# An Analysis of User Mobility in Cellular Networks 

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#### Abstract

User mobility impacts the performance of cellular networks. However, there is a lack of results on this problem because of the difficulty of the analysis. The existing results are limited to handover rate and mean path length that a user is associated with the same base station. In this paper, we derive the probability distribution function of the path length that a user will be associated with the same base station. It is assumed that the user travels along a straight path and it is associated to the nearest base station. We make the stochastic geometry assumption that the base stations are distributed over the area according to a Poisson point process. We provide simulation results as further evidence that the analysis is correct. The results of this paper may be useful in the design of cellular networks.


## KEYWORDS

User mobility; cellular networks; handover; path length distribution

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## 1 INTRODUCTION

The impact of mobility on the performance of the cellular networks is important, since most of the time users receiving service are mobile. As the user moves from one cell to the

[^0]neighboring cell, then the user has to be served by the new cell and this requires handover. Handover increases the network load as it increases signaling overhead. The rapid growth of the demand for wireless communications has led to the need of increasing capacity of wireless networks. Since the amount of available spectrum is limited, this has resulted in shrinking of the cell sizes to increase spectrum reuse and consequently the wireless network capacity. However, handover rate, mean number of handovers per unit time, increases with decreasing cell size and with higher mobility [1].

Despite of the significance of user mobility, there is a lack of results on this problem, because of difficulty of the analysis. Initially, queueing networks was used to model mobility in cellular networks. In those models, each cell would be modeled as a queue and handoff would be modeled as transfer of a customer from one queue to another [2, 3]. However, these results fail to capture geometric pattern of the base stations in the plane. Recently, results from stochastic geometry has been applied in the studying of wireless networks. This technique assumes that the base stations are distributed according to a Poisson Point Process (PPP) over the plane [4]. This technique has also been applied to the study of the user mobility in the cellular networks. The main performance measures of interest have been handover rate and mean sojourn time. Sojourn time refers to the amount of time that a user spends in a cell. In [5], it is assumed that a user follows a variation of the random waypoint mobility (RWP) model. In RWP, a user travels in a certain direction for a random path length at a given speed, before changing the direction and speed randomly. In [5], they determine mean handover rate and mean sojourn time for single tier cellular networks. In [6], user mobility has been studied in multiple tiers of networks. They determine handoff rate for both horizontal and vertical handoffs, which refer to handoffs within a tier and across the tiers respectively for arbitrary user trajectories. In [7], they determine the mean sojourn time for a user moving at a constant speed along a randomly placed straight line in a cell that has the shape of convex polygon.
In this work, we assume that the user is moving along a straight path. Under the stochastic geometry assumption we determine probability distribution of path length without handover. This result corresponds to the distribution of the sojourn time for a user moving at a constant speed. We confirm
the correctness of the analysis through simulations. We think that as the network becomes more dense and multi-tier, more information than the handover rate will be needed to determine the performance of the system.

The remainder of the paper is organized as follows: Section 2. describes the system model, Section 3. derives conditional probability of no handover and Section 4. determines probability distribution of path length without handover. Finally, Section 5. presents the conclusions of the paper.

## 2 SYSTEM MODEL

Next, we describe the system model under consideration. We assume that the user moves along a straight line in small fixed size steps of $d$. We assume that the base stations are distributed in the plane according to a PPP with parameter $\lambda$ stations $/ m^{2}$. Let $S_{B}$ denote the area of the region $B$ in the plane, then probability of having $k$ base stations in this region is given by,

$$
\begin{equation*}
P_{k}=\frac{e^{-\lambda s_{B}}\left(\lambda S_{B}\right)^{k}}{k!}, \quad k=0,1,2, \ldots \tag{1}
\end{equation*}
$$

We assume that the user will be served by the nearest base station, which will be referred to as the tagged base station.

