



AUTOMATIC DETECTION OF FEATURES IN ULTRASOUND IMAGES OF THE EYE

R. Youmaran, P. Dicorato, T. Hall, A. Adler



Outline

- Introduction
 - Problem definition
 - Parameters of interest
- The algorithm
- Results
- Concluding Remarks





Introduction

- Developed an automated technique to analyze ultrasound images of the eye & measure Glaucoma angle
- Proposed technique addresses the following challenges with Ultrasound images:
 - Denoising
 - Poor resolution
 - Poor contrast
 - Weak edge (boundary) delineation
 - Identification and feature extraction



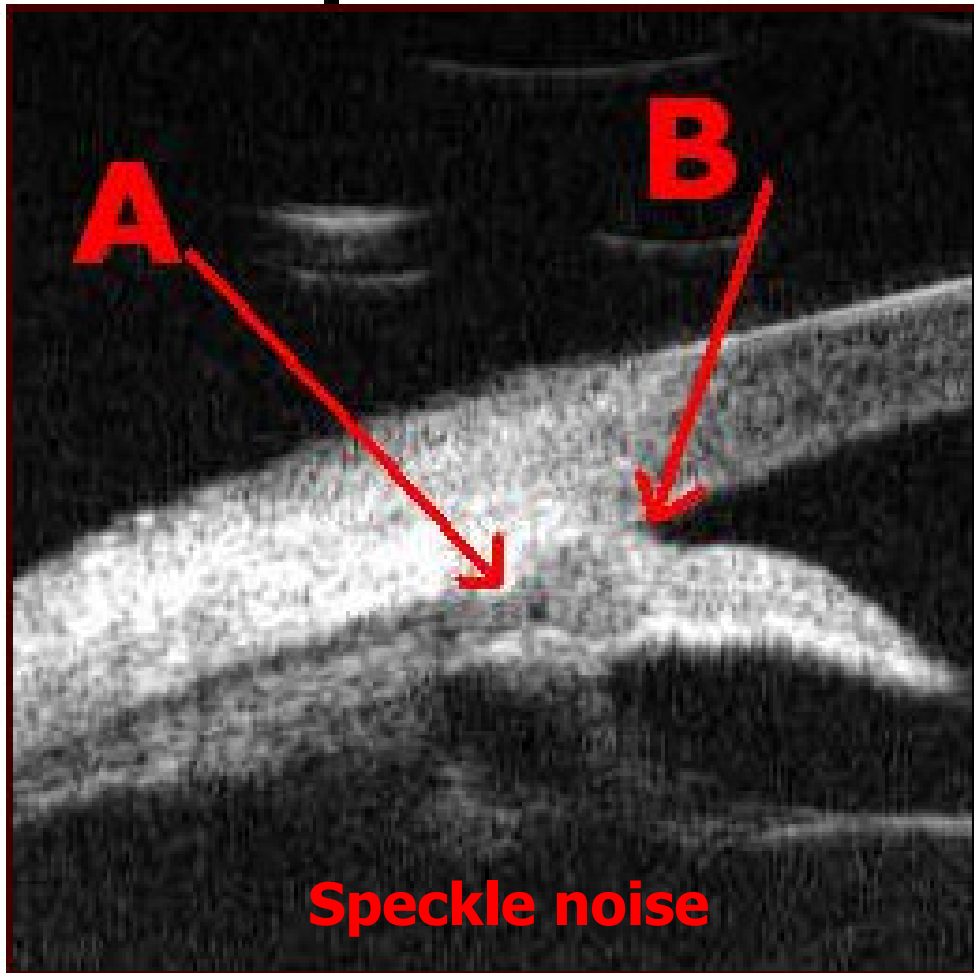


Problem definition

- Glaucoma involves increased fluid pressure inside the eye, which damages the optic nerve and causes partial vision loss and can progress to blindness
- Early detection of Glaucoma could prevent total loss of vision
 - Measure of IOP
 - Measure of open-angle



