

SYSC 5701

Operating System Methods for Real-Time Applications

Priority-Driven Scheduling for Periodic Tasks

Winter 2014

Assumptions (Liu Ch. 6)

1. no aperiodic or sporadic tasks
2. tasks are independent
3. uniprocessor
- will relax assumptions 1 & 2 later
 - aperiodic & sporadic → Liu Ch. 7
 - interdependency → Liu Ch. 8
 - Already seen “Access Control”!

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2

Uniprocessor

- why not relax this assumption?
- multiprocessor typically managed by allocating a set of tasks to each processor
 - static: once allocated, task handled only by that processor
 - tasks do not migrate among processors
- have a fixed task set for each processor

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3

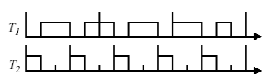
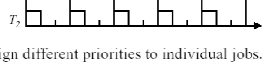
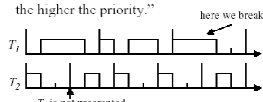
Priority-Driven Scheduling Algorithms

- **Static-(or Fixed-)Priority** – assigns the same priority to all jobs in a task.
- **Dynamic-Priority** – may assign different priorities to individual jobs within each task
 - e.g., earliest-deadline-first (EDF) algorithm

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4

Static-Priority vs. Dynamic Priority

- **Static-Priority:** All jobs in task have same priority.
- example:
 - Rate-Monotonic:** “The shorter the period, the higher the priority.”
 - $T_1 = (5, 3, 5)$

 - $T_2 = (3, 1, 3)$

- **Dynamic-Priority:** May assign different priorities to individual jobs.
- example:
 - Earliest-Deadline-First:** “The nearer the absolute deadline, the higher the priority.”
 - 

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5

Processor Utilization

- recall that for a periodic task T_i , the ratio

$$u_i = e_i / p_i \rightarrow \text{utilization of task } T_i$$
- the **total utilization U** of all tasks in a system is the sum of the utilizations of all individual tasks:

$$U = \sum_{i=1}^n \frac{e_i}{p_i}$$

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6

Fixed-Priority Scheduling of Periodic Tasks

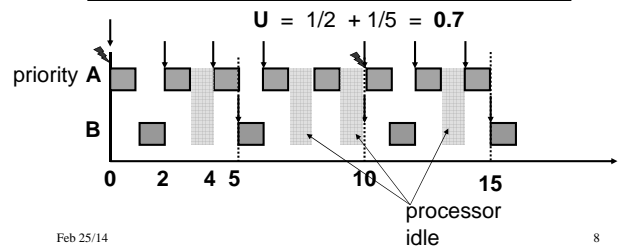
- consider some examples
- consider some methods that can be used to determine the schedulability of a task set:
 - Utilization-based test
 - Response-time (or time-based) test

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7

Example #1

Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (High Priority)	2	2	1
B (Low Priority)	5	5	1

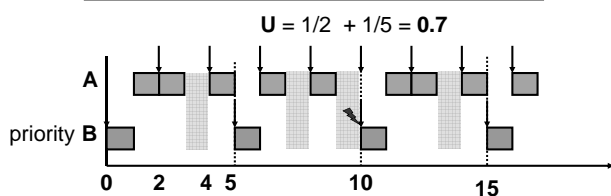


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8

Example #2

Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (Low Priority)	2	2	1
B (High Priority)	5	5	1

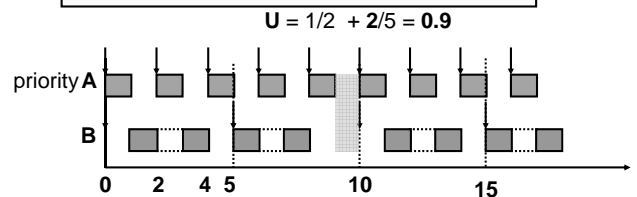


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9

Example #3

Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (High Priority)	2	2	1
B (Low Priority)	5	5	2