We let $A_{i}$ denote user location in the plane at the end of $i$ th step $i=1,2, \ldots$ with initial user location being $A_{1}$. We let $C$ denote the tagged base station when the user is at location $A_{1}$. We assume that when the user is at location $A_{i}$ the tagged base station is still $C$. From Fig.1, this means that there are no base stations located within the circle centered at $A_{i}$ that goes through $C$. Let us consider movement of the user from point $A_{i}$ to $A_{i+1}$ as shown in Fig. 1. The user to remain associated with the tagged base station $C$ when it moves from $A_{i}$ to $A_{i+1}$, then there should not be any stations located in the circle centered at $A_{i+1}$ that goes through point $C$. We already know that there are no any base stations within the overlap area of these two circles. From Fig. 1, the user will remain associated with the tagged base station $C$ at $A_{i+1}$ if there are no base stations located within the non-overlapping area of the circle $A_{i+1}$ with the circle $A_{i}$. As shown in Fig.1, let $S_{A_{i} \cap A_{i+1}}$ denote the area of the intersection of the circles centered at $A_{i}$ and $A_{i+1}$ respectively and $S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)}$ denote the nonoverlapping area of the circle centered at $A_{i+1}$ with that centered $A_{i}$ respectively. As a result probability of no handover as the user moves from point $A_{i}$ to $A_{i+1}$ will be given by,

$$
\begin{align*}
& \mathrm{P}_{\mathrm{r}}(\text { no handover } \mid \text { tagged base station is } C)= \\
& \mathrm{P}_{\mathrm{r}}\left(\text { no base station in } S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)}\right) \tag{2}
\end{align*}
$$

Substituting from equation (1),
$\mathrm{P}_{\mathrm{r}}($ no handover $\mid$ tagged base station is $C)=$ $\exp \left(-\lambda S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)}\right)$

In the next section, we will first determine the above conditional probability and in the section following that we will determine probability of the path length without handover.

In the following, we will let $X Y$ denote the line segment between the points $X$ and $Y$ and the length of this line segment as $|X Y|$.


Figure 1: Intersection of the circles centered at $A_{i}$ and $A_{i+1}$ with tagged base station located at $C$.

## 3 DERIVATION OF THE PROBABILITY OF NO HANDOVER FOR SINGLE STEP USER MOVEMENT

Next, we will derive conditional probability that there is no handover as the user moves from location $A_{i}$ to $A_{i+1}$ given the location of the tagged base station $C$. In Fig. 1, we will assume that there is a Cartesian coordinate system located at point $A_{i}$ with the straight line $A_{i} A_{i+1}$ forming the y -axis. We will let $\left(x_{i}, y_{i}\right)$ denote the Cartesian coordinates of $C$ in this coordinate system.
Letting $r_{i}$ denote the distance of $C$ from $A_{i}$, then $r_{i}=\left|A_{i} C\right|$. Let $r_{i+1}$ denote the distance of the user when it is located at $A_{i+1}$ from the tagged base station $C, r_{i+1}=\left|A_{i+1} C\right|$. Then depending on the quadrant that the tagged base station is located there are four cases to be considered. Since the user is moving along the yaxis, the probability of no handover will be same for the positions of tagged base station $C$ which are symmetric wrt yaxis. Thus we only need to analyze what happens when the tagged base station is in the first and fourth quadrants and multiply the resulting probability by two. In the case that the tagged base station is located in the first quadrant, there are two subcases depending on whether the step size is greater or smaller than the y-coordinate of the tagged base station. As a result, there are three cases to be considered depending on the location of the tagged base station $C$ in quadrants $I$ and $I V$.

Next, we will determine conditional probability of no handover for each of the cases by determining nonoverlapping area of the two circles for each of these cases. Since the user moves at steps of size $d$, then $d=\left|A_{i} A_{i+1}\right|$.

Case (i): Tagged base station is in quadrant $I$ and $y_{i}<d$.