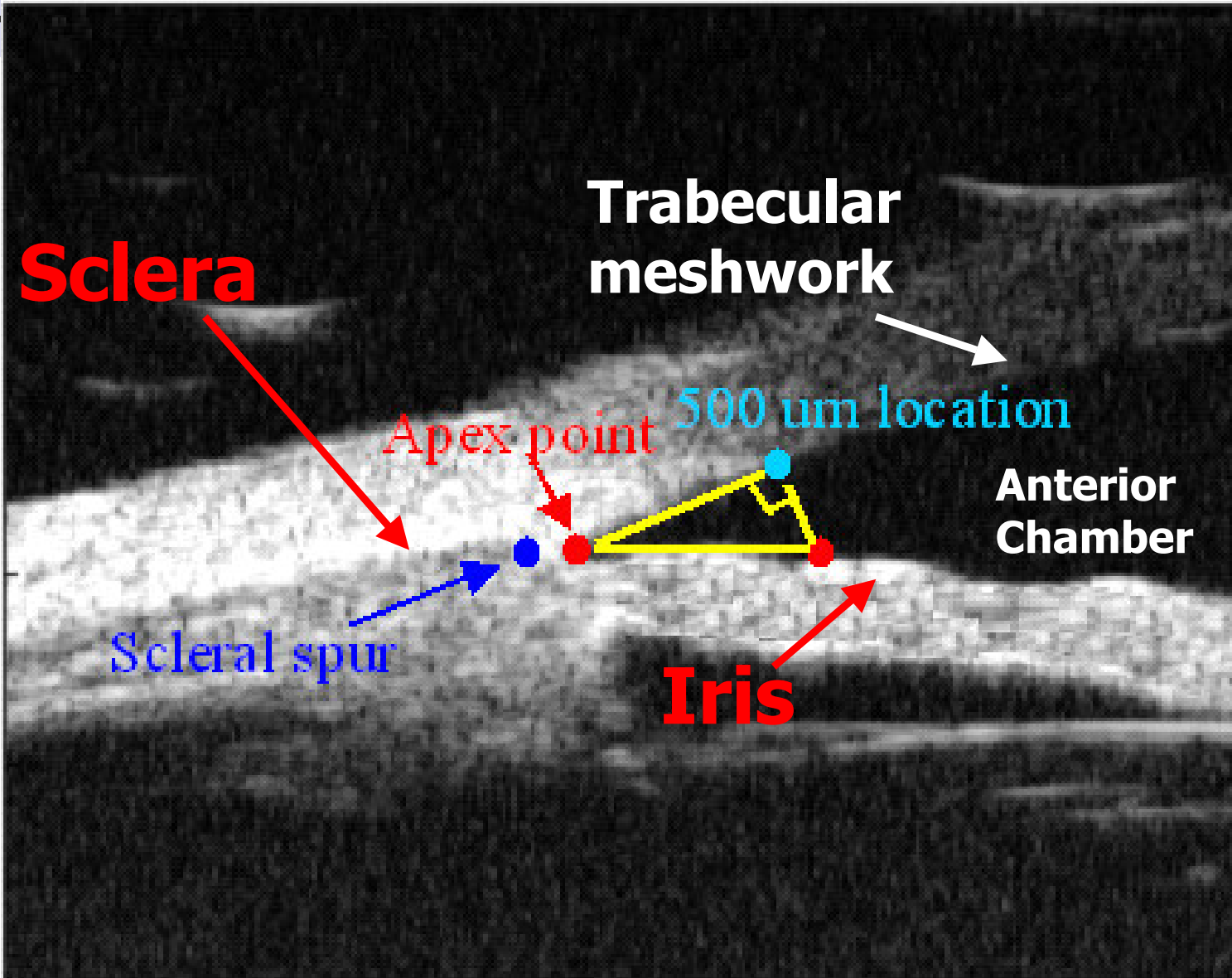
Parameters of interest



Feature A: Scleral Spur
Feature B: Apex point



Features of interest



Ultrasound images of the eye

Open (normal)



Closed (diseased)



