

# Automatic Identification of Participants in Haptic Systems

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# Agenda

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- Introduction
- Haptics-Biometric Systems
- Approach
- Results
- Conclusions and Further Work

# Introduction

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## Authentication Systems

- Something that you have (e.g., key)
- Something that you know ( PIN )

## Biometrics Systems

- Allow identification of individuals
  - Something that you are/do

- Iris Recognition
- Voice Recognition
- Face Recognition
- Fingerprint

## Haptics Systems

- Introduce the complex sense of touch, force and haptic feedback in human-computer int



# Can we authenticate using haptics?

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- Exploring the feasibility of automatically identifying participants using haptic systems
- It would lead to important and interesting applications ( e.g control access in haptic systems )
- Propose a research avenue for identification
- To explore the user's behaviour

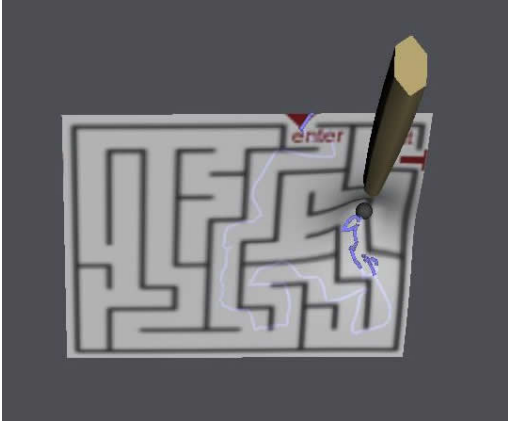
# Methodology

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- **Data Acquisition**
  - Haptic-based applications
  - Simple maze solving experimentation
- **Analysis:**
  - First Degree Statistics
  - Dynamic Time Warping
  - Spectral Analysis

# Data Acquisition

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- Haptic-Based Application
- Description:
  - 3D Elastic Membrane Maze solving process
- Software:
  - Python-VRML/Reachin API implementation

## Hardware:

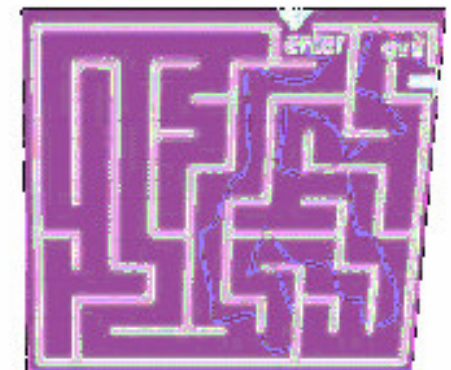
- Reachin Display system
  - Phantom, Display and Stereo-glasses



# Experiment

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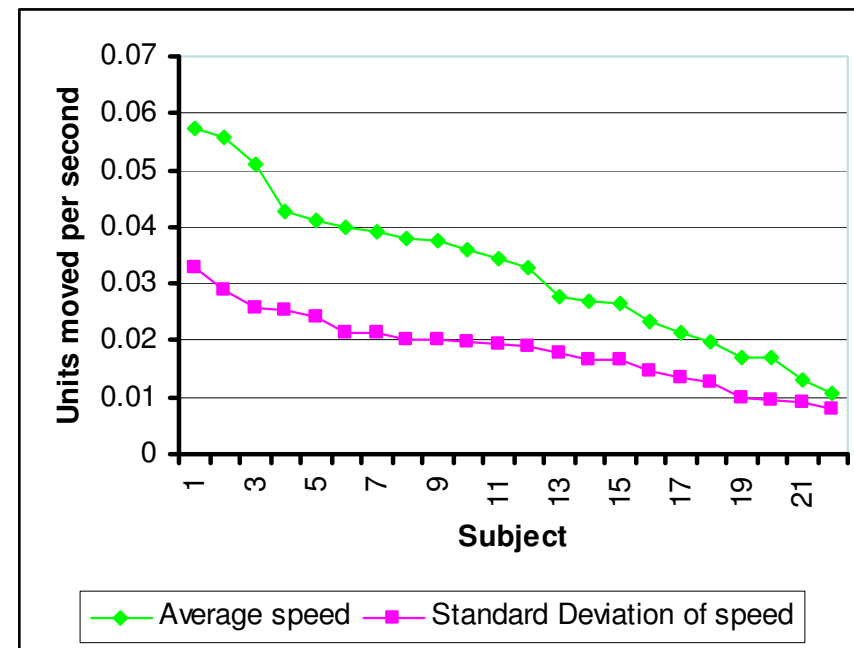
- To construct a Haptic maze on an elastic membrane
- User is asked to navigate the stylus through the maze
- Each person performed exactly the same maze 10 times.
- A group of 22 volunteers took part in the experiment