This case has been shown in Fig. 2. Let $\theta_{i}, \theta_{i+1}$ denote the angle between lines $A_{i} C, A_{i+1} C$ and the horizontal axis respectively. Similarly, let $\varphi_{i}, \varphi_{i+1}$ denote the angle between lines $A_{i} C, A_{i+1} C$ and the vertical axis respectively.

$$
\begin{equation*}
\theta_{i}=\frac{\pi}{2}-\varphi_{i}, \quad \theta_{i+1}=\frac{\pi}{2}-\varphi_{i+1} \tag{4}
\end{equation*}
$$



Figure 2: The network diagram when $C$ is located in the first quadrant and $y_{i}<d$.

In Fig. 2, we let $D$ denote the intersection of the lines $A_{i} A_{i+1}$ and $B C$. As a result, we have,

$$
\left|A_{i} D\right|=r_{i} \sin \theta_{i}, \quad\left|A_{i+1} D\right|=d-r_{i} \sin \theta_{i}
$$

$$
\begin{align*}
|C D| & =|B D|=r_{i} \cos \theta_{i}  \tag{5}\\
r_{i+1} & =\sqrt{\left|A_{i+1} D\right|^{2}+|C D|^{2}}
\end{align*}
$$

Substituting in the above from (5),

$$
\begin{equation*}
r_{i+1}=\sqrt{\left(d-r_{i} \sin \theta_{i}\right)^{2}+r_{i}^{2} \cos ^{2} \theta_{i}} \tag{6}
\end{equation*}
$$

In Fig. 1, from the right triangle $\Delta A_{i+1} D C$,

$$
\begin{equation*}
\varphi_{i+1}=\cos ^{-1} \frac{\left|A_{i+1} D\right|}{\left|A_{i+1} C\right|}=\cos ^{-1} \frac{d-r_{i} \sin \theta_{i}}{r_{i+1}} \tag{7}
\end{equation*}
$$

where the second equation above follows from (5). From equation (4), $\theta_{i+1}$ is given by,

$$
\begin{equation*}
\theta_{i+1}=\frac{\pi}{2}-\cos ^{-1} \frac{d-r_{i+1} \sin \theta_{i+1}}{r_{i+1}} \tag{8}
\end{equation*}
$$

As shown in Fig. 3, let us define $\nabla A_{i} B C$ as the smaller of the sectors of the circle centered at $A_{i}$ and the $\operatorname{arc} \widetilde{B C}$. Similarly in Fig. 4, defining $\nabla A_{i+1} B C$ as the smaller of the sectors of the
circle centered at $A_{i+1}$ and the arc $\widetilde{B C}$. Next, let $S_{\nabla A_{i} B C}, S_{\nabla A_{i+1} B C}$ denote the areas of the circular sectors $\nabla A_{i} B C, \nabla A_{i+1} B C$ respectively, then, from Fig. 2,

$$
\begin{equation*}
S_{\nabla A_{i} B C}=\varphi_{i} r_{i}^{2}=r_{i}^{2}\left(\frac{\pi}{2}-\theta_{i}\right) \tag{9}
\end{equation*}
$$

where the second equation follows from (4).

$$
\begin{equation*}
S_{\nabla A_{i+1} B C}=\varphi_{i+1} r_{i+1}^{2}=r_{i+1}{ }^{2} \cos ^{-1} \frac{d-r_{i} \sin \theta_{i}}{r_{i+1}} \tag{10}
\end{equation*}
$$

where the second equation in the above follows from (5).


Figure 3: $\nabla A_{i} B C$ is the smaller of the sectors of the circle centered at $\boldsymbol{A}_{\boldsymbol{i}}$.


Figure 4: $\nabla A_{i+1} B C$ is the smaller of the sectors of the circle centered at $\boldsymbol{A}_{\boldsymbol{i + 1}}$.

Next let $S_{\triangle A_{i} B C}, S_{\Delta A_{i+1} B C}$, denote the areas of the triangles $\Delta A_{i} B C$, and $\Delta A_{i+1} B C$ as shown in Fig.s 5 and 6 respectively. Then from Fig. 2,

$$
\begin{gather*}
S_{\triangle A_{i} B C}=\left|A_{i} D\right| *|C D|=\frac{1}{2} r_{i}^{2} \sin 2 \theta_{i}  \tag{11}\\
S_{\triangle A_{i+1} B C}=\left|A_{i+1} D\right| *|C D|=\left(d-r_{i} \sin \theta_{i}\right) r_{i} \cos \theta_{i} \tag{12}
\end{gather*}
$$

where the second equations in the above follow from substitution from (5).