**Intra-ocular
pressure**



uOttawa

L'Université canadienne
Canada's university



THE ALGORITHM



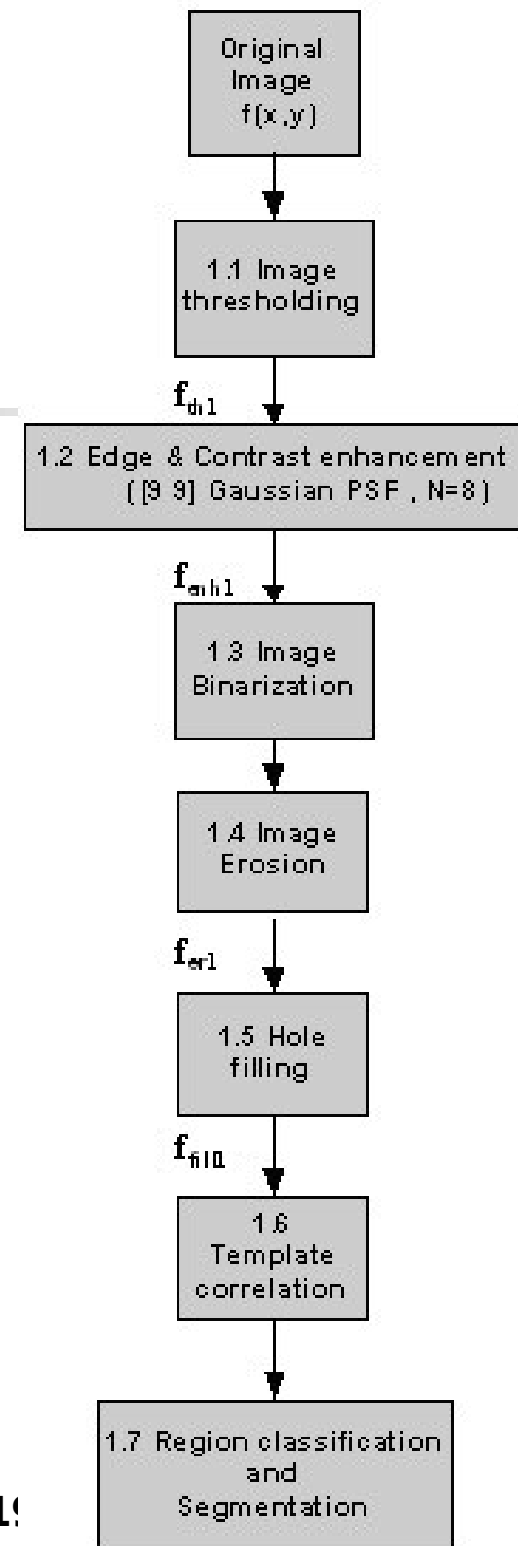
uOttawa

L'Université canadienne
Canada's university

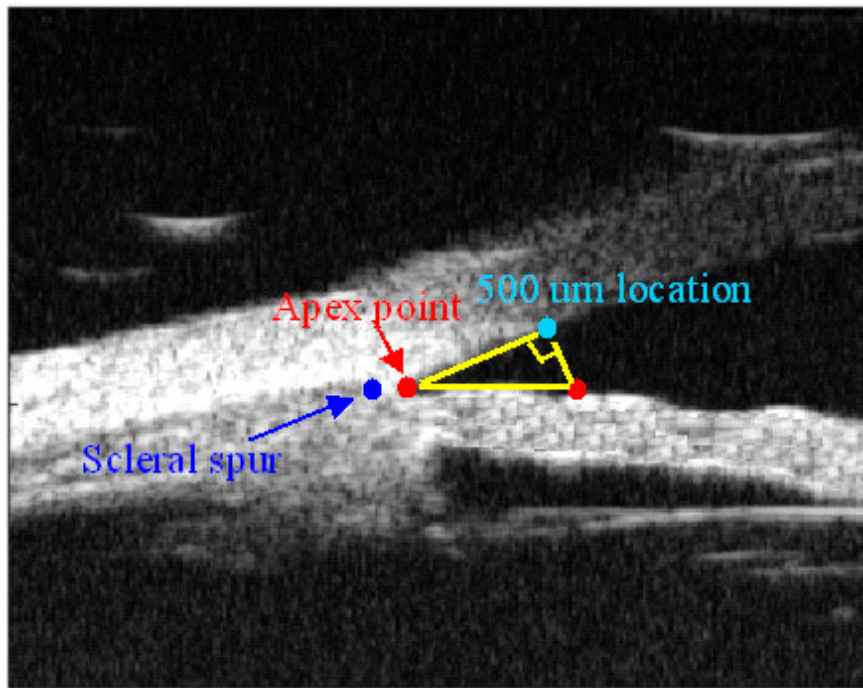
IMTC 2005, Ottawa, Canada, 17th-19th May 2005

Step 1

- Coarse enhancement
- Anterior chamber segmentation



Non-Linear Edge & Contrast Enhancement



uOttawa

L'Université canadienne
Canada's university

Original

Coarsely Enhanced

Template Correlation

- Correlation is used to locate the anterior chamber
- Template regions:



- Enhanced image is correlated with each template and the average correlation point is computed





Anterior Chamber Classification

- Each closed region is analyzed independently
- Classification is based on the geometrical properties:
 - object area
 - Centroid
 - major-axis
 - minor-axis length

