

SYSC 5701

Operating System Methods for Real-Time Applications

Access Control: PCP
Winter 2014

Resource-Sharing Dependencies

- A job cannot proceed (is blocked) because of resource-sharing synchronization
- Resource-sharing requires mutually exclusive access to the resource
- Can cause priority inversions

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Resources

- serially reusable “units” of resource
 - eg. binary semaphore has one unit
 - counting semaphore has *count* units
- grant mutually exclusive right to access a unit
- once a unit is granted to a job, must not be reused by other jobs until released
- Recall management of mutual exclusion “unit” in monitors!

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Access to Resources

- job requests resource(s)
 - job “locks” the resource(s)
- lock is managed by o/s (kernel)
- if resource(s) not available job is blocked
- eventually, job is granted the resource(s) and is unblocked
- when finished with resource(s)
 - job “unlocks” resource(s) for reuse

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Access (more)

related material from earlier in course:

- semaphores, IPC
 - monitors
 - critical sections
 - mutual exclusion
- constructs to enable programs to control locking and unlocking of resources
- parts of programs that require locking
- the desired effect

Result: task can have interdependencies when accessing resources

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Access Control Protocol

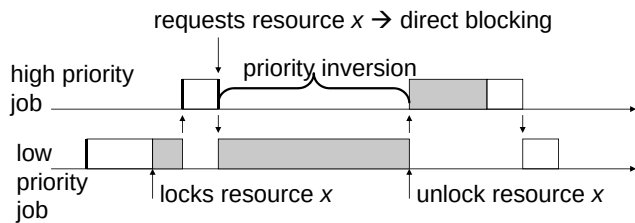
- resource conflict:
 - two jobs require same resource type
 - jobs must contend for the resource
- access control protocol: set of rules for
 1. granting resources
 2. scheduling jobs requesting resources

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Priority Inversion

- a higher priority job is prevented from executing by a lower priority job
 - the priority relationship is inverted!

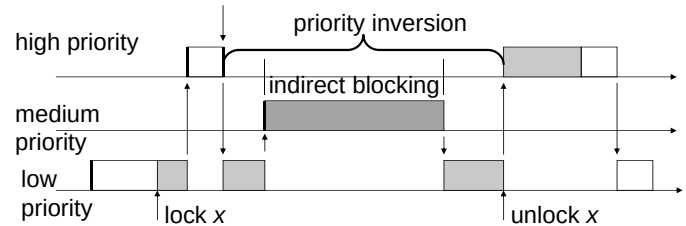


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Unbounded Priority Inversion

- duration of priority inversion is not a function of the time for low priority job to execute the relevant critical section



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Worst Case Job Response Time

- **preemption time:** delay due to higher priority job
- **execution time:** time to do job's work
- **blocking time:** time spent blocked
 - hopefully, blocking time is a simple function of delays while lower-priority jobs execute critical sections
 - if not, then difficult to compute (unbounded)

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Avoiding Unbounded Priority Inversion

1. disable preemption
2. priority inheritance protocol
3. priority ceiling protocol

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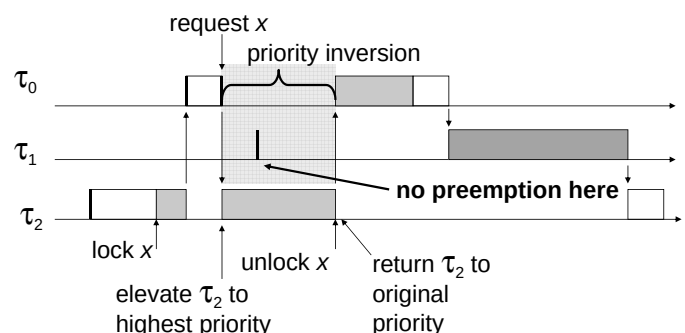
Disable All Preemption

- disable preemption during critical sections
- effectively elevate job in critical section to highest priority (cannot be preempted)
- priority elevation only needed when higher-priority jobs are requesting the relevant critical section – in other cases, the lower priority job should be preemptable by higher-priority jobs
- OK if critical sections are very short relative to shortest deadlines

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Disable Preemption for Unbounded PI Example



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Variation on Disable Preemption: Priority Ceiling Emulation

Priority Ceiling:

- the priority ceiling of resource R_i is the highest priority of all jobs that require access to R_i at any time during their operation
- denote $\Pi(R_i)$
- Q: do any jobs with priority higher than $\Pi(R_i)$ access R_i ?