Figure 5: Triangle $\Delta A_{i} B C$


## Figure 6. Triangle $\Delta \boldsymbol{A}_{\boldsymbol{i + 1}} B C$

Next let $S_{A_{i+1}}$ denote the area of the circle centered at $A_{i+1}$ with radius $r_{i+1}$,

$$
\begin{equation*}
S_{A_{i+1}}=\pi r_{i+1}^{2} \tag{13}
\end{equation*}
$$

Then, from Fig. 2, the area of the intersection of the circles centered at $A_{i}$ and $A_{i+1}$ respectively is given by,

$$
\begin{equation*}
\mathrm{S}_{\mathrm{A}_{\mathrm{i}} \cap \mathrm{~A}_{\mathrm{i}+1}}=S_{\nabla A_{i+1} B C}-\mathrm{S}_{\Delta \mathrm{A}_{\mathrm{i}+1} \mathrm{BC}}+S_{\nabla A_{i} B C}-\mathrm{S}_{\Delta \mathrm{A}_{\mathrm{i}} \mathrm{BC}} \tag{14}
\end{equation*}
$$

The area of the circle at $A_{i+1}$ that does not overlap with circle $A_{i}$,

$$
\begin{equation*}
S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)}=S_{A_{i+1}}-S_{A_{i} \cap A_{i+1}} \tag{15}
\end{equation*}
$$

Substituting in the above from (9-13), then,
$\mathrm{S}_{A_{i+1}-\mathrm{A}_{\mathrm{i}} \cap \mathrm{A}_{\mathrm{i}+1}}=\pi r_{i+1}^{2}-\left[r_{i+1}{ }^{2} \cos ^{-1} \frac{d-r_{i} \sin \theta_{i}}{r_{i+1}}-(d-\right.$
$\left.\left.r_{i} \sin \theta_{i}\right) r_{i} \cos \theta_{i}+r_{i+1}{ }^{2}\left(\frac{\pi}{2}-\theta_{i}\right)-\frac{1}{2} r_{i}{ }^{2} \sin 2 \theta_{i}\right]$

Next substituting equation (16) in (3) gives us conditional probability of no handover as the user moves from point $A_{i}$ to $A_{i+1}$ for this case,
$\mathrm{P}_{\mathrm{r}}\left(\right.$ no handover $\mid r_{i}$ and $\left.\theta_{i}\right)=\exp \left\{-\lambda\left[\pi r_{i+1}^{2}-\right.\right.$
$\left[r_{i+1}{ }^{2} \cos ^{-1} \frac{d-r_{i} \sin \theta_{i}}{r_{i+1}}-\left(d-r_{i} \sin \theta_{i}\right) r_{i} \cos \theta_{i}+r_{i+1}{ }^{2}\left(\frac{\pi}{2}-\theta_{i}\right)-\right.$ $\left.\left.\left.\frac{1}{2} r_{i}{ }^{2} \sin 2 \theta_{i}\right]\right]\right\}$

We note that in the above $\left(r_{i}, \theta_{i}\right)$ gives the location of the tagged base station $C$.

Case (ii): Tagged base station is in quadrant $I$ and $y_{i}>d$.
This case is shown in Fig. 7 and the derivation of probability of no handover is similar to the previous case, therefore, we will only explain the differences and otherwise present the results.


Figure 7: The network diagram when $C$ is located in the first quadrant and $y_{i}>d$.