using an elliptical model



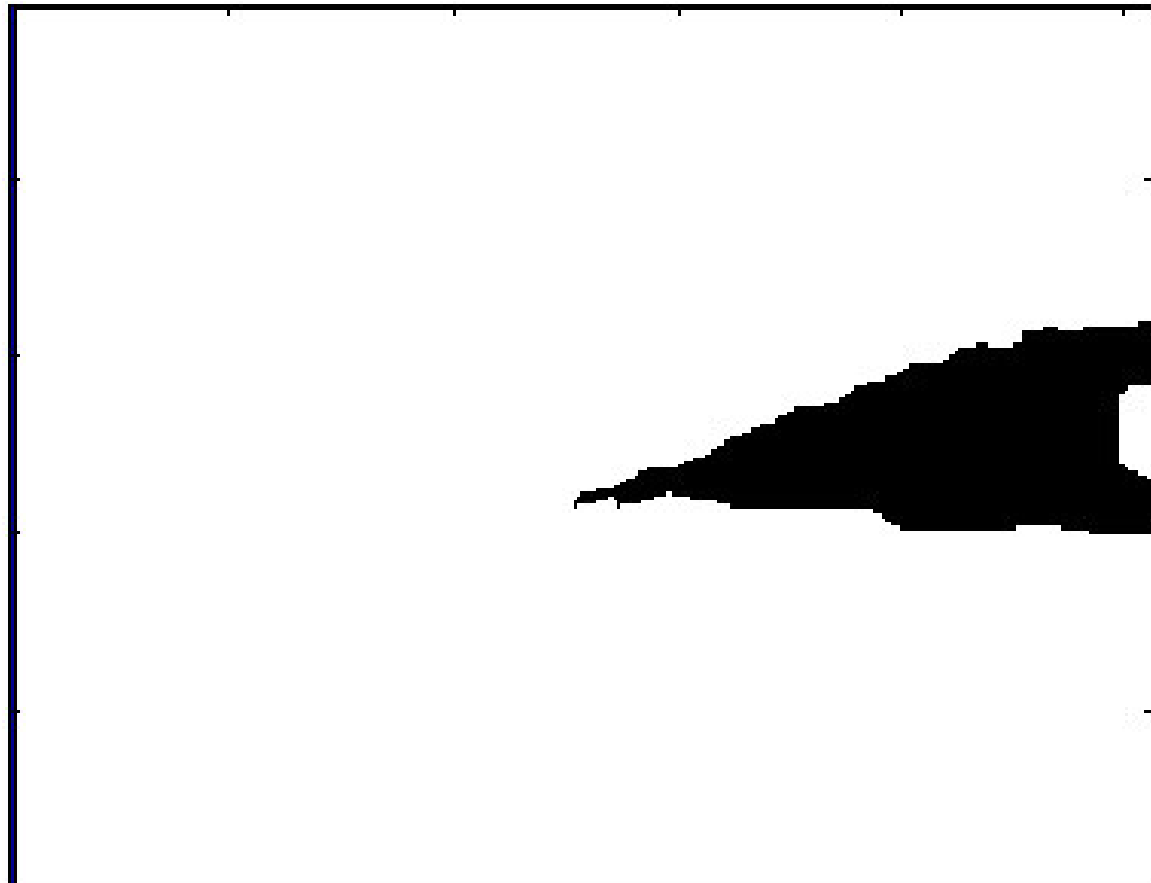


cont'd...

- The following parameters are computed for segmentation of the closed regions:
 - *Center*. Defined as the center coordinate of a region
 - *Distance center-correlation point*: **Must be minimized**
 - *Area*: Must be > 50 pixels, otherwise, the region is considered to be speckle noise