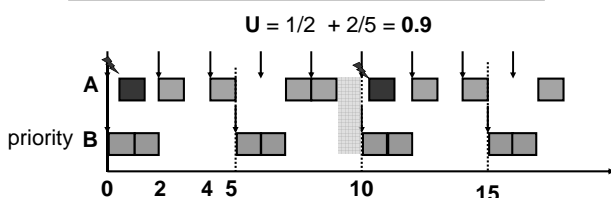


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10

Example #4

Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (Low Priority)	2	2	1
B (High Priority)	5	5	2

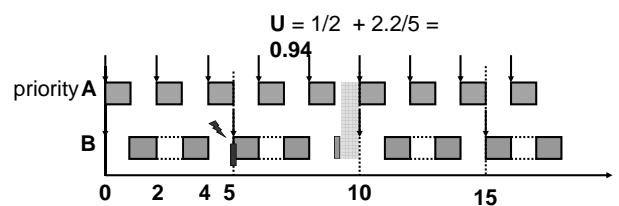


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11

Example #5

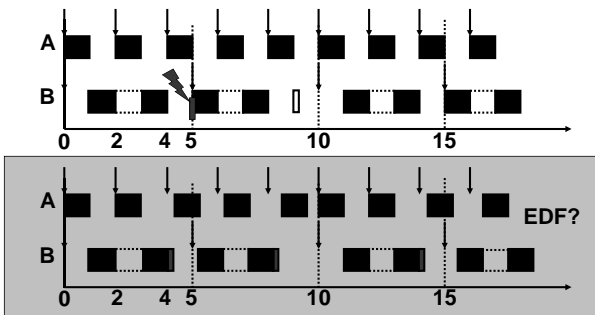
Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (High Priority)	2	2	1
B (Low Priority)	5	5	2.2



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12

Is There a Feasible Schedule for Example 5?



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13

Analysis of Examples

- Changing the static priorities assigned to each task can impact the task set's feasibility
 - e.g., examples 3 and 4.
- Even if the total task utilization is less than 1.0, the task set may not have a feasible (static) priority assignment
 - e.g., example 5

Is there an upper bound on processor utilization that ensures schedulability?

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14

Issues in Fixed Priority Assignment

- How to assign priorities?
- How to determine which assignment is the best; e.g., how to evaluate a priority assignment algorithm (method)?
- How to compare different priority assignment algorithms?

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15

Fixed Priority Assignment Methods

- According to **execution times** (e_i)
 - smallest/largest execution time first
- According to **periods** (p_i)
 - smallest/largest period first
- According to **task utilization** (e_i / p_i)
 - smallest/ largest task utilization first
- Other? **Deadlines (DMA)**, etc.

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16

Rate-Monotonic Algorithm (RM)

- **rate** (frequency) of task is inverse of its period
 $f_i = 1 / p_i$
- **higher rate (shorter period) = higher priority**

C. L. Liu and J. W. Layland, classic paper → posted!
read it!
 "Scheduling Algorithms for Multiprogramming in a Hard Real-Time Environment", JACM, Vol. 20, No. 1, pages 46-61, 1973.

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17

Deadline-Monotonic Algorithm (DM)

- tasks with **shorter relative deadlines** are assigned **higher priorities**.
- when relative deadlines (D_i) equal to their periods (p_i), the rate-monotonic algorithm is the same as the deadline-monotonic algorithm.

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18

Rate-Monotonic Assumptions

- tasks may be preempted
- tasks are periodic
- tasks execution times (e_i) are constant

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19

Optimal Priority Assignment

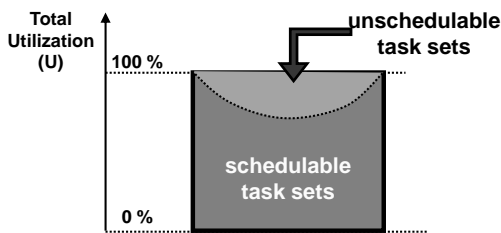
- a given priority assignment algorithm is **optimal** if whenever a task set can be scheduled by some fixed priority assignment, then it can also be scheduled by the given algorithm
- Liu and Layland show that:
 - rate-monotonic algorithm is optimal

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20

Maximum Achievable Utilization

A task set is **fully utilized** if any increase in run-time of any task would result in a missed deadline.