Equation (4) continues to hold for this case. In Fig. 7, we let $D$ denote the extension of the line $A_{i} A_{i+1}$ that intersects with $B C$. Then, we have,

$$
\begin{gather*}
\left|A_{i} D\right|=r_{i} \sin \theta_{i}, \quad\left|A_{i+1} D\right|=r_{i} \sin \theta_{i}-d, \\
|C D|=|B D|=r_{i} \cos \theta_{i} \tag{18}
\end{gather*}
$$

As may be seen, $\left|A_{i+1} D\right|$ differs from the previous case. Next, we give the equations corresponding to (6-12) for this case,

$$
\begin{gather*}
r_{i+1}=\sqrt{\left(r_{i} \sin \theta_{i}-d\right)^{2}+r_{i}^{2} \cos ^{2} \theta_{i}}  \tag{19}\\
\varphi_{i+1}=\cos ^{-1} \frac{\left|A_{i+1} D\right|}{\left|A_{i+1} C\right|}=\cos ^{-1} \frac{r_{i} \sin \theta_{i}-d}{r_{i+1}}  \tag{20}\\
\theta_{i+1}=\frac{\pi}{2}-\varphi_{i+1}=\frac{\pi}{2}-\cos ^{-1} \frac{r_{i} \sin \theta_{i}-d}{r_{i+1}}  \tag{21}\\
S_{\nabla A_{i} B C}=\varphi_{i} r_{i}^{2}=r_{i}^{2}\left(\frac{\pi}{2}-\theta_{i}\right)  \tag{22}\\
S_{\nabla A_{i+1} B C}=\varphi_{i+1} r_{i+1}^{2}=r_{i+1}^{2} \cos ^{-1} \frac{r_{i} \sin \theta_{i}-d}{r_{i+1}}  \tag{23}\\
S_{\triangle A_{i} B C}=\left|A_{i} D\right| *|C D|=\frac{1}{2} r_{i}^{2} \sin 2 \theta_{i}  \tag{24}\\
S_{\Delta A_{i+1} B C}=\left|A_{i+1} D\right| *|C D|=\left(r_{i} \sin \theta_{i}-d\right) r_{i} \cos \theta_{i} \tag{25}
\end{gather*}
$$

The nonoverlapping area of the circle centered at $A_{i+1}$ with that centered at $A_{i}$ respectively, is given by,

$$
\begin{align*}
S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)} & =\left(S_{\nabla A_{i+1} B C}-S_{\Delta A_{i+1} B C}\right) \\
& -\left(S_{\nabla A_{i} B C}-S_{\Delta A_{i} B C}\right) \tag{26}
\end{align*}
$$

Substituting in the above from (22-25), then,
$S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)}=\left\{r_{i+1}{ }^{2} \cos ^{-1} \frac{r_{i} \sin \theta_{i}-d}{r_{i+1}}-\left(r_{i} \sin \theta_{i}-\right.\right.$
d) $\left.r_{i} \cos \theta_{i}\right\}-\left\{r_{i+1}{ }^{2}\left(\frac{\pi}{2}-\theta_{i}\right)-\frac{1}{2} r_{i}{ }^{2} \sin 2 \theta_{i}\right\}$
(27)

As may be seen the expression for the nonoverlapping area differs from the previous case given in (16). Substituting (27) into (3) gives the conditional probability of no handover for this case,
$P_{r}\left(\right.$ no handover $\mid r_{i}$ and $\left.\theta_{i}\right)=\exp \left\{-\lambda\left[\left[r_{i+1}{ }^{2} \cos ^{-1} \frac{r_{i} \sin \theta_{i}-d}{r_{i+1}}-\right.\right.\right.$
$\left.\left.\left.\left(r_{i} \sin \theta_{i}-d\right) r_{i} \cos \theta_{i}\right]-\left[r_{i+1}{ }^{2}\left(\frac{\pi}{2}-\theta_{i+1}\right)-\frac{1}{2} r_{i}{ }^{2} \sin 2 \theta_{i}\right]\right]\right\}$
Case (iii) : Tagged base station $C$ is in quadrant $I V$.
This case is shown in Fig. 8, again derivation of the probability of no handover is similar to the previous cases, therefore, we will only explain the differences and otherwise present the results.
For convenience in this analysis $\theta_{i}$ will be measured counterclockwise from the horizontal axis.