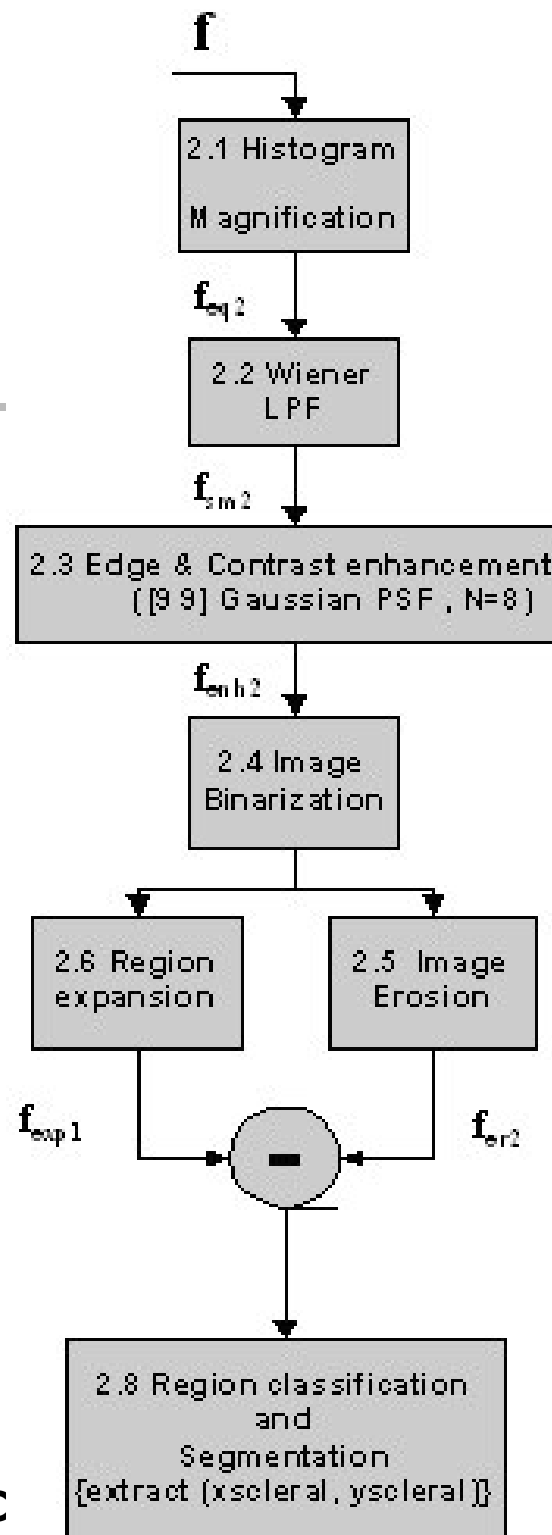


Anterior Chamber segmented



Step 2

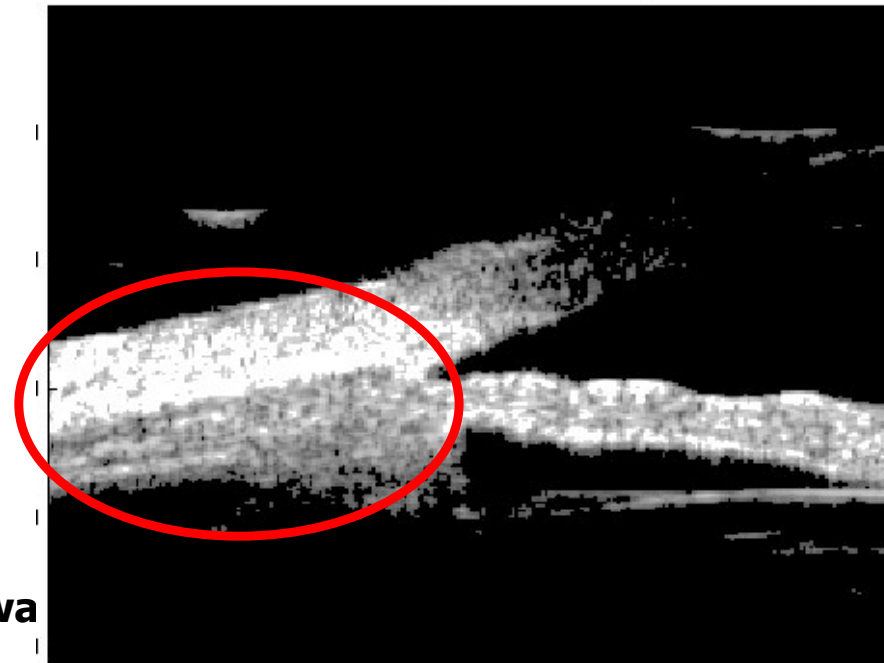
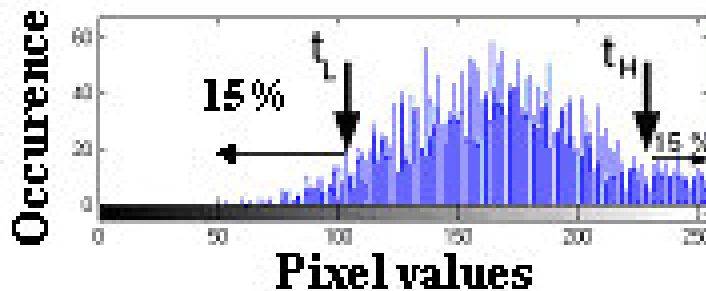
- Fine enhancement
- Sclera segmentation



Histogram magnification

- A histogram magnification: enhance texture of sclera
- Threshold values: 15% and 85% of the total number of pixels

Texture of interest



Enhancement result



uOttawa

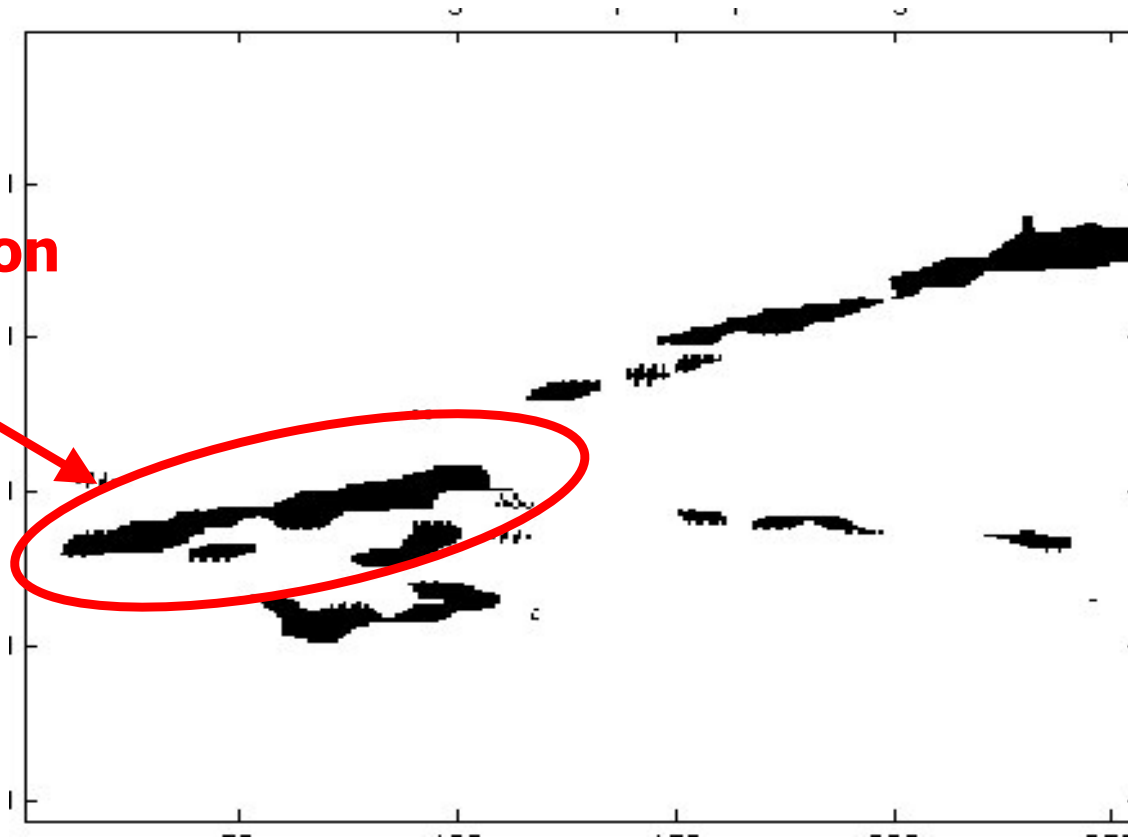
L'Université canadienne
Canada's university

