# Optimal PEEP selection in Mechanical Ventilation using EIT

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#### Outline

#### Introduction

- The Problem
- How to solve the problem?

#### Contributions

- IP Calculation
- Fuzzy Logic System

#### 3 Results

- Sigmoid vs. Linear
- Linear vs. Visual
- Optimal PEEP

#### References

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- **Purpose:** Investigate the use of Electrical Impedance Tomography (EIT) within mechanical ventilation.

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- Contributions:
  - Summarize scholarly papers on ALI.
  - Inflection Point (IP) location on EIT and pressure data.
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  - Summarize scholarly papers on ALI.
  - Inflection Point (IP) location on EIT and pressure data.
  - S Creation of Fuzzy Logic System using IP.
- Novel Aspects:
  - **1** Use of short recruitment maneuever ( $\leq 2$ min)
  - 2 Regional Inflection Points used
  - Use of Inflection Points within an automated classification system

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#### The Problem

# ALI & VILI



#### **Respiratory Function Models**

$$P_{ao} = \frac{V}{C} + \dot{V}R + \ddot{V}I - P_{mus} \tag{1}$$

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- Interested in  $\frac{V}{C}$  only.
- To remove other components this thesis data did two things:
  - Slow Constant Flow
  - 2 Antheysia

#### Pressure-Volume Curves

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#### Data used

Data used:

- 26 patients
- low constant flow maneuver (4 L/min)
- start 0 mbar  $\rightarrow$  35 mbar / 2L



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# Electrical Impedance Tomography (EIT)

EIT is real-time impedance tomography, it can be used to accuratly measure air distrubtion within the thorax.

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Figure: Example reconstruction using the GREIT methods of a healthy lung patient (patient 7).

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### Contributions

#### • Automated IP calculation

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### Contributions

- Automated IP calculation
- Rule-base Fuzzy Logic Classifier

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Three Types of IP location methods were used:

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# **IP** Calculation

Three Types of IP location methods were used:

Sigmoid method

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- 3-piece linear spline method

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Three Types of IP location methods were used:

- Sigmoid method
- ② Visual heuristics
- 3 -piece linear spline method

Multiple methods were implemented for comparison reasons.

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#### Sigmoid Method



- Clinicians used this method to locate Inflection Points from global PV curves.
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  - Place two line. 1) Along low compliance. 2) Along High compliance. Locate Intersection.

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- Multiple methods exist:
  - Ind location where PV curve has linear compliance
  - Pressure where rapid increase in compliance occurs
  - Place two line. 1) Along low compliance. 2) Along High compliance. Locate Intersection.
- This thesis:
  - 5 participants
  - If in linear manner to get closest to all the data points

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 Image: Non-State
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• Similar to visual methods

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- Fits to 3 lines with Inflection Points being located at intersection

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Location of IP

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- Location of IP
- ② Fuzzification

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The Fuzzy System is designed into 4 sections:

- Location of IP
- Puzzification
- O Premise Calculation (Application of IF-THEN)
- Oefuzzification and Optimization

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#### **IP** and **Fuzzification**

IP were taken from the 3-piece linear optimization portion and used in the creation of the fuzzification graphs.

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Membership	Input 1 (mbar)	Input 2 (mbar)	Input 3 (mbar)	Input 4 (mbar)
Below	min(p)	min(p)	-2+LIP	LIP
In Between	-2+LIP	LIP	UIP	2+UIP
Above	UIP	2+UIP	max(p)	max(p)

Table: Details on creating the trapezoidal based fuzzy membership functions

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The Inference is conducted using the Rule base. With key relations to previous papers:

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- Pressure below the LIP is considered collapsed
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- Good' = Normal states
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**Defuzzification** was done by breaking the output states into two classifications:

- Good' = Normal states
- 2 'Bad' = Collpased + Overdistended states

Upon averaging over lung region MAX value between the difference of 'Good' and 'Bad' states is performed to locate the PEEP. • Fuzzy Logic Schematic

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#### Sigmoid vs. Linear



Figure: How frequent each sigmoid and linear method are not able to find IP.

#### Sigmoid vs. Linear

![](_page_48_Figure_2.jpeg)

Figure: How frequent each sigmoid and linear method are not able to find IP.

	Mean	Std	Median
LIP - Inflation	1.47	3.02	1.50
UIP - Inflation	-6.80	2.54	-6.82
LIP - Deflation	4.07	1.84	4.07
UIP - Deflation	-2.37	2.24	-2.78

Table: Difference between Sigmoid and Linear Method

#### Linear vs. Visual Heuristics

#### • Difference = Linear IP – Visual Heuristic IP

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#### Linear vs. Visual

#### Linear vs. Visual Heuristics

- Difference = Linear IP Visual Heuristic IP
- -0.6247mbar for LIP -0.4662mbar for UIP

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- best average = 0.016mbar worst average = -1.507mbar

#### Linear vs. Visual Heuristics

- Difference = Linear IP Visual Heuristic IP
- -0.6247mbar for LIP -0.4662mbar for UIP
- best average = 0.016mbar worst average = -1.507mbar
- Provides insight to accuracy of linear method

#### Results

#### **Optimal PEEP**

#### Hetergenaity

![](_page_53_Figure_3.jpeg)

Figure: Progressive change of lung state with pressure

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### LIP+2 vs FLS

![](_page_54_Figure_3.jpeg)

Figure: Global PI curve with LIP, UIP, and the LIP+2 mbar pressure and the Fuzzy optimal selection with according FLS based pressure.

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▶ Fuzzy Logic Schematic

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