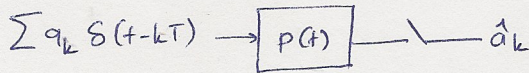
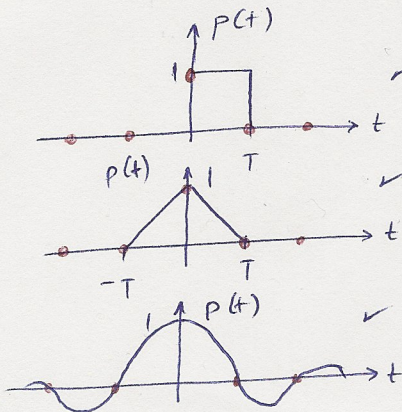
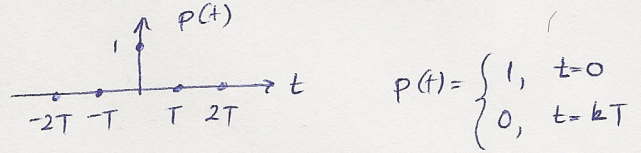


Omit noise $p(t) = h_T(t) * h_c(t) * h_r(t)$



no ISI condition in time domain



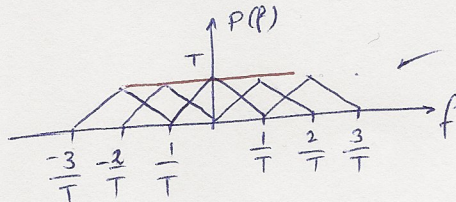
Find the no ISI cond in freq domain

$$p(t) \sum_{k=-\infty}^{\infty} \delta(t-kT) = s(t)$$

$$P(f) * \frac{1}{T} \sum \delta(f - \frac{k}{T}) = 1$$

$$\sum P(f - \frac{k}{T}) = T$$

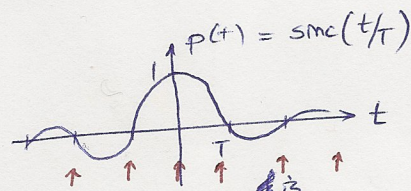
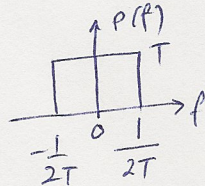
consider a $\text{sinc}^2(\frac{t}{T}) \rightarrow$ triangular(f)



infinitely many solutions.

Find the minimum BW solution.

By inspection



spectral efficiency: in order to transmit at rate $R (= \frac{1}{T})$, Bandwidth needed? $\frac{R}{2}$
how much

Baseband: $\eta_{max} = 2 \text{ sym/sec/Hz}$

Bandpass: $\eta_{max} = 1 \text{ sym/sec/Hz}$

— Sep 30

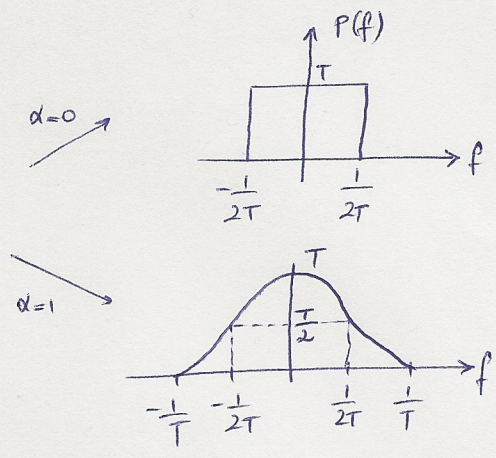
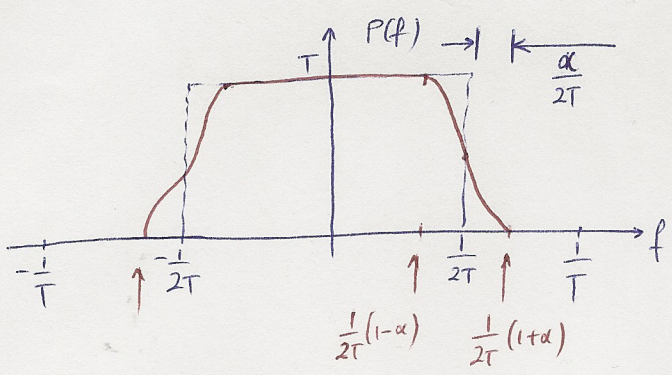
(synchronization)

Time-domain sinc pulses cause practical problems. For instance, not robust wrt timing errors.