Figure 8: The network diagram when tagged base station $C$ is in quadrant $I V$.

From Fig. 8, we let $D$ denote the extension of the line $A_{i} A_{i+1}$ that intersects with $B C$. Then, we have,

$$
\begin{gather*}
\left|A_{i} D\right|=r_{i} \sin \theta_{i}, \quad\left|A_{i+1} D\right|=r_{i} \sin \theta_{i}+d, \\
|C D|=|B D|=r_{i} \cos \theta_{i} \tag{29}
\end{gather*}
$$

As may be seen, $\left|A_{i+1} D\right|$ differs from the previous cases. Next, we give the equations corresponding to (6-12) for this case,

$$
\begin{equation*}
r_{i+1}=\sqrt{\left(r_{i} \sin \theta_{i}+d\right)^{2}+r_{i}^{2} \cos ^{2} \theta_{i}} \tag{30}
\end{equation*}
$$

$$
\begin{gather*}
\varphi_{i+1}=\cos ^{-1} \frac{\left|A_{i+1} D\right|}{\left|A_{i+1} C\right|}=\cos ^{-1} \frac{r_{i} \sin \theta_{i}+d}{r_{i+1}}  \tag{31}\\
\theta_{i+1}=\frac{\pi}{2}-\cos ^{-1} \frac{r_{i} \sin \theta_{i}+d}{r_{i+1}}  \tag{32}\\
\varphi_{i}=\frac{\pi}{2}-\theta_{i}  \tag{33}\\
S_{\nabla A_{i} B C}=\varphi_{i} r_{i}^{2}=r_{i}^{2}\left(\frac{\pi}{2}-\theta_{i}\right)  \tag{34}\\
S_{\nabla A_{i+1} B C}=\varphi_{i+1} r_{i+1}^{2}=r_{i+1}^{2} \cos ^{-1} \frac{r_{i} \sin \theta_{i}+d}{r_{i+1}}  \tag{35}\\
S_{\Delta A_{i} B C}=\left|A_{i} D\right| *|C D|=\frac{1}{2} r_{i}^{2} \sin 2 \theta_{i}  \tag{36}\\
S_{\Delta A_{i+1} B C}=\left|A_{i+1} D\right| *|C D|=\left(r_{i} \sin \theta_{i}+d\right) r_{i} \cos \theta_{i} \tag{37}
\end{gather*}
$$

Then, the area of the intersection of the circles centered at $A_{i}$ and $A_{i+1}$ respectively, is given by,

$$
\begin{align*}
& S_{A_{i} \cap A_{i+1}}=S_{A_{i}}-\left[\left(S_{\nabla A_{i+1} B C}-S_{\Delta A_{i+1} B C}\right)\right. \\
& \left.\quad-\left(S_{\nabla A_{i} B C}-S_{\triangle A_{i} B C}\right)\right] \tag{38}
\end{align*}
$$

where $S_{A_{i}}$ is given by,

$$
\begin{equation*}
S_{A_{i}}=\pi r_{i}^{2} \tag{39}
\end{equation*}
$$

Substituting in (38) from (34-37) and (39), then,
$S_{A_{i} \cap A_{i+1}}=\pi r_{i}^{2}-\left[\left\{r_{i+1}{ }^{2} \cos ^{-1} \frac{r_{i} \sin \theta_{i}+d}{r_{i+1}}-\left(r_{i} \sin \theta_{i}+\right.\right.\right.$ d) $\left.\left.r_{i} \cos \theta_{i}\right\}-\left\{r_{i+1}{ }^{2}\left(\frac{\pi}{2}-\theta_{i}\right)-\frac{1}{2} r_{i}{ }^{2} \sin 2 \theta_{i}\right\}\right]$
(40)