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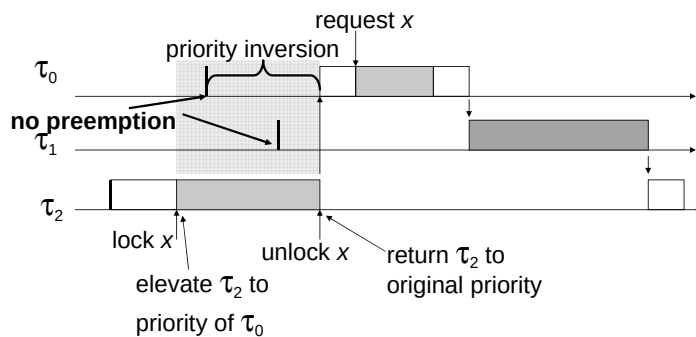
Priority Ceiling Emulation

- in critical section, job runs at priority = priority ceiling for the resource
 - i.e. no job that might request access to the resource is able to run!
- job in critical section disables all jobs that might access critical section
- at end of critical section, job returns to original priority
- jobs at priority higher than the ceiling are still eligible to run

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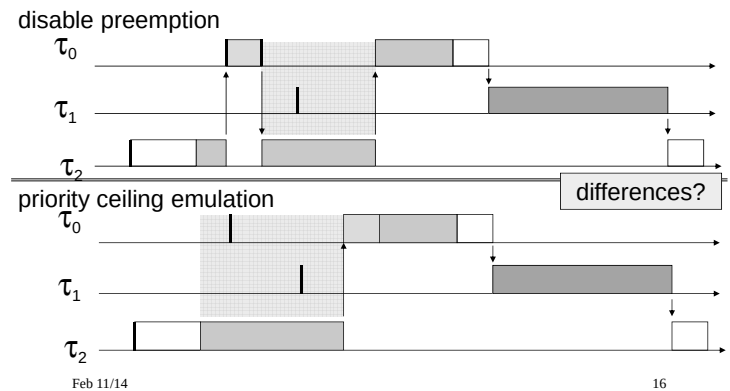
Priority Ceiling Emulation for Unbounded PI Example



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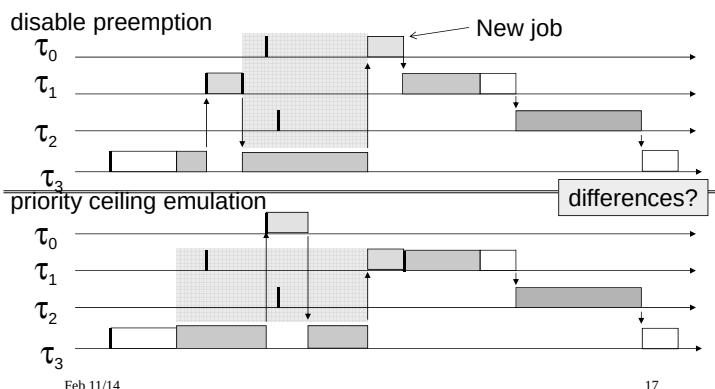
Priority Ceiling Emulation vs. Disable Preemption Example 1



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Priority Ceiling Emulation vs. Disable Preemption Example 2



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Basic Priority Inheritance Protocol

- while a job_{low} is holding any resource: raise its priority to the highest priority of any job requesting any resource held by job_{low}
- dynamic $\rightarrow$ raise at time higher priority job requests the resource
- when unlock a resource: assign job_{low} the higher of (1) its original priority, or (2) the highest priority of a job requesting a resource held by job_{low}