IMTC 2005, Ottawa, Canada, 17th-19th May 2005

Region Subtraction

- Removes all large regions and keeps only fine details

Targeted region



IMTC 2005, Ottawa, Canada, 17th-19th May 2005

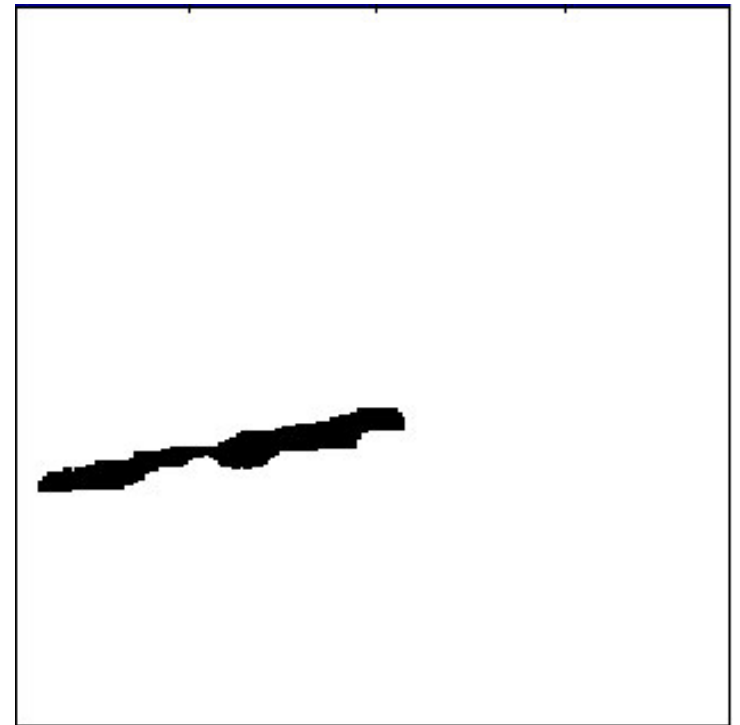


uOttawa

L'Université canadienne
Canada's university

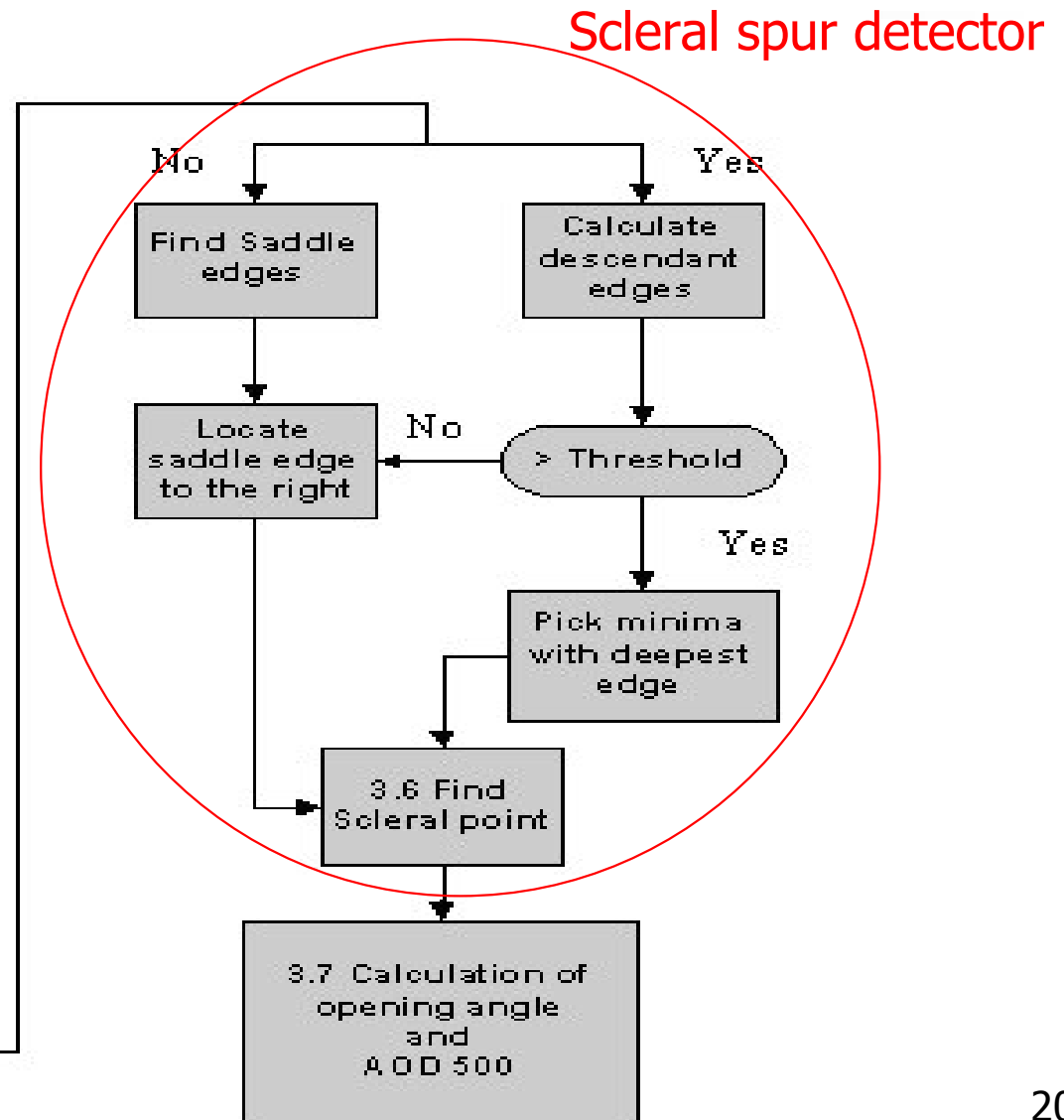