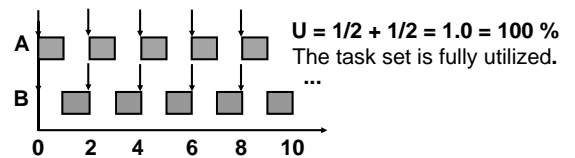


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21

Example #6

Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (High Priority)	2	2	1
B (Low Priority)	2	2	1

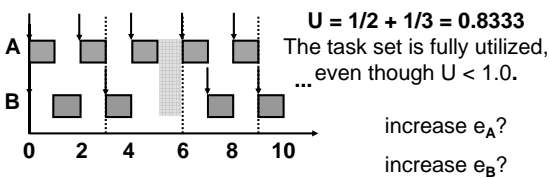


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22

Example #7

Task T_i	Period p_i	Deadline D_i	Run-Time e_i
A (High Priority)	2	2	1
B (Low Priority)	3	3	1

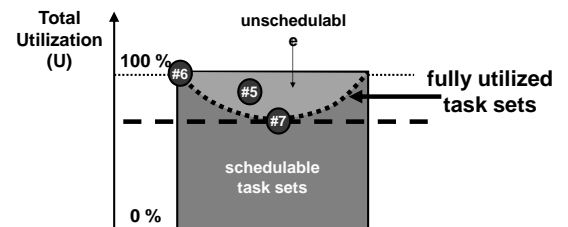


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23

Fully utilized task sets

different algorithms have different "fully utilized" curves



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24

Utilization-Based Test

- A **sufficient, but not necessary**, test for schedulability of a task set that is assigned priorities using the rate-monotonic algorithm.
- Compute total task utilization $U(n) = U$.

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25

Liu and Layland's Results

Theorem 2: If a feasible fixed priority assignment exists for some task set, then the rate-monotonic priority assignment is feasible for that task set.

Theorem 4: For a set of n tasks with fixed priority assignment, the least upper bound to the processor utilization factor is

$$U_{RM}(n) = n (2^{1/n} - 1)$$

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26

Values for $U_{RM}(n)$

- $U(1) = 1.0$
- $U(2) = 0.828$
- $U(3) = 0.779$
- $U(4) = 0.756$
- $U(\infty) = 0.69 \quad (\ln 2)$

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27

RM Utilization Test

Utilization vs worst-case utilization bound

- also called **schedulable utilization**

$$U_{RM}(n) \leftrightarrow U$$

- If $U > 1$, then the task set **is not** schedulable
- If $U \leq U_{RM}(n)$, then the task set **is** schedulable
- Otherwise: $U_{RM}(n) < U \leq 1$
 - **no conclusion** can be made
 - try more detailed analysis

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28

Response Time Tests

- for use when $U_{RM}(n) < U \leq 1$
- analyze tasks to determine the worst case response time for jobs
- if worst case response of a job exceeds its deadline, then no feasible schedule
- for independent tasks, only delays are due to preemption by higher priority tasks

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29

Worst-Case Simulation

- assume a critical instant for all tasks
- construct schedule according to the scheduling algorithm
- only need to consider largest task period
- if all tasks meet their deadlines
 - then tasks are feasibly schedulable

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30

Time-Demand Analysis

- tasks place incremental demands on processor time
 - let $\omega_i(t)$ be demand from task i and all higher priority tasks
- processor delivers (processing) linearly
- check each task i , to be feasible:
 - $\omega_i(t) = t$ for some $t \leq p_i$
- how is this different from worst-case simulation?

