# A Stroke Based Algorithm for Dynamic Signature Verification

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# Outline

- 1. Introduction
- 2. Data acquisition and signature processing
- 3. Feature extractions
- 4. Signature verification
- 5. Experiments
- 6. Conclusions

# 1. Introduction

#### ynamic Signature Verification in Biometric Techniques

- ► A biometric technique for authentication
  - Could replace today's password, pin number etc



#### Dynamic signature



# >Parameters of interest

- Pen tip velocity and acceleration
- Time between strokes
- Pressure
- Stroke sequencing
- . . .

# ➤Advantages

- Natural and intuitive
- Commonly accepted for authentication
- Less intrusive than iris, fingerprint, etc.

# ► *Related work*

- Time warping
- Euclidian or other distance measure
- neural network

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#### System Architecture



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#### 2. Data Acquisition and Signature Processing



Patriot digital pad



A sample signature



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#### 3. Feature Extraction Methods



#### Stoke Based Feature Extraction



#### Stoke Based Feature Extraction



Stroke-based normalized pressure vs. time

#### 4. Feature Distribution for Signature Verification



Average writing speed for a set of signatures



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Correlation value of significant stroke for a set of signatures



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# 5. Signature Verification Experiments

# **Experiment 1**

- # of volunteers : 10
- # of signatures: 110
- Training set : 50 signatures
- Test set: 60 signature

# **4 best non-stroke based features**

• Average writing speed

. . .

- Total time during the signing process
- Var\_pressure in 10 sliding windows
- Mean\_x\_ displacement in 100 windows

#### • Objective: To compare the effect of non-stroke based features with stroke based features when they apply in a verification system

### **Stroke based features**

- Correlation coefficient for the pressure significant strokes
- Time duration for velocity significant stroke

FRR and FAR comparison

	False Reject Rate (FRR)	False Accept rate (FAR)
4 feature based system (without stroke features)	30%	46.67%
6 feature based system (with stroke features)	6.67%	13.33%

# 5. Signature Verification Experiments

# **Experiment 2**

- # of volunteers : 10
- # of signatures: 180
- Training set : 120 signatures (60, 20 and 5 signatures)
- Test set: 60 signature
- 6 features based system

# <u>Results</u>

- FRR of 3.33% < 6.67% in Exp. 1
- FAR of 6.67% < 13.33% in Exp. 1
- A large training set get better performance
- Smaller training sets don't have high cost

# **Experiment 3**

- # of volunteers : 10
- # of signatures: 55
- Training set : 25 signatures
- Test set: 30 signature
- 6 features based system



FRR and FAR tradeoff curve on variable thresholds

#### 5. Signature Verification Experiments

#### Dynamic Signature Verification Using Stroke Based Feature Extraction Algorithm \_ 8 × File Edit View Insert Tools Window Help Control Manual User Interface for Dynamic Signature Verification Using Stroke Based Feature Extraction Algorithm Procedure: Displacement X Displacement Y 1)User sign several signatures; Sample Dynamic Signature Signal Block Blue - pressure values 2)Show training signals; 3)Another user input signature: Blue - Template signature Red - pen lifted up from 0.5 0.5 4)Show test signal; the pad surface Red - Current signature 5)Comparrison; 0 6)Check; 500 1000 0 500 1000 7)Clear test block; Velocity X Signature Velocity Y 8)Next user. 2 0.5 BROMPTICKS WNAMIC SIGNATURE -2 L -1 Signals DNA 0.5 n. 500 1000 500 1000 FALL Pressure Velocity Angle IRIS SCAN Voice FINGERPRINT 1 SIGNATURE Template Signal BEHAMIC 0.5 0.5 0.5 IC CARD STAMP CARD 0 0 Current Signal Kev 500 1000 500 1000 Ó. 500 1000 n. OBJECT - 🗆 × 🜖 Right Features Ε. 000----RIGHT----000 **Feature Block Reference Features** Dot - Reference signatures Circle - Current signature ΟK **Current Feature** Checking Feature #1 Feature #3 Feature #5 0.5 0.05 . ٠ 0 0.5 Clear 0 0 0 0 8 8 0 4 6 0 4 6 n. 4 6 MCR Lab VIVO Lab Feature #2 Feature #4 Feature #6 4000 40 Multimedia Communication Video Image Vison 0 **Research Lab** Audio Lab 0 3000 6 0 30 University of Ottawa Univeristy of Ottawa Ottawa, ON, CANADA Ottawa, ON, CANADA 2000 20 http://www.mcrlab.uottawa.ca http://www.site.uottawa.ca/ 2 6 8 0 2 6 8 2 6 8 0 school/research/viva/

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# 6. Conclusions and future work

#### **Conclusions**

- A novel stroke based feature algorithm
- A DSV system was successfully designed, developed, and tested
- Stroke based features improve accuracy
- Reduced 23.33% in FRR and 33.33% in FAR
- Larger training sets perform better
- A FRR and FAR tradeoff curve

#### <u>Future work</u>

- Bigger reference signature set
- More features
- Updated digital pad