Raised cosine pulses

$$p(t) = \text{sinc}\left(\frac{t}{T}\right) \left(\frac{\cos\left(\frac{\pi \alpha t}{T}\right)}{1 - \frac{4\alpha^2 t^2}{T^2}} \right)$$

$$P(f) = \begin{cases} T, & 0 \leq |f| < \frac{1}{2T} \\ \frac{T}{2} \left\{ 1 - \sin\left(\frac{\pi(|f| - \frac{1}{2T})}{\frac{1}{T} - 2f}\right) \right\}, & \frac{1}{2T} \leq |f| < \frac{1}{T} \\ 0, & |f| \geq \frac{1}{T} \end{cases}$$



100%: excess BW

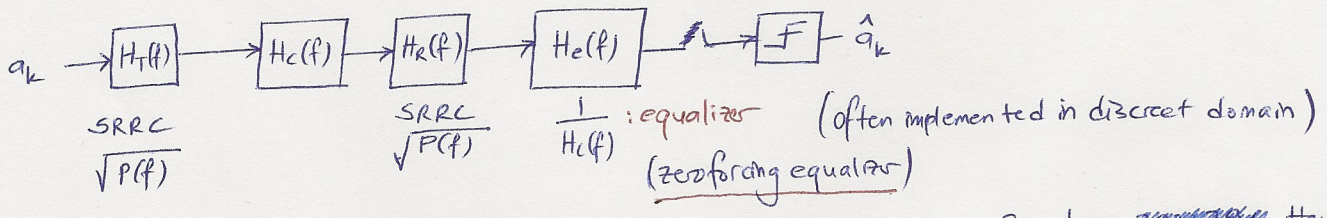
Spectral Efficiency: $\frac{1}{1+\alpha}$ sym/sec/Hz - Bandpass
 $\frac{2}{1+\alpha}$ sym/sec/Hz - Baseband

Note that we have been operating on $P(f) = H_T(f) H_C(f) H_R(f)$

Consider $H_C(f) = \delta(f)$

$H_R(f)$ and $H_T(f)$ must be matched filters to have the best error performance.

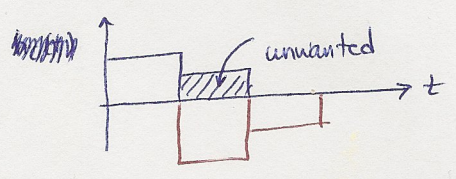
$|H_T(f)| = |H_R(f)| = \sqrt{P(f)}$ square-root raised-cosine filters (SRRC)



Read pp ~~218-220~~, Haykin
 Eye Patterns

Equalization (pp ~~218-220~~, Haykin)

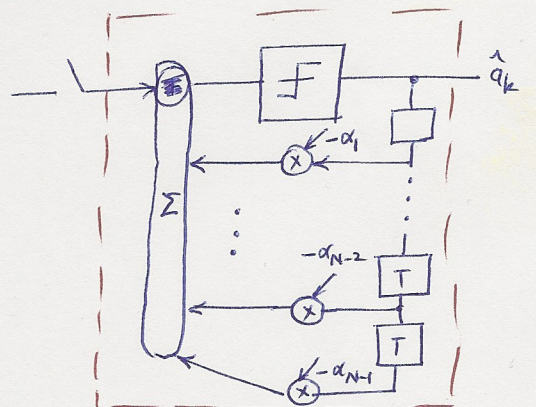
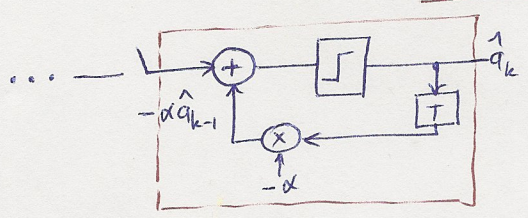
Consider $h_c(t) = \delta(t) + \alpha(t-T)$



received signal in the absence of noise

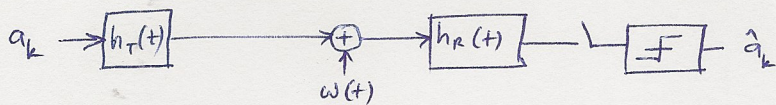
Decision Feedback Equalizer

$h_c(t) = \sum_{i=0}^{N-1} \alpha_i \delta(t-iT)$ assume wlog $\alpha_0 = 1$



Case I) no channel (ideal channel) but noise

ideal channel: $h_c(t) = \alpha \delta(t-t_0)$
 attenuation ←
 propagation delay ←



Optimal receiver: MF + threshold detector

$$h_R(t) = h_T(T-t)$$

$$|H_R(f)| = |H_T(f)|$$

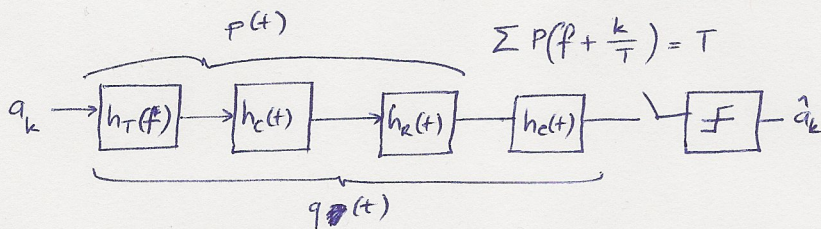
$$BER = P_e = \frac{1}{2} \text{erfc} \left[\sqrt{\frac{E_b}{N_0}} \right]$$

BER may be made arbitrarily small, but $P_e \neq 0$

Case II) no noise but channel

→ derive no-ISI ^{criteria} ~~criteria~~ for $P(f) = H_T(f)H_c(f)H_R(f)$

$$p(t) = \begin{cases} 1, & t=0 \\ 0, & t=kT \end{cases}$$



But $h_c(t)$ may be time varying → make $q(t)$ no-ISI by introducing ^{equalizer} $h_e(t)$.

