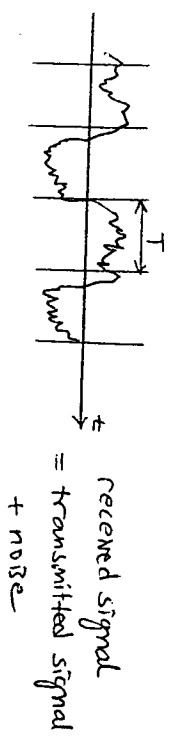
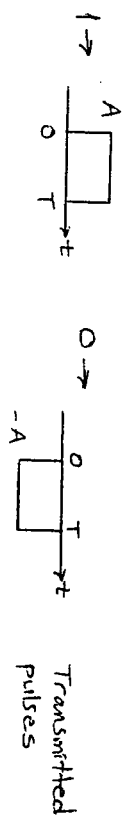
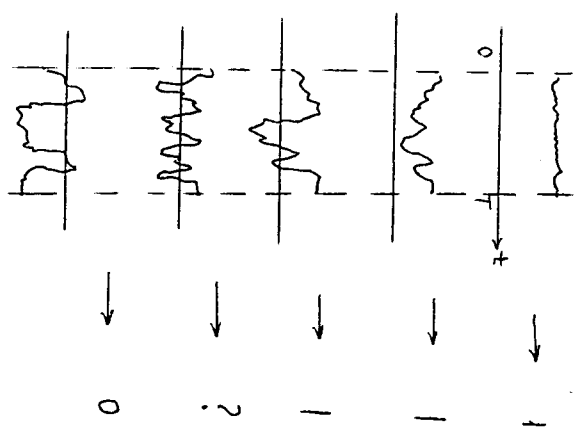


Ch. 7 BASEBAND PULSE TRANSMISSION

Some Insight to Detection Theory

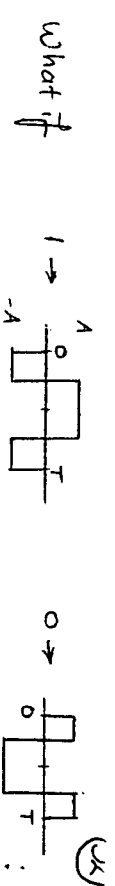


How do you decide whether a '1' or a '0' is transmitted?



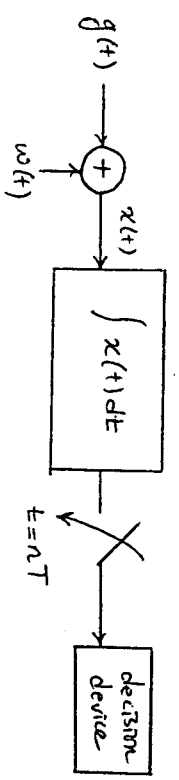
Intuitive detection rule: Integrate the received waveform over a period of bit duration (T)

$$\int_0^T \dots$$

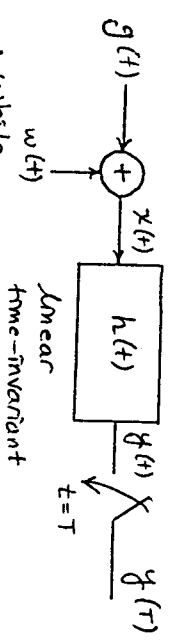


Received signal: $x(t)$. But if integrate $\rightarrow \int_0^T x(t) dt \approx 0$

∴ Integrator detector is not a general structure



Matched Filter Detector



- white
- stationary
- zero mean
- PSD: $N_0/2$

Maximize the signal-to-noise ratio (SNR) at the output

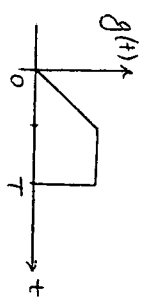
$$\begin{aligned} x(t) &= g(t) + w(t) \\ y(t) &= x(t) * h(t) = (g(t) + w(t)) * h(t) \\ &= g(t) * h(t) + w(t) * h(t) \\ &= g_c(t) + n(t) \end{aligned}$$

$$SNR |_{\text{output}} = \frac{\text{instantaneous signal power}}{\text{average power of noise}} \quad \leftarrow \text{measured at } t=T$$