Next, the area of the circle at $A_{i+1}$ that does not overlap with circle $A_{i}$,

$$
\begin{equation*}
S_{A_{i+1}-\left(A_{i} \cap A_{i+1}\right)}=S_{A_{i+1}}-S_{A_{i} \cap A_{i+1}} \tag{41}
\end{equation*}
$$

where $S_{A_{i+1}}$ is area of the circle $A_{i+1}$ given by,

$$
\begin{equation*}
S_{A_{i+1}}=\pi r_{i+1}^{2} \tag{42}
\end{equation*}
$$

Next, substituting $(40,42)$ in $(41)$ and then the result in (3) gives,

$$
\begin{align*}
& P_{r}\left(\text { no handover } \mid r_{i} \text { and } \theta_{i}\right)=\exp \left[-\lambda\left\{\pi r_{i+1}{ }^{2}-\quad\left[\pi r_{i}^{2}-\right.\right.\right. \\
& {\left[\left\{r_{i+1}{ }^{2} \cos ^{-1} \frac{r_{i} \sin \theta_{i}+d}{r_{i+1}}-\left(r_{i} \sin \theta_{i}+d\right) r_{i} \cos \theta_{i}\right\}-\left\{r _ { i + 1 } { } ^ { 2 } \left(\frac{\pi}{2}-\right.\right.\right.} \\
& \left.\left.\left.\left.\left.\left.\theta_{i}\right)-\frac{1}{2} r_{i}{ }^{2} \sin 2 \theta_{i}\right\}\right]\right]\right\}\right] \tag{43}
\end{align*}
$$

## 4 DETERMINING PROBABILITY DISTRIBUTION OF PATH LENGTH WITHOUT HANDOVER

Next, we will determine probability distribution of path length without handover. Let us assume that when the user is at position $A_{1}$, it is being served by the base station $C$. From the results of the previous section, probability of no handover may be determined recursively as the user moves from one position to the next one.

If path length without handover is $\ell$ or more steps it means that when the user is at location $A_{\ell}$ it is still being served by station C.


Figure 9: The network diagram as the user moves from position $A_{1}$ towards $A_{\ell}$ with the initial tagged base station being $C$.

Let us define,
$F_{\ell}=P_{r}$ (no handover is at least $\ell$ steps), $\ell \geq 1$.
$P_{\ell}=P_{r}$ (no handover is $\ell$ steps), $\ell \geq 0$.
Next, we will determine these probabilities conditioned on the location of the base station $C, r_{1}, \theta_{1}$.

Defining,
$F_{\ell \mid r_{1}, \theta_{1}}=P_{r}$ (no handover is at least $\ell$ steps $\left.\mid r_{1}, \theta_{1}\right)$
$P_{\ell \mid r_{1}, \theta_{1}}=P_{r}\left(\right.$ no handover is $\ell$ steps $\left.\mid r_{1}, \theta_{1}\right)$
Then, we have,
$F_{\ell \mid r_{1}, \theta_{1}}=$
$\prod_{i=2}^{\ell+1} P_{r}\left(\right.$ no stations in $S_{A_{i}-\left(A_{i-1} \cap A_{i}\right)} \mid r_{1}$ and $\left.\theta_{1}\right)$,
$\ell \geq 1$

$$
\begin{equation*}
P_{\ell \mid r_{1}, \theta_{1}}=F_{\ell \mid r_{1}, \theta_{1}}-F_{\ell+1 \mid r_{1}, \theta_{1}}, \ell \geq 1 \tag{44}
\end{equation*}
$$

$P_{\ell \mid r_{1}, \theta_{1}}=1-P_{r}\left(\right.$ no base station in $S_{A_{2}-\left(A_{1} \cap A_{2}\right)} \mid r_{1}$ and $\left.\theta_{1}\right)$, $\ell=0$.

