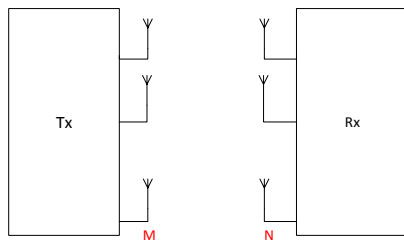
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Define the sets $\mathcal{S}^1 = \{s_1^1, \dots, s_{\mathcal{N}_1}^1\}$ and $\mathcal{S}^2 = \{s_1^2, \dots, s_{\mathcal{N}_2}^2\}$, where the set \mathcal{S}^1 (\mathcal{S}^2) contains the more (less) protected subsymbols.

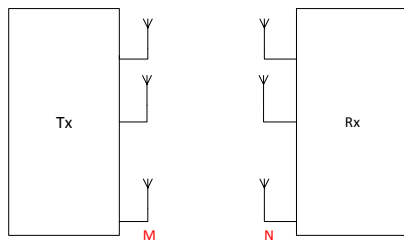
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- The chosen supersymbol s_i is mapped onto the pair (s_i^1, s_i^2) by some bijective function $f : \mathcal{S} \rightarrow \mathcal{S}^1 \times \mathcal{S}^2$.

(2) Non-Coherent Signaling

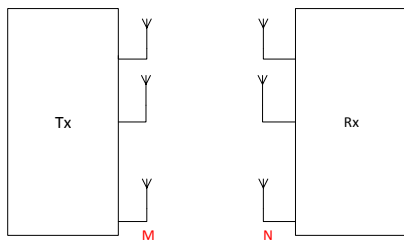


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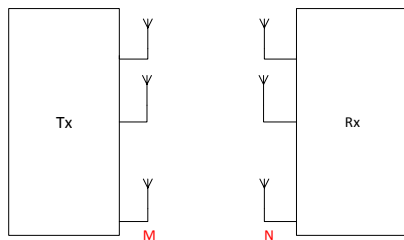
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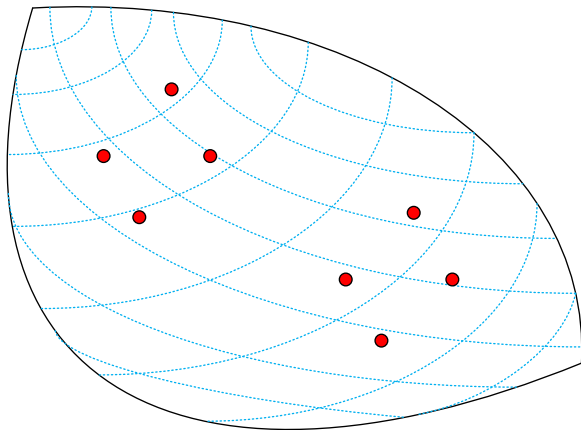


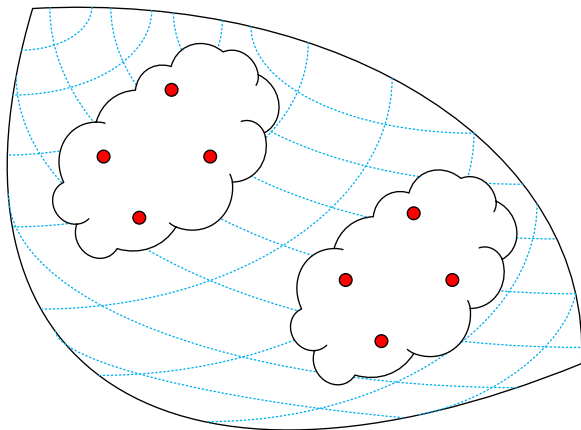
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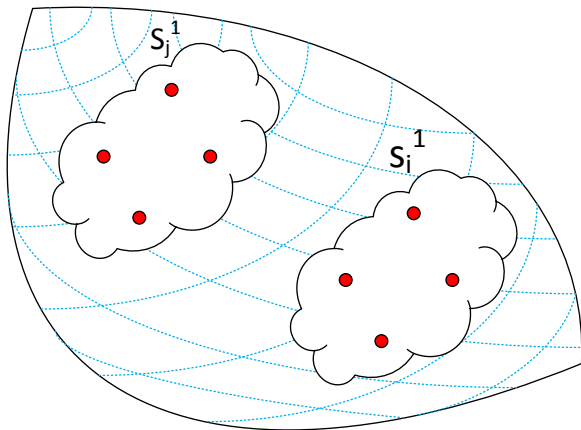


- Channel state information (CSI) is unknown at both transmitter and receiver.
- Transmission takes place over T symbol durations. Channel coefficients are assumed constant during that interval. We only consider $T > M$.
- Transmitted symbols are represented by points on the Grassmannian manifold $\mathbb{G}_{T,M}(\mathbb{C})$.