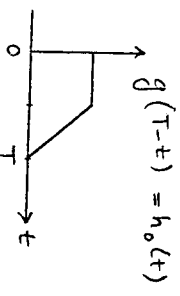
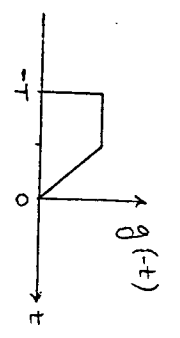
$$\eta = \frac{|\beta_0(T)|^2}{E[n^2(t)]}$$

Choosing $h_0(t) = g(T-t)$ maximizes η

Matched Filter Receiver

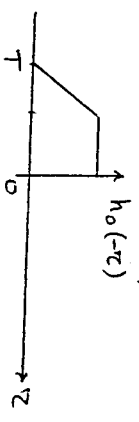


Find $g(t) * h_0(t) = g_0(t)$

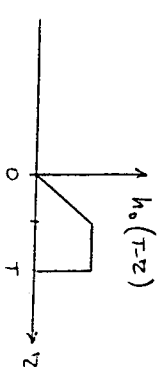
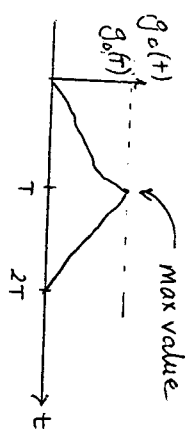
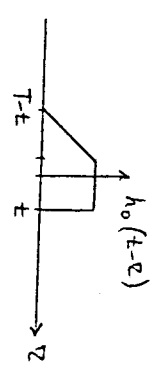


Loc (16), 0 < t < 18

$$g_0(t) = g(t) * h_0(t) = \int_{-\infty}^{\infty} g(\tau) h_0(t-\tau) d\tau$$

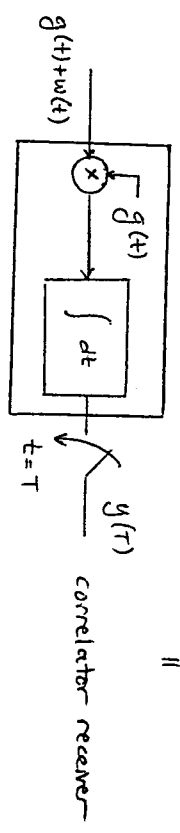
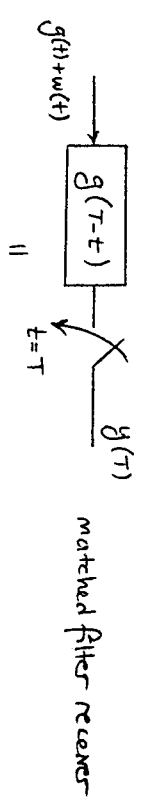


$$g_0(T) = \int_{-\infty}^{\infty} g(\tau) h_0(T-\tau) d\tau$$



$$g_0(T) = \int_{-\infty}^{\infty} g^2(\tau) d\tau = \text{energy} = E$$

Matched Filter = correlator receiver



What is η_{max} ? (η_{max} occurs when a matched filter is used)

$$\eta_{\text{max}} = \frac{|\beta_0(T)|^2}{E[n^2(t)]}$$

$$\beta_0(T) = E$$

$$E[n^2(t)] = \int_{-\infty}^{\infty} S_N(f) df$$

$$n(t) = w(t) * h(t)$$

$$S_N(f) = |H(f)|^2 S_w(f) = \frac{N_0}{2} |H(f)|^2$$

$$E[n^2(t)] = \frac{N_0}{2} \int_{-\infty}^{\infty} |H(f)|^2 df$$

$$= \frac{N_0}{2} \int_{-\infty}^{\infty} |h(t)|^2 dt = \frac{N_0}{2} E$$

$$\therefore \eta_{\text{max}} = \frac{2E}{N_0}$$

In evaluating the ability of a MF receiver to combat AWGN, we find that all signals that have the same energy are equally effective.