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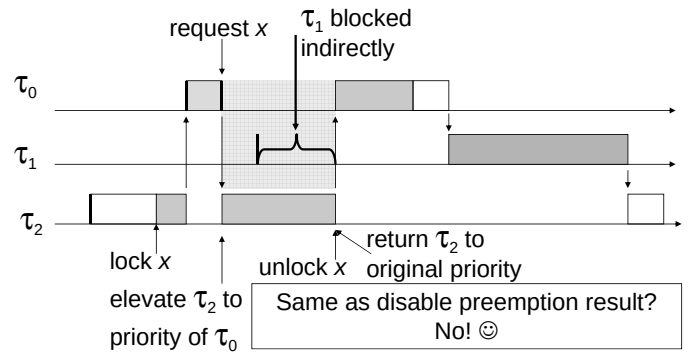
Lowering Priority Scenario

- Suppose job_{low} holds resource 1 and it is then requested by job with priority τ_2
 - raise job_{low} to priority τ_2
- Now job_{low} acquires resource 2 and it is then requested by job with priority τ_1
 - raise job_{low} to priority τ_1
- Now job_{low} releases resource 1
 - what should be priority of job_{low} now?
 - How does this fit with the rule on previous slide?

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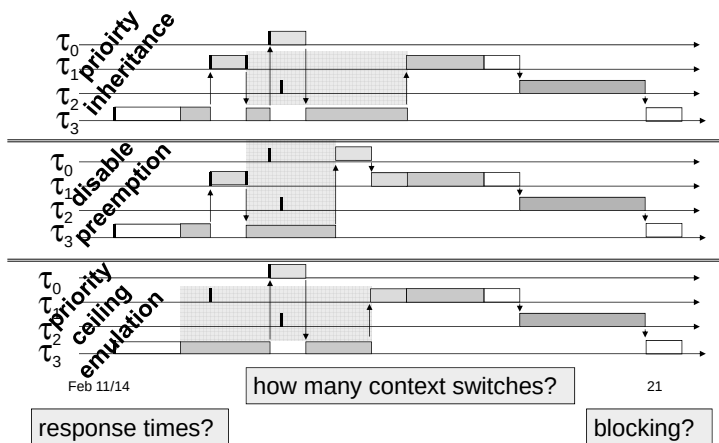
Basic Priority Inheritance for Unbounded PI Example



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What about All Three?



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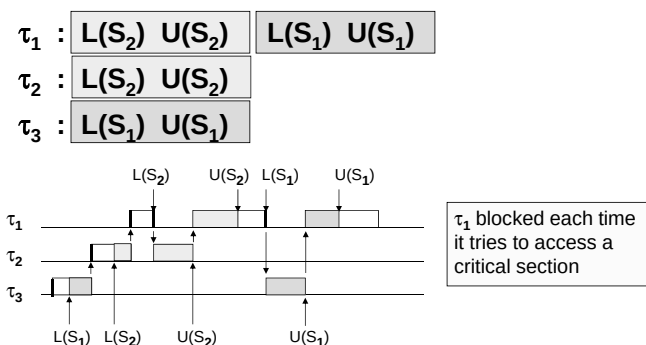
Is Blocking a Function of Time to Execute Critical Sections?

- suppose m critical sections accessed by task τ
- job of τ can be blocked directly, at most, m times
 - not counting indirect blocking!
- if n tasks at lower priority than τ
 - job of τ can be blocked, at most, at one critical section in each of the n tasks
 - blocking time is bounded, ☺ but ... may suffer from “chain blocking” – blocks each time attempt to access a critical section

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Chain Blocking Example

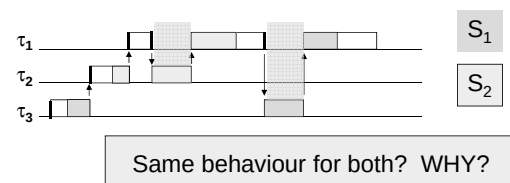


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Chain Blocking for Disable Preemption & Priority Inheritance?