schedule vs.
calculation ! 31

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Example #8

T_1	$e_1 = 50$	$p_1 = 75$	$u_1 = 0.666$
T_2	$e_2 = 25$	$p_2 = 150$	$u_2 = 0.167$
T_3	$e_3 = 25$	$p_3 = 300$	$u_3 = 0.083$

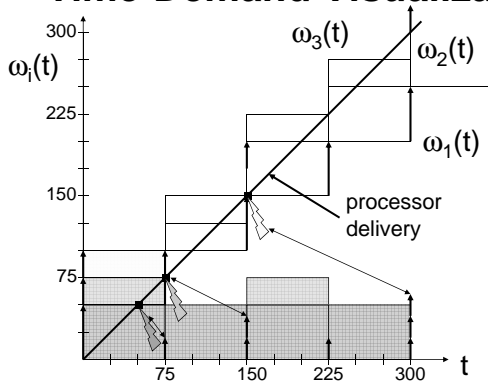
$$U = \sum u_i = 0.916 > 0.779 \leftarrow U(3)$$

\therefore does not meet utilization bound!

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32

Time-Demand Visualization



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33

How to Solve ?

For each task:

- consider demand at each scheduling point
 - before next demand
- if task's demand \leq delivery before deadline,
 - then feasible !

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34

Example 9

T_1	$C_1 = 30$	$p_1 = 70$	$u_1 = 0.429$
T_2	$C_2 = 60$	$p_2 = 200$	$u_2 = 0.3$
T_3	$C_3 = 78$	$p_3 = 375$	$u_3 = 0.208$

$$U = \sum u_i = 0.937 > 0.779 \quad (U(3))$$

\therefore does not meet utilization bound! ☹

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35

Consider Each Task

- Task 1: highest priority \rightarrow meets deadline
 - $30 \text{ (execution}_1) \leq 70 \text{ (period}_1)$
- Will need to know Scheduling Points:
 - periods: 70, 200, 375
 - scheduling points: (when new demand is released)
 - 0, 70, 140, 200, 210, 280, 350, 375
 - all released

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36

Continue (Task 2)

- Task 2: can only be delayed by Task 1
 - first scheduling point: $t = 70$ (T_1)
 - demand = $30 + 60 = 90$ ☹️
 - second scheduling point: $t = 140$ (T_1)
 - demand = $2 \cdot 30 + 60 = 120$ ☺️
- ↖ before next release! i.e. before T_1 scheduled

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37

Continue (Task 3)

Now for Task 3:

- first scheduling point: $t = 70$ (T_1)
 - demand = $30 + 60 + 78 = 168$ ☹️
- second scheduling point: $t = 140$ (T_1)
 - demand = $2 \cdot 30 + 60 + 78 = 198$ ☹️
- third scheduling point: $t = 200$ (T_2)
 - demand = $3 \cdot 30 + 60 + 78 = 228$ ☹️

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38

Continue (Task 3 con't)

- fourth scheduling point: $t = 210$ (T_1)
 - demand = $3 \cdot 30 + 2 \cdot 60 + 78 = 288$ ☹️
- fifth scheduling point: $t = 280$ (T_1)
 - demand = $4 \cdot 30 + 2 \cdot 60 + 78 = 318$ ☹️
- sixth scheduling point: $t = 350$ (T_1)
 - demand = $5 \cdot 30 + 2 \cdot 60 + 78 = 348$ ☺️
- whew! all tasks feasible

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39

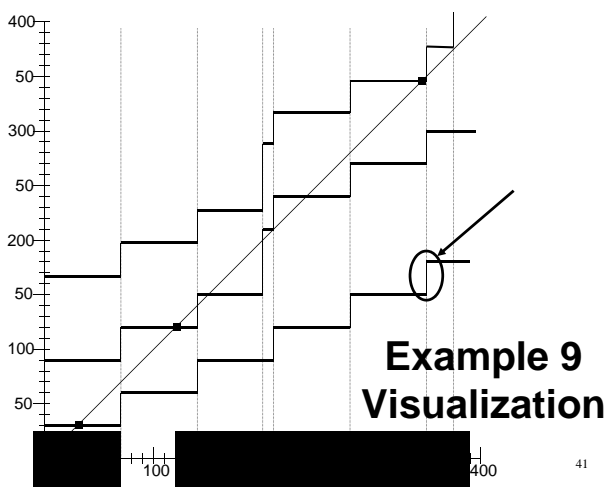
Easier way?