Effect of Amplification



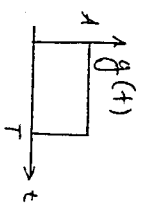
$$y'(t) = \underbrace{g(t) + h'(t)}_{g'_0(t)} + \underbrace{w(t) + k h'(t)}_{n'(t)}$$

$$= k \underbrace{g(t) * h(t)}_{g_0(t)} + \underbrace{k w(t) * h(t)}_{n(t)}$$

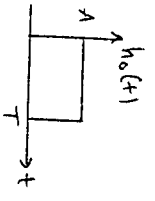
$$\eta' = \frac{|g'_0(T)|^2}{E[n'^2(t)]} = \frac{k^2 |g_0(T)|^2}{E[k^2 n^2(t)]} = \eta$$

∴ Amplification does not affect the SNR!

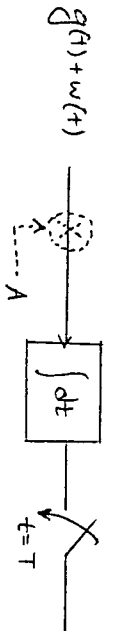
Ex:



$$h_0(t) = g(T-t)$$



Correlator Receiver Implementation



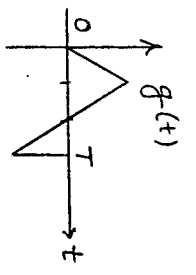
(The intuitive structure in p.31)

Integrate-and-dump circuit

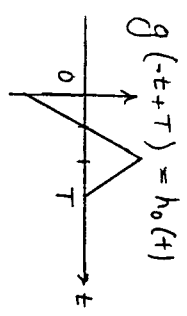
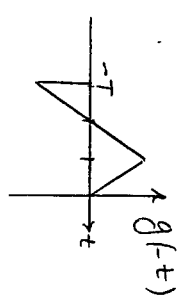
(MF for NRZ signalling)

(35)

Ex:



$$h_0(t) \triangleq g(T-t)$$

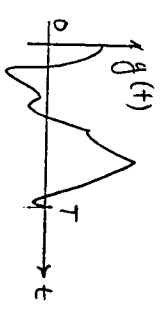


Check: $h_0(t-T) \Big|_{t=T} \stackrel{?}{=} g(t)$

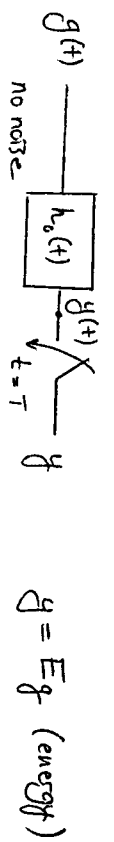
Find the MF $h_0(t)$.

(36)

Ex:



What is the MF output if there is no noise?

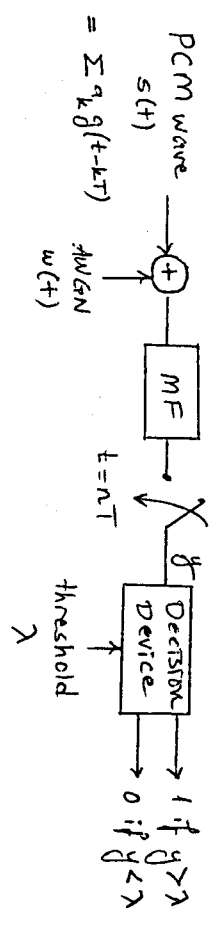


More Insight on MF

- Since amplification does not affect SNR, what is important is the shape of $h(t)$.
- Then, what shape to choose?
- Since noise is stationary, its average power is the same at all t .
- Therefore, emphasize the portion of $g(t)$ that is more robust against noise.