- still a problem!
- previous example:



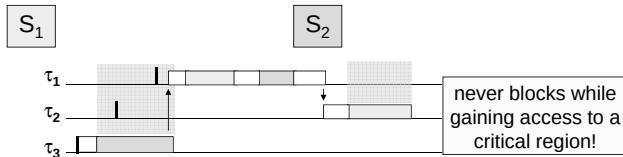
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Chain Blocking for Priority Ceiling Emulation?

- never blocks on request!
- resource always available (GOOD!) ... WHY?
- for previous example:

$$\Pi(S_1) = \pi(\tau_1) \quad \Pi(S_2) = \pi(\tau_1)$$



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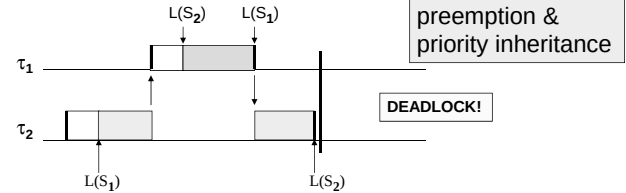
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Potential Deadlock

- loop of tasks blocked waiting for each other

$\tau_1 : L(S_2) \ L(S_1) \ U(S_1) \ U(S_2)$

$\tau_2 : L(S_1) \ L(S_2) \ U(S_2) \ U(S_1)$

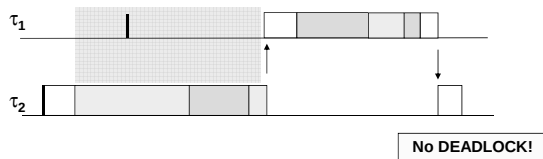


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Deadlock for Priority Ceiling Emulation?

- no!
- resource always available WHY?



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Performance vs. Penalty

- priority ceiling emulation looks “best” in terms of performance
 - penalty? → may delay higher priority jobs even though no conflict would occur → unnecessary priority inversion!
- disable preemption & priority inheritance
 - only elevate priority when a conflict occurs → avoids unnecessary priority inversion

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Basic Priority Ceiling Protocol

- combine priority ceiling emulation with priority inheritance protocol
 - ✓ priority ceiling
 - ✓ inheritance only when conflict
- current priority ceiling: $\hat{\Pi}(t)$
 - highest priority ceiling of all resources currently in use

meaning of “conflict” is key!

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Basic Priority Ceiling Protocol Rules

Scheduling Rule:

- job released at assigned priority
- preemptive and priority driven at job’s current priority

Allocation Rule: when J requests R at time t

- if R already locked – request denied and J blocked

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Allocation Rule (con't)

if R is free:

- if priority of J at t $> \hat{\Pi}(t)$, allocate R to J
 - J does not access any of the held resources!
- else: if J is the job holding the resource(s) whose priority ceiling = $\Pi(t)$, allocate R to J
 - Not possible for different jobs to hold resources with same priority ceiling! (see i. and iii.)
- otherwise: request denied and J is blocked

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Allocation Rule (paraphrasing)

- a job cannot acquire a resource unless its priority is higher than the ceilings of all other resources currently acquired by other jobs
- if priority higher than ceilings, then job will not request access to any of the other active resources (by the definition of a ceiling!)
- when request denied and job is blocked, higher priority jobs might still be able to acquire resource! (deny access $\neq$ FIFO blocking)

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Priority-Inheritance Rule

- while a job J_{low} is holding any resource: raise its priority to the highest priority of any job requesting any resource held by J_{low}
- dynamic: at time t when a job J becomes blocked, the job J_{low} which blocks J inherits the current priority of J
- J_{low} executes at inherited priority until t' when it releases every resource whose priority ceiling is greater or equal to the inherited priority
- at t': priority of J_{low} falls to the higher of (1) its original priority, or (2) the priority of the highest job requesting one of the resources still held by J_{low}

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Lowering Priority Scenario

- Suppose job J_{low} holds resource 1 with priority ceiling π_3 which is then requested by job with priority π_4 (rules?)
 - raise J_{low} to priority π_4
- Now J_{low} acquires resource 2 with priority ceiling π_1 which is then requested by job with priority π_2 (rules?)
 - raise J_{low} to priority π_2
- Now J_{low} releases resource 1
 - what should be priority of J_{low} now? (rules?)
- Now J_{low} releases resource 2
 - what should be priority of J_{low} now? (rules?)
- What if resources released in other order? (rules?)