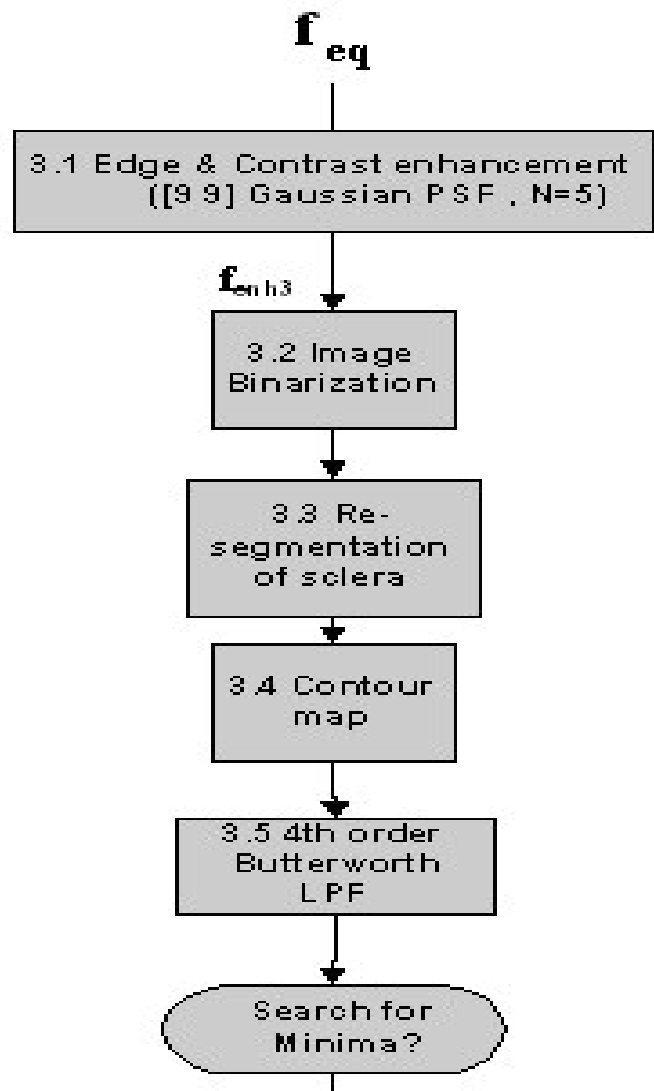
Sclera region classification and segmentation

- The following parameters are computed:
 - (a) Right-most pixel of each closed region
 - (b) Distance from the apex point to the right-most pixel is computed:
Must be minimized



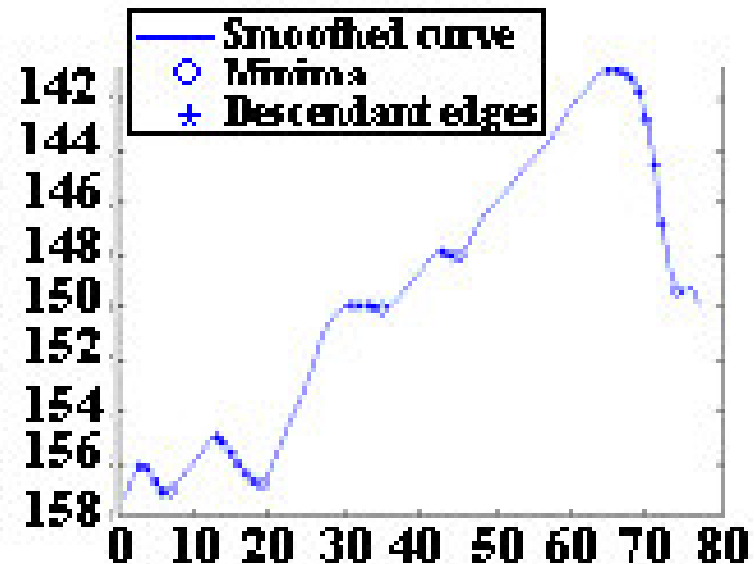
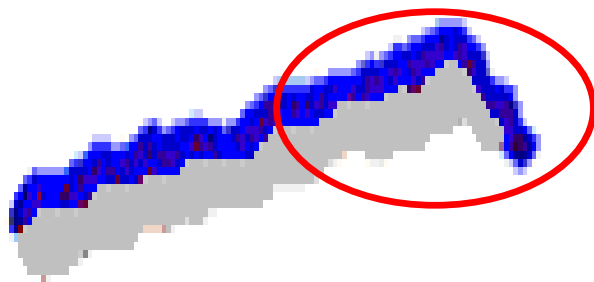
Step 3