Receiver Structure

(37)

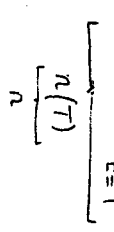


Some Insight on Threshold Selection

(a) '0's and '1's: equally likely $\rightarrow P_0 = P_1 = \frac{1}{2}$
 (ii) Antipodal signalling

1 $\rightarrow g(t)$
 0 $\rightarrow -g(t)$

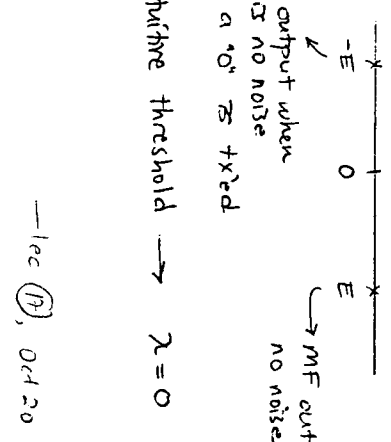
$$\Rightarrow y = \pm E + (h_0(t) * w(t))$$



$$= \pm E + n$$

MF output when there's no noise and a '1' is tried.
 and a '0' is tried.

Mutifire threshold $\rightarrow \lambda = 0$



-lec (B), Oct 20

(ii) Non-antipodal signalling

• Special case: OOK

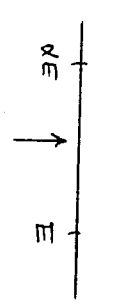
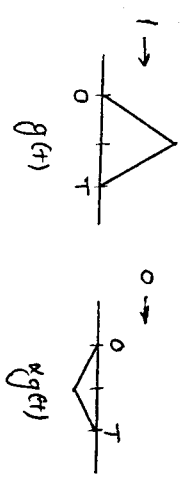
$$y = \begin{cases} E+n, & \text{if 1 tried} \\ n, & \text{if 0 tried} \end{cases}$$



Mutifire threshold $\rightarrow \lambda = \frac{E}{2}$

• general case

1 $\rightarrow g(t)$
 0 $\rightarrow \alpha g(t)$



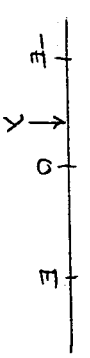
$$\lambda = \frac{\alpha+1}{2} E$$

$$h_0(t) = g(T-t)$$

Rule: For equally-likely signalling, the optimum threshold value (λ_0) is the arithmetic mean of the two possible outcomes of the MF when there's no noise.

(b) Non-equally-likely case
 Assume $P_1 \gg P_0$

antipodal \rightarrow



Limiting case $P_1=1, P_0=0 \rightarrow \lambda = -\infty$

(38)

Probability of Error Calculation

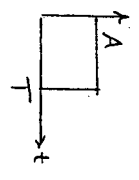
$$P_e = \underbrace{P(0|1)} P_1 + \underbrace{P(1|0)} P_0$$

Prob of sending a "1" but deciding for a "0" P_F (false alarm)

P_M (miss)

Assumptions

- perfect channel
- AWGN with $N_0/2$ and zero-mean
- MF receiver
- antipodal signalling with $g(t)$



$E_b = A^2 T$ (bit energy)

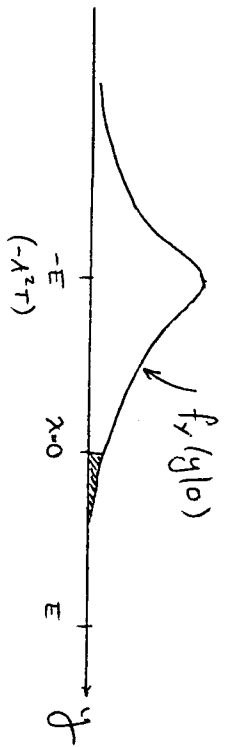
$y(y_{\text{thresh}}) = -A^2 T + n$

$$n = w(t) * h_0(t) = \int_{-\infty}^{\infty} w(\tau) h(T-\tau) d\tau$$

$w(t)$: Gaussian process \rightarrow $n(t)$: Gaussian process \rightarrow n : Gaussian rv