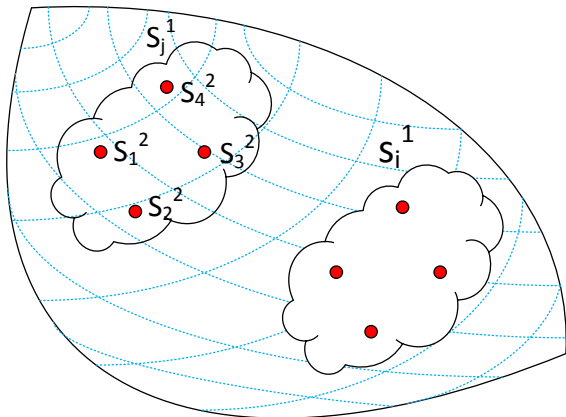




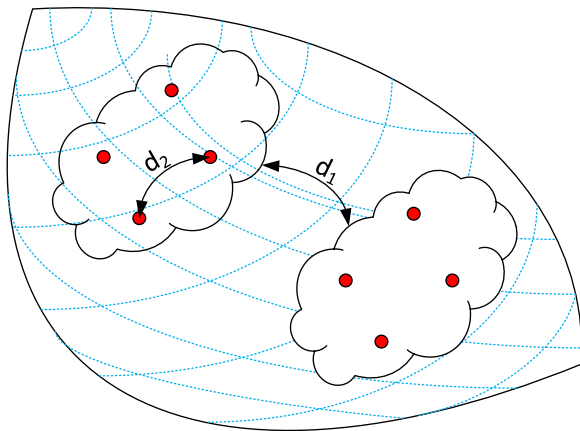
The constellation is decomposed into disjoint subsets.



More important symbols encode subsets.



Less important symbols encode points within a chosen subset.



d_1 (d_2) controls the error probability of the more (less) protected symbols.

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How to Measure the Distance between Constellation Points?

- For unitary signaling, the asymptotic error probability of mistaking \mathbf{X}_i for \mathbf{X}_j under GLRT detection is given by¹

$$P_{ij} = (d_{cp}(\mathbf{X}_i, \mathbf{X}_j)\gamma T)^{-MN} M^{MN} \binom{2MN-1}{MN},$$

$$d_{cp}(\mathbf{X}_i, \mathbf{X}_j) = \left(\prod_{k=1}^M \sin^2 \theta_k \right)^{\frac{1}{M}}.$$

$\{\theta_i\}_{i=1}^M$ are the principle angles between the subspaces associated with \mathbf{X}_i and \mathbf{X}_j .

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- The **Chordal Product Distance**² (not a true distance!) can be employed to define the coding gain of the more (less) protected symbols.

$$d_1 = \min_{i \neq j} d_{cp}(\Omega_i, \Omega_j),$$

$$d_2 = \min_{\mathbf{X}, \mathbf{Y} \in \mathcal{C}} d_{cp}(\mathbf{X}, \mathbf{Y}).$$

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- Our design approach is entirely based on the more intuitive chordal distance. However, the connection between both metrics is essential since the coding gains are expressed in terms of the product chordal distance.

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- For an initial layer ξ_1 , we define a sequence of $L - 1$ **children** layers $\xi_2, \xi_3, \dots, \xi_L$.