Finally, unconditional distribution of probability that path length with no handover equals to $\ell$ steps is given by,

$$
\begin{equation*}
P_{\ell}=\int_{0}^{2 \pi} \int_{0}^{\infty} P_{\ell \mid r_{1}, \theta_{1}} f\left(r_{1}, \theta_{1}\right) d r_{1} d \theta_{1} \tag{46}
\end{equation*}
$$

where $f\left(r_{1}, \theta_{1}\right)$ is the joint probability density function (pdf) of the location of the tagged base station when the user is at location $A_{1}$, next we will determine this joint pdf. Let us define the following probability distribution,
$G\left(r_{1}\right)=P_{r}$ (when the user is at location $A_{1}$ and its distance to station $C$ is less than $r_{1}$ )

$$
\begin{aligned}
& G\left(r_{1}\right)=1-P_{r}(\text { no base station } \\
& \left.\quad \text { within the circle centered at } A_{1} \text { and radius } r_{1}\right)
\end{aligned}
$$

From equation (1),

$$
\begin{equation*}
G\left(r_{1}\right)=1-e^{-\lambda \pi r_{1}^{2}} \tag{47}
\end{equation*}
$$

Then, pdf of the user distance when it's at $A_{1}$ to the tagged base station is given by,

$$
\begin{equation*}
g\left(r_{1}\right)=\frac{d G\left(r_{1}\right)}{d r_{1}}=2 \lambda \pi r_{1} e^{-\lambda \pi r_{1}^{2}}, r_{1}>0 . \tag{48}
\end{equation*}
$$

Since the tagged base station is equally likely to be at any location on the circle centered at $A_{1}$ with radius of $r_{1}$, the pdf of $\theta_{1}$ is given by,

$$
\begin{equation*}
h\left(\theta_{1}\right)=\frac{1}{2 \pi}, \quad 0<\theta_{1}<2 \pi \tag{49}
\end{equation*}
$$

and joint pdf is given by,

$$
\begin{equation*}
f\left(r_{1}, \theta_{1}\right)=g\left(r_{1}\right) h\left(\theta_{1}\right) \tag{50}
\end{equation*}
$$

We note that the double integral in (46) does not have a closed form and it needs to be evaluated numerically.

The average path length without hand over is given by,

$$
\begin{equation*}
\bar{L}=\sum_{\ell=1}^{\infty} \ell P_{\ell} \tag{51}
\end{equation*}
$$

## 5 NUMERICAL RESULTS

In this section, we present numerical results regarding the analysis in the paper as well as simulation results for comparison. The results are given for three cell sizes with radiuses, 50,100 and 200 m . We assume that the step size is $d=$ 1 m , We note that step size may be chosen arbitrarily small to achieve any accuracy.
Table 1. shows the average path length without handover for both analysis and simulation. As may be seen, the numerical and simulation results are very close to each other. It's also seen that the average path length without handover increases with increasing cell radius. Figures $10-15$ show the probability of path
length without handover as a function of the number of steps for both analysis and simulation for the three cell sizes. It may be seen that probability of no handover drops down gradually with increasing path length. As may be seen again, analysis and simulation results are in agreement with each other, which gives further evidence that the analysis is correct.

| $\mathbf{r}(\mathbf{m})$ | Analysis | Simulation |
| :---: | :---: | :---: |
| 50 | 40.76 | 40.62 |
| 100 | 82.01 | 82.53 |
| 200 | 164.50 | 165.02 |

Table. 1: Average path length without handover for both analysis and simulation for cell sizes with radiuses 50, 100 and 200 m .


Figure 10: Probability of path length without handover for cell radius of 50 m from analysis.


Figure 11: Probability of path length without handover for cell radius of 50 m from simulation.


Figure 12: Probability of path length without handover for cell radius of 100 m from analysis.


Figure 13: Probability of path length without handover for cell radius of 100 m from simulation.


Figure 14: Probability of path length without handover for cell radius of 200 m from analysis.


Figure 15: Probability of path length without handover for cell radius of 200 m from simulation.

## 6 CONCLUSIONS

In this paper, we have studied user mobility in cellular networks. We have derived probability distribution of path length without handover as the user moves along a straight line. The analytical and simulation results are in agreement with each other which provides further proof that analysis is correct. To the best of our knowledge, this is the first result on the path length distribution of the user with the same base station. The knowledge of the
probability distribution of path length without handover will enable better assessment of the impact of handover on the performance of the system.

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