$\mu_n = H(0) \mu_w = 0$

- the decision variable y is a rv.
- If we know the mean and variance of y , we can readily obtain its pdf.



$$P_F = P(1|0) = \int_{-\infty}^0 f_y(y|0) dy$$

$y = \underbrace{-A^2 T + n}_{\text{constant}} \rightarrow G(0; \sigma_n^2)$

$\rightarrow y: G(-A^2 T; \sigma_n^2)$

$$\sigma_n^2 = E[n_1, n_2] = E \left[A^2 \int_0^T w(t)w(u) dt du \right]$$

$$= A^2 \int_0^T \int_0^T E[w(t)w(u)] dt du$$

$$= A^2 \int_0^T \int_0^T R_w(t,u) dt du$$

$$= A^2 \int_0^T \left(\frac{N_0}{2} \int_0^T \delta(t-u) dt \right) du$$

$$= \frac{A^2 N_0}{2} \int_0^T du = \frac{A^2 T N_0}{2}$$

$$\rightarrow f_y(y|0) = \frac{1}{\sqrt{2\pi A^2 T N_0}} e^{-\frac{(y + A^2 T)^2}{2 A^2 T N_0}}$$

$$P_F = P(1|0) = \int_0^\infty \frac{1}{\sqrt{2\pi A^2 T N_0}} e^{-\frac{(y + A^2 T)^2}{2 A^2 T N_0}} dy$$

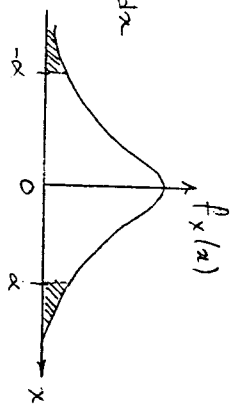
There is no closed form expression for the above integral.

Define a new function $\text{erfc}(x)$... complementary error function

$\text{erfc}(x)$ = area under the tails of a Gaussian r.v. with $\mu=0$ and $\sigma^2=1/2$.

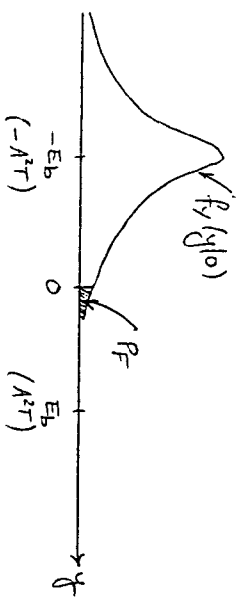
$$f_x(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$$

$$\text{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_x^\infty e^{-x^2} dx$$



$\text{erfc}(x)$ = sum of the shaded areas

Our case:

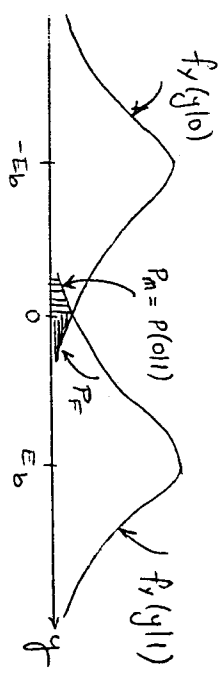


define $u = \frac{y + A^2 T}{\sqrt{A^2 T N_0}}$ $du = \frac{dy}{\sqrt{A^2 T N_0}}$

$$P_F = \int_0^\infty \frac{1}{\sqrt{2\pi A^2 T N_0}} e^{-u^2} \sqrt{A^2 T N_0} du$$

$$P_F = \frac{1}{\sqrt{\pi}} \int_0^\infty e^{-u^2} du = \frac{1}{2} \text{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right)$$