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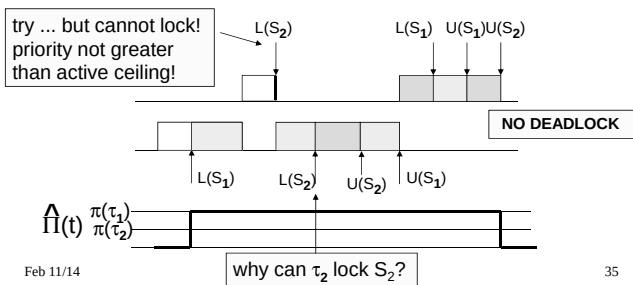
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Recall Previous Deadlock Example

$\tau_1 : L(S_2) L(S_1) U(S_1) U(S_2)$

$\tau_2 : L(S_1) L(S_2) U(S_2) U(S_1)$

$\Pi(S_1) = \pi(\tau_1) \quad \Pi(S_2) = \pi(\tau_1)$



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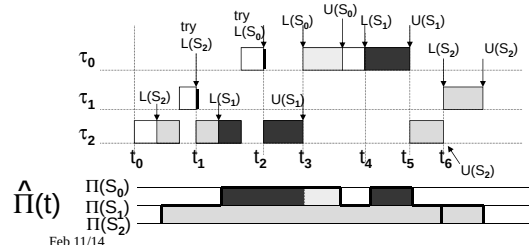
Another Example

$\tau_0 : L(S_0) U(S_0) L(S_1) U(S_1)$

$\tau_1 : L(S_2) U(S_2)$

$\tau_2 : L(S_2) L(S_1) U(S_1) U(S_2)$

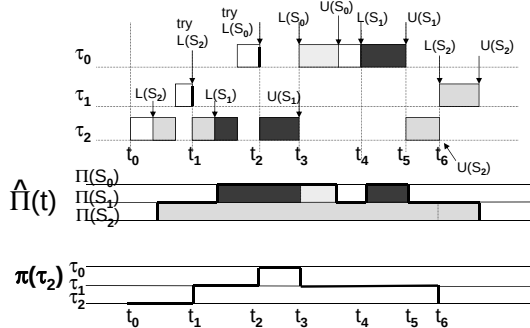
$\Pi(S_0) = \pi(\tau_0) \quad \Pi(S_1) = \pi(\tau_0) \quad \Pi(S_2) = \pi(\tau_1)$



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Priority Inheritance in Example



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Behaviour

- t_0 : $\pi(\tau_2) = \tau_2$
- t_1 : $\Pi(S_2) = \pi(\tau_1) \therefore$ block, bump τ_2 to $\pi(\tau_1)$
- t_2 : $\Pi(S_1) = \pi(\tau_0) \therefore$ block, bump τ_2 to $\pi(\tau_0)$
- t_3 : $\pi(\tau_2)$ returns to $\pi(\tau_1)$, τ_0 resumes
- t_4 : S_1 free, only other active resource is S_2
 $\Pi(S_2) = \pi(\tau_1) \rightarrow \Pi(t_4)$ and $\pi(\tau_0) > \Pi(t_4)$
 $\therefore$ allocate S_1 to τ_0
- t_5 τ_2 resumes
- t_6 : $\pi(\tau_2)$ returns to $\pi(\tau_2)$, τ_1 resumes

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Points Seen in Example

- a job is blocked by a (possibly nested) critical section of at most one lower priority job
- ceiling blocking occurs – a job is prevented from entering a critical section by ceiling of an active resource $\rightarrow$ not because the requested resource was busy !
 - e.g. t_2 : τ_0 is blocked even though S_0 is free