- why not just check demand at end of p_3 ?
 - if T_3 meets deadline, then should have slack then?
- scheduling point: $t = 375$ (T_3)
 - demand = $6 \cdot 30 + 2 \cdot 60 + 78 = 378$ ☹️

HUH?

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40



41

Alternative ?

- let I_i be the delay in task i 's response time due to higher priority tasks
- response time $R_i = e_i + I_i$ (Equ. 1)
- worst case response time: task i and all higher priority tasks release a job at the same instant
 - $I_i =$ sum of all higher priority jobs execution times

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42

of Jobs Over an Interval

- suppose: periodic task j:
- number of jobs in $[0, R) = \left\lceil \frac{R}{p_j} \right\rceil$ ← “ceiling” function: integer round-up

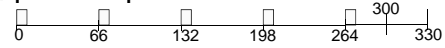
- delay to lower priority tasks due to these jobs is: $\left\lceil \frac{R}{p_j} \right\rceil e_j$

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43

Consider Task with period p_i Over Time Interval P : $p_i < P$

- $p_i = 66, e_i = 10, P = 300$



- work associated with task is “requested” at the beginning of each period
- there are $\lceil P/p_i \rceil$ (max.) requests in interval e.g. $300 / 66 = 4.54$, rounds up to 5
- to meet deadline P , must perform work $\lceil P/p_i \rceil$ times during P

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44

of Higher Priority Jobs Over an Interval

- suppose: i periodic tasks, all with phase 0
- rate monotonic priority assignment
- total delay to task i due to higher priority tasks is:

$$I_i = \sum_{j=0}^{i-1} \left\lceil \frac{R_i}{p_j} \right\rceil e_j \quad (\text{Equ. 2})$$

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45

Response Time Equ.

- Substitute Equ 2 into Equ 1:

$$R_i = e_i + \sum_{j=0}^{i-1} \left\lceil \frac{R_i}{p_j} \right\rceil e_j \quad (\text{Equ. 3})$$

- can solve using a recurrence relation:
 - initially, estimate $R_i^0 = e_i$ (no delay)
 - use estimate to calculate better estimate, recurse
 - stop when solution found

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46

Recurrence Relation

$$R_i^0 = e_i$$

$$R_i^{n+1} = e_i + \sum_{j=0}^{i-1} \left\lceil \frac{R_i^n}{p_j} \right\rceil e_j$$

stop when $R_i^{n+1} = R_i^n$

if $R_i^n \leq D_i$ then task i meets deadline!

substitute R_i^0
solve for R_i^1

substitute R_i^n
solve for R_i^{n+1}

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47

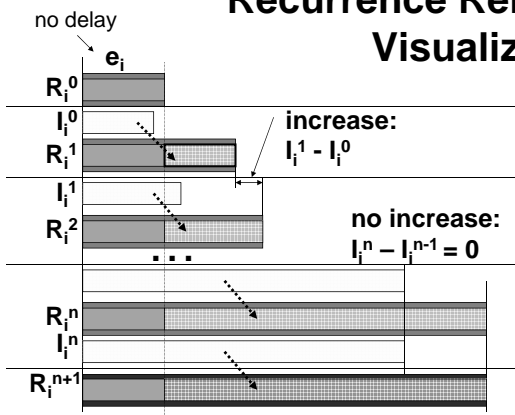
Recurrence Relation: Conceptually

- initial estimate = execution time of task i
 - during this time, there will be delay from higher priority tasks
 - how much?
 - add this delay to estimate
 - results in “larger” time estimate
- stop when estimate does not increase