# First Degree Statistics

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- Each subject's comparable positions through the maze were evaluated
- Velocity was calculated in pixels/per second
- Velocity was relatively steady for most of the subjects
- Subjects with higher stylus speed showed different acceleration values.





# Analysis : Dynamic Time Warping

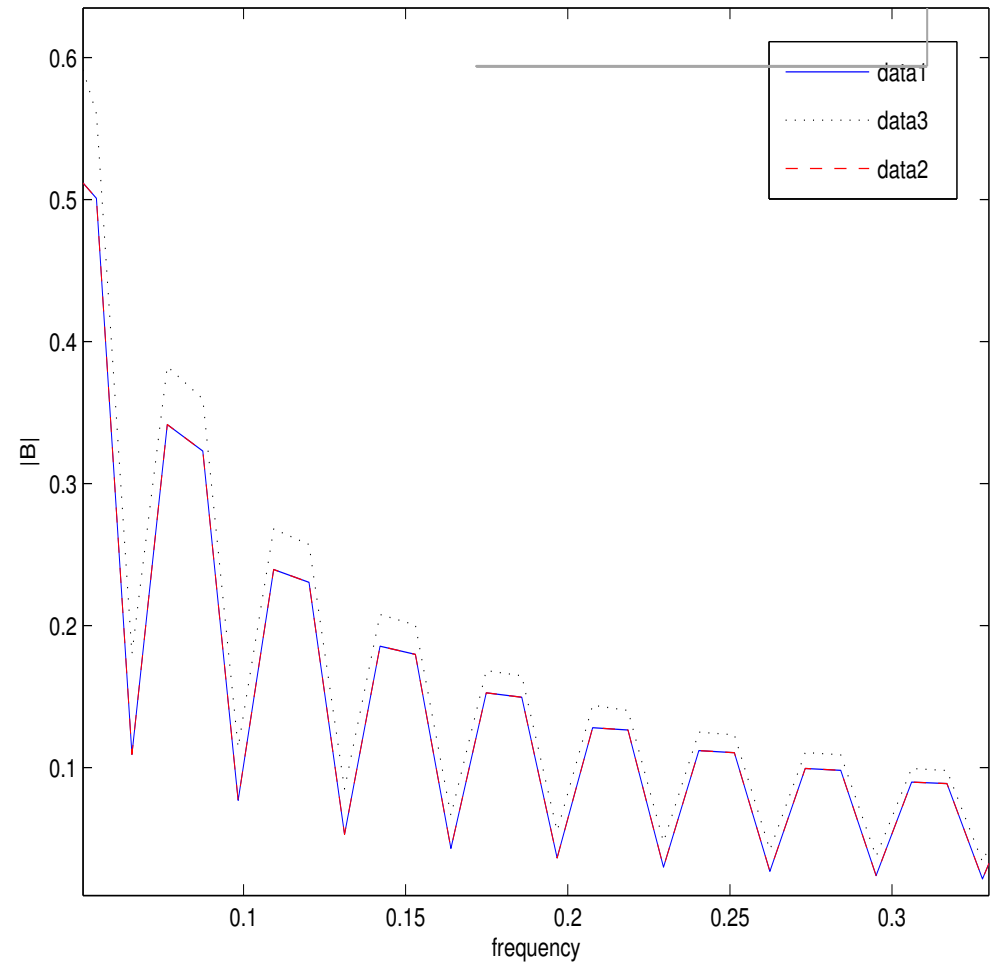
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- Dynamic time warping analysis creates a match score (MS) of two data sets  $d^1$  and  $d^2$
- Comparing their respective strokes; i.e. changes in direction on the 2D plane.
- This technique is used for false rejection rate and false accept rate (FRR/FAR) calculations