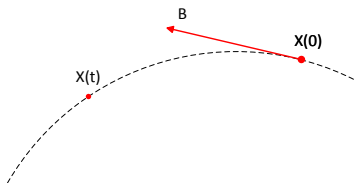
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Design Approach (1)³

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- Starting at $\mathbf{X} = \mathbf{X}(0)$, the motion of a point traveling along some direction \mathbf{B} is given by

$$\mathbf{X}(t) = [\mathbf{X} \quad \mathbf{X}_\perp] \begin{bmatrix} \mathbf{V} \cos \Sigma t \\ \mathbf{U} \sin \Sigma t \end{bmatrix}.$$

Where $\mathbf{B} = \mathbf{U}\Sigma\mathbf{V}^\dagger$ is the SVD of \mathbf{B} , \mathbf{X}_\perp is the orthogonal complement of \mathbf{X} and t is a step parameter.

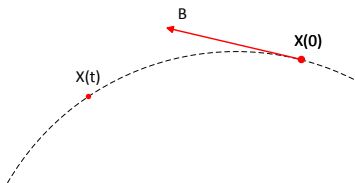


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- Elements of ξ_i are found by transitioning along K geodesics emanating from each member in the i^{th} **parent** layer.

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$$\xi_i = \left\{ [\mathbf{X}_p \quad \mathbf{x}_{p\perp}] \begin{bmatrix} \mathbf{V}_k \cos \Sigma_k t_i \\ \mathbf{U}_k \sin \Sigma_k t_i \end{bmatrix} \mid \forall \mathbf{X}_p \in \mathcal{C}_i, \forall k = 1, \dots, K \right\}.$$

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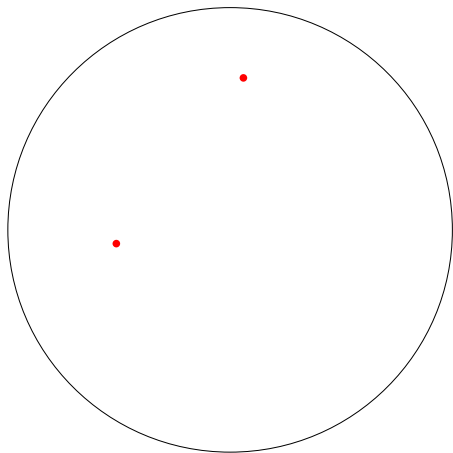
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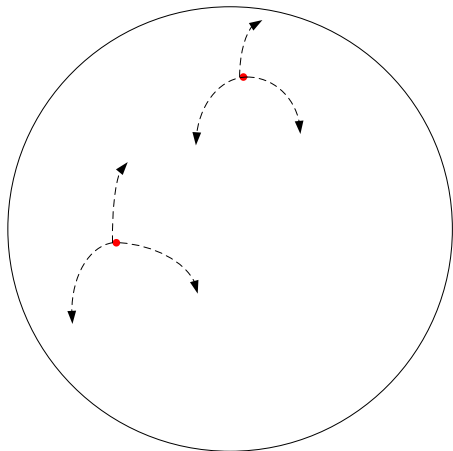
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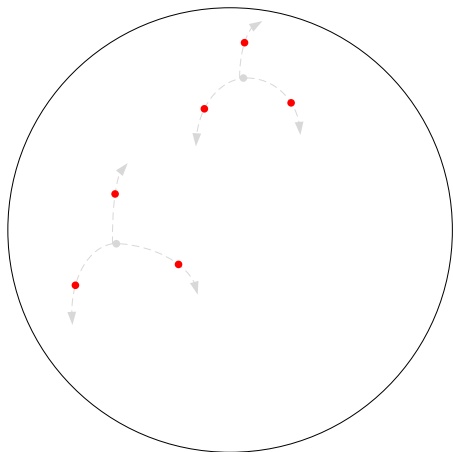
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- The size of the constellation is given by $|\mathcal{C}| = N'(K + 1)^{L-1}$, where N' is the initial constellation size and K is the number of geodesic directions.



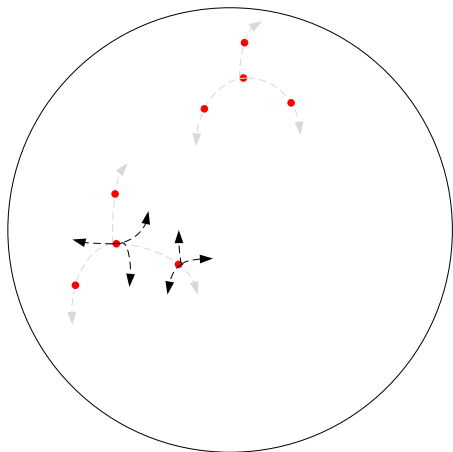
Initial constellation.