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Properties of Basic Priority Ceiling Protocol

- no deadlock !
- job blocks in at most one critical section
 - blocking is bounded
 - no chain blocking $\rightarrow$ shorter blocking bound than Priority Inheritance Protocol
- once acquire first resource, all resources needed will be available when requested

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Implementation of Basic Priority Ceiling Protocol

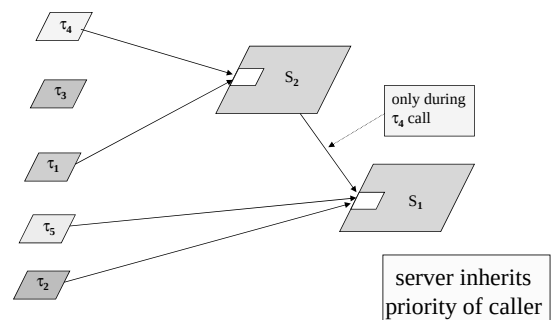
- don't need "lock" queues (e.g. semaphore queue)
- maintain queue of tasks that are ready-to-run or blocked – maintain in priority order
- task at head is current task
- need list of active resources – ordered by ceiling priority (includes task that locked the resource, and highest priority of any task blocked waiting for the resource)
- *lock* and *unlock* manipulate queue and list
- need analysis of critical section use – establish priority ceilings prior to run-time

Why is a single queue sufficient?

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Example Using Client / Server (similar to Liu text)



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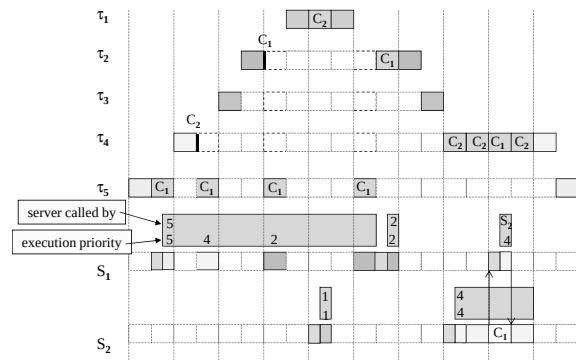
Ceilings in Example

- $\text{Ceiling}(S_1) = \max \{ \tau_2, \tau_4, \tau_5 \}$
(τ_4 indirect)
= $\text{Priority}(\tau_2)$
- $\text{Ceiling}(S_2) = \max \{ \tau_1, \tau_4 \}$
= $\text{Priority}(\tau_1)$
- τ_3 does not access servers

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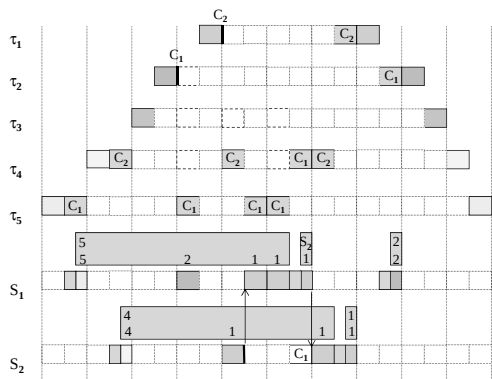
Basic Priority Ceiling Protocol Behaviour



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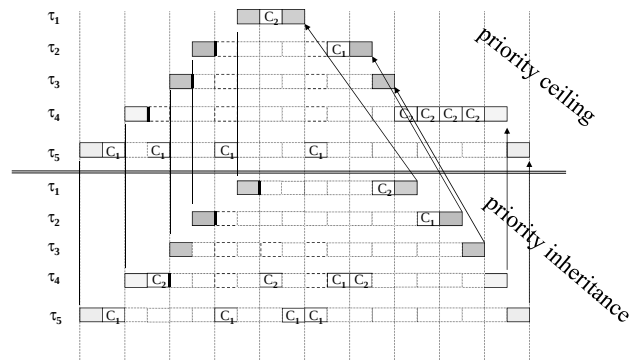
Basic Priority Inheritance Same Example



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Response Comparison



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