- Extra fine enhancement
- Sclera region re-segmentation



Sclera Contour Mapping

- 1-D signal plot of the contour
- Smoothing: Remove outliers and abrupt variations in the outline





Scleral Spur Detection

- The scleral spur is detected based on the following steps:
 - (1) A gradient operator is applied on the smoothed contour
 - (2) All minima coordinates & points along descendent edge prior are computed
 - (3) If no minima are detected, all points with zero gradient are located and defined as saddle edges





cont'd...

- Identification/detection of the scleral spur:
 - **One local minimum:** The scleral spur coordinate
 - **Multiple minima:** Calculate the magnitude Δ_{edge} of each edge prior to a minimum. The largest Δ_{edge} is chosen to compute the scleral spur coordinate
 - **No minima:** Select the saddle edge located most to the right of the 1-D outline

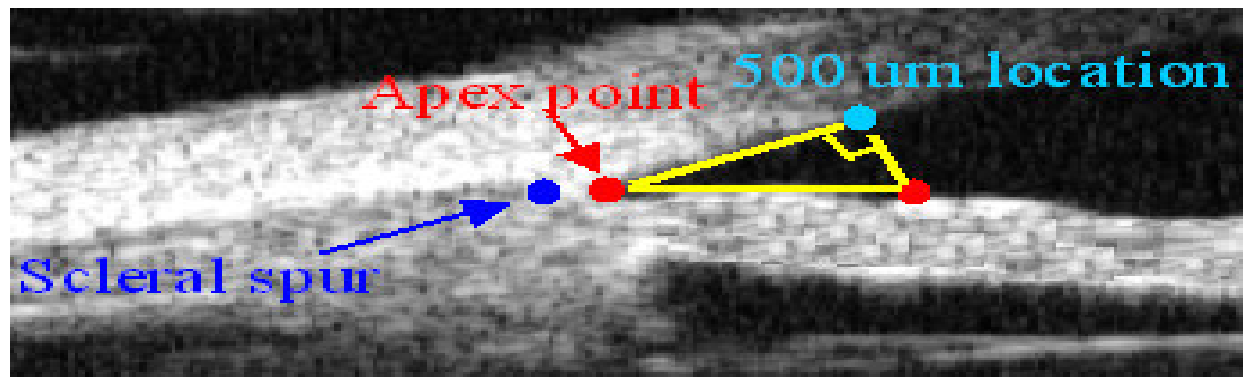


Determination of Measured Parameters

- Clinical parameters:

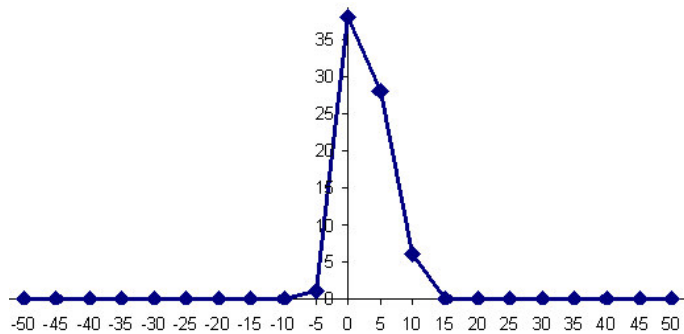
(1) Open-angle exists if the 500 μm point is located to the right of the Apex point

(2) AOD 500: Through orthogonal projection from the trabecular meshwork to the iris



Outcomes of Algorithm

Scleral Spur Pixel offset error

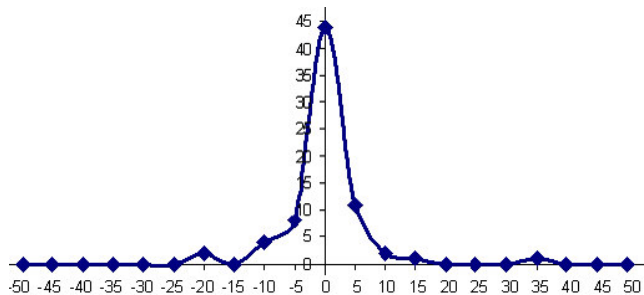


Horizontal direction

(1) Failure: Can not segment regions

(2) Success: Clinical parameters are computed and differ from those measured by the technologist to within 97.5 μm

(3) Potential Fault/Error: The offset error is greater than 97.5 μm in either direction



Vertical direction





Failure / Success rate

- On a sample of 80 images:
 - Features were correctly identified in 97% of images (outcome 2)
 - 3% of images presented inaccurate estimates (outcome 3) of the clinical parameters, with 351 um offset error on average





Concluding Remarks

- We proposed an algorithm to automatically identify clinical features in ultrasound images of the eye
- The algorithm computes the AOD 500 and the open-angle parameters
- The algorithm predictions are very similar to the trained technologist's observation
- Success rate is approximately 97%