# Spectral Analysis

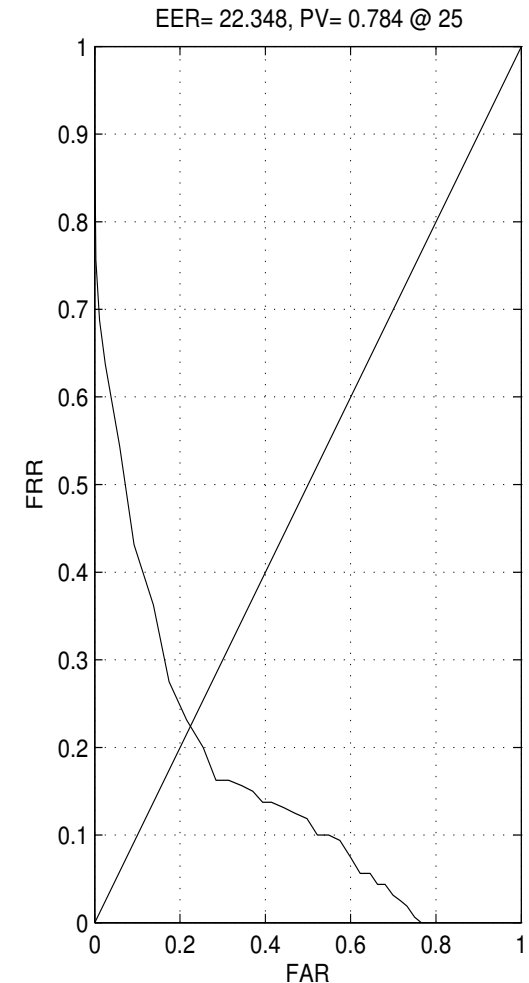
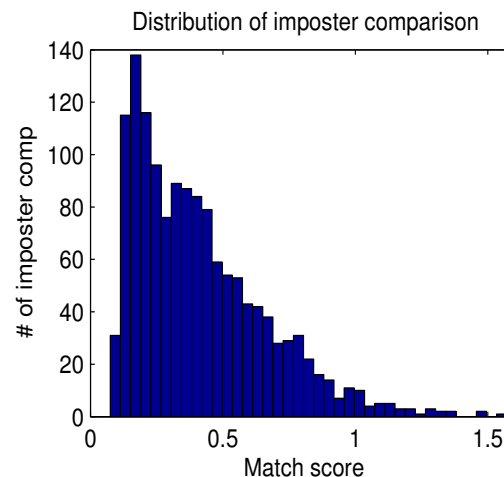
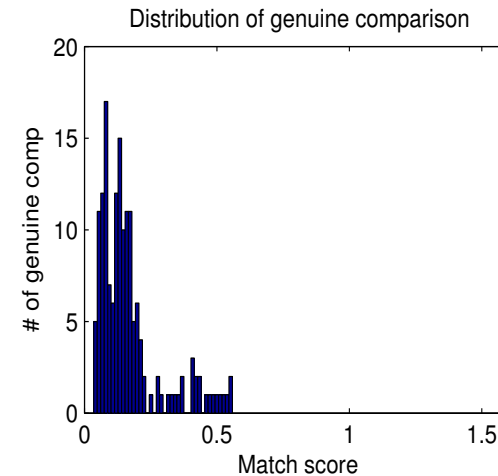
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- The frequency spectrum of the 3D position data is analyzed
- Based on windowed discrete time Fourier transform.
- $\text{data}_1$  and  $\text{data}_2$  are from the same user and  $\text{data}_3$  from different user



# Results

- To quantify the performance of the proposed algorithms:
  - Standard verification analysis was applied
- A Probability Verification(PV) of 78.8% at 25% FAR
- Equal Error Rate (EER) stands at 22.3% with a threshold MS of 0.195



# Conclusions and Further Work

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PV	Training Effect	
	With	Without
Time Warping	49.0%	60.1%
Spectral Analysis	67.6%	78.8%

- We have investigated the possibility of automatic identification in Haptic systems
- Results are mixed. Basic analysis appears to show a relatively low PV.
- On the other hand further analysis appears to show improvements in