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48

Recurrence Relation Visualization



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49

Scheduling Visualization

- what does each estimate mean in terms of delay vs. the amount of task i execution ?
- what does each increase between estimates represent (in these terms) ?
- when the recursion stops, what does the absence of increase represent (in these terms) ?
- convince yourself that you understand this ☺

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50

Response Time Analysis

- For each task, T_i , compute worst-case response time (R_i).
- If ($R_i \leq D_i$) for each task T_i , then the task set is feasible (schedulable).
- Response Time Analysis is both **necessary** and **sufficient**.
- How does this relate to Time-Demand Analysis?

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51

Recall Example #8

$$T_1 : e_1 = 50 \quad p_1 = 75 \quad u_1 = 0.666$$

$$T_2 : e_2 = 25 \quad p_2 = 150 \quad u_2 = 0.167$$

$$T_3 : e_3 = 25 \quad p_3 = 300 \quad u_3 = 0.083$$

$$U = \sum u_i = 0.916 > 0.779 \leftarrow U(3)$$

\therefore does not meet utilization bound!

let's work the recursive response time analysis on the board !

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52

What about Assumptions?

1. deadline = period
→ now!
2. strictly periodic tasks (Liu Ch. 7)
→ next (Aperiodic)
2. tasks are independent (Liu Ch. 8)
→ next next (Access Control)

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53

Arbitrary Response Times

- $D_i \neq p_i$
- if $D_i < p_i$ → tighter deadline
- if $D_i > p_i$ → may have more than one released & ready job for task i
– in these jobs assume FIFO scheduling of task i
- will use concept of level- π_i busy interval

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54

Level- π_i Busy Interval ($t_0, t]$

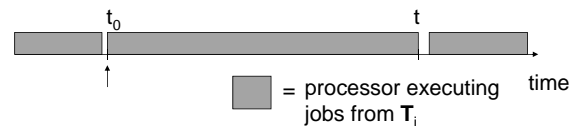
- task subset T_i – all tasks with priority π_i or higher
- starts at t_0 , when:
 - all jobs in T_i released before t_0 have completed
 - a job in T_i is released
- ends at t :
 - first instant after t_0 when all jobs in T_i released since t_0 have completed

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55

Conceptually

- no pending work from T_i when interval starts
- during interval, no slack time & processor always executing jobs with priority π_i or higher
- no pending work from T_i when interval ends



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56

Critical Instant?

- Worst case load when all tasks in T_i release a job at t_0
 - then critical instant!

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57

Task i Schedulability Test

Assume:

- critical instant for T_i at t_0
 - T_i contains all tasks with priority π_i or higher
 - all tasks in T_i other than task i meet deadlines
1. If first job of each task (including T_i) completes before end of its **period**, and $J_{i,1}$ meets deadline → schedulable!
 - if $J_{i,1}$ misses deadline → not schedulable

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58

T_i Schedulability Test (con't)

2. If first job of some task does not complete before end of its period:
 - a) compute length of level- π_i busy interval
 - solve recurrence relation:

$$R_i^{n+1} = \sum_{j=0}^i \left\lceil \frac{R_i^n}{p_j} \right\rceil e_j$$

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59

T_i Schedulability Test (step 2 con't)

- b) compute response time for each task i job in level- π_i busy interval – for response time of j^{th} job, solve:

$$R_i^{n+1} = j e_i + \sum_{k=0}^{i-1} \left\lceil \frac{R_i^n}{p_k} \right\rceil e_k$$

- if all task i jobs meet deadlines → schedulable

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60

Is Test Finite?

- YES! $U \leq 1$ (has to be!) **AND** no slack time in level- π_i busy interval (by definition of interval)
 - level- π_i busy interval is finite
 - can find length of interval
 - can find job response times