Geodesic directions ensure maximal spacing.



Children points are found along the geodesic directions.



The process can be further repeated to add more points.

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- With careful selection of this parameter, a specific coding gain can be ensured for the more protected layer over the Equal Error Protection scheme.
- We propose two ways of doing this:
 - 1 Geometric Mean Approximation.
 - 2 Polynomial Regression.

- A lower bound on minimum subset distance d_1 is established in terms of $\beta = \sin t$.

$$d_1 \gtrsim \frac{1}{M} (d_{pack} - 2\sqrt{M}\beta)^2 - \frac{M-1}{2M^2} (d_{pack} - 2\sqrt{M}\beta)^4,$$

where $d_{pack} = \frac{M(T-M)}{T} \sqrt{\frac{N'}{N'-1}}$.

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- Setting the desired coding gain to be equal to the RHS guarantees that the actual coding gain is at least as large as the desired value.
- This bound is rather crude when the constellation size is large.

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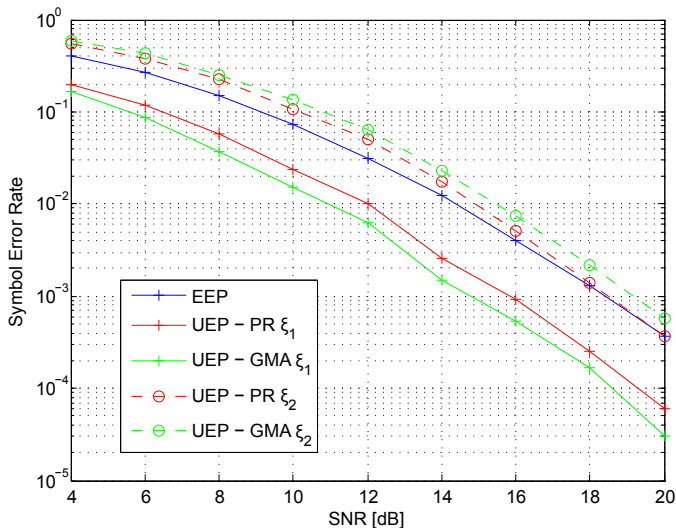
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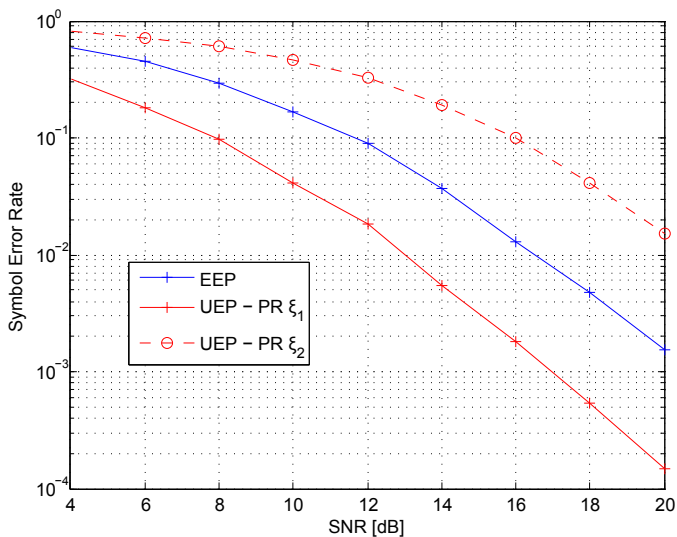
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- With enough observations ($l \geq n$), we can estimate the unknown coefficients a_i .
- Performance analysis suggests that this is the more reliable approach.

- $R = 1.5$ bpcu, 33% of data is important



- $R = 2$ bpcu, 50% of data is important



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- The decoder then investigates the children of the q largest ML metric. The process is repeated for $L > 2$.
- A decision is made in favor of some \mathbf{X} , if \mathbf{X} maximizes the ML metric over all examined points.
- A reduction factor of $(\frac{q}{K})^{L-1}$ is realized in the number of operations needed.

Analysis of Simplified Decoder

- $K = 15$.