One realization

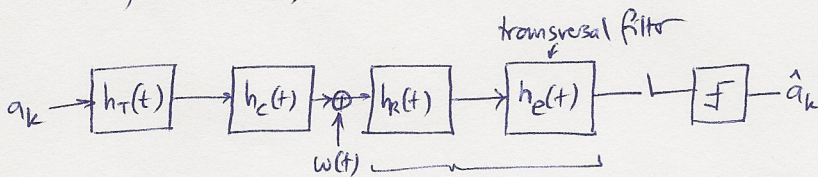
$h_T(t), h_R(t)$: MF pair

$$|H_T(f)| = |H_R(f)| = \sqrt{P(f)} \quad \text{SRRC filters}$$

$$|H_e(f)| = \frac{1}{|H_c(f)|} \quad \dots \text{channel inversion (zero-forcing)}$$

BER = 0

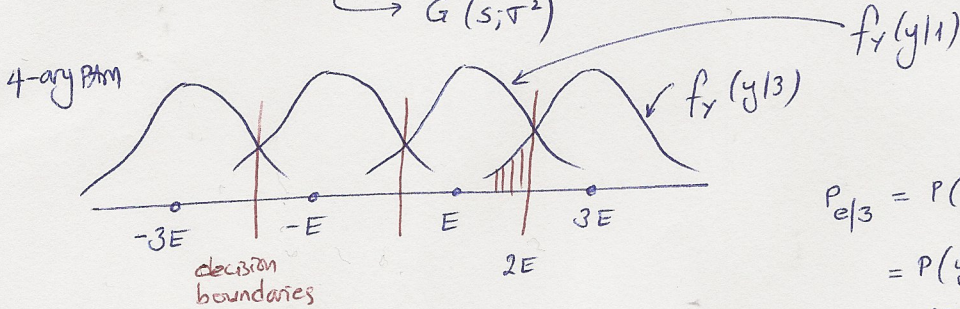
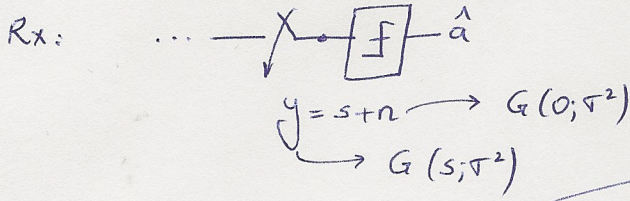
Case III) channel, noise



optimum linear receiver (p. 282-287, Haykin)
 effective against both noise and ISI
 minimizes mean-square error → MMSE receiver

Tail of a Gaussian PDF

$$P_e = P(\hat{a} \neq a) = \sum_i P_{e|i} P_i$$



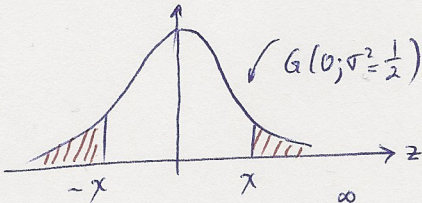
$$P_{e|3} = P(\hat{a} \neq 3 | a=3)$$

$$= P(y < 2E | a=3)$$

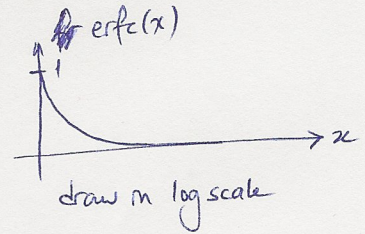
$$= \int_{-\infty}^{2E} f_Y(y|3) dy = \int_{-\infty}^{2E} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y-3E)^2}{2\sigma^2}} dy$$

$$= \int_{-\infty}^{-E} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{y^2}{2\sigma^2}} dy = \int_E^{\infty} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{y^2}{2\sigma^2}} dy$$

Gaussian tail dies out very quickly $\rightarrow P_e$: low



$$\text{Shaded Area} = 2 \times \frac{1}{\sqrt{2\pi} \frac{1}{\sqrt{2}}} \int_x^{\infty} e^{-\frac{z^2}{2 \cdot \frac{1}{2}}} dz = \frac{2}{\sqrt{\pi}} \int_x^{\infty} e^{-z^2} dz \triangleq \text{erfc}(x)$$



Binary Antipodal PAM: $P_e = \frac{1}{2} \text{erfc} \sqrt{\frac{E}{N_0}}$