Note that $P_e = P(0|1)P + P(1|0)P_0$



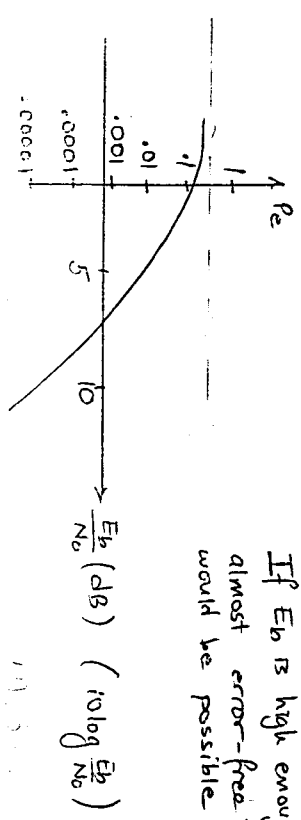
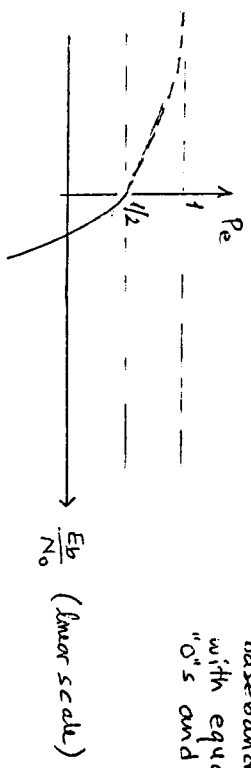
$$y(\text{given } 1) = A^2 T + n$$

By inspection: $P_M = P_F = \frac{1}{2} \text{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right)$

$$P_e = \frac{1}{2} P_M + \frac{1}{2} P_F$$

$$P_e = \frac{1}{2} \text{erfc} \left(\sqrt{\frac{E_b}{N_0}} \right)$$

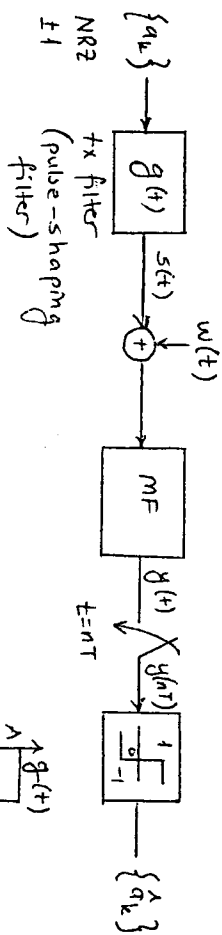
performance of MF receiver with any antipodal baseband scheme with equally-likely "0"s and "1"s.



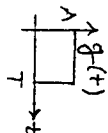
If E_b is high enough, almost error-free transmission would be possible

Mini Review (Noise Performance)

(43)



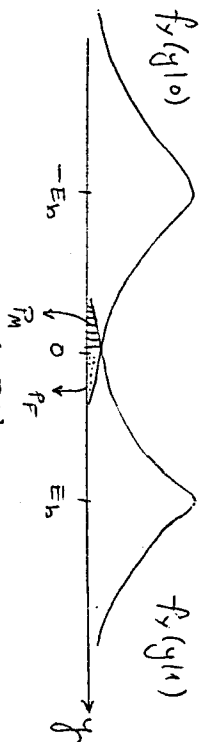
$$P_e = P(a_k \neq \hat{a}_k) = P(0|1)P_1 + P(1|0)P_0$$



$$y = \pm E_b + n \rightarrow G(0, \sigma_n^2)$$

$$\rightarrow G(\pm E_b, \sigma_n^2)$$

Find the pdfs of $y|0$ and $y|1$, and compute P_M and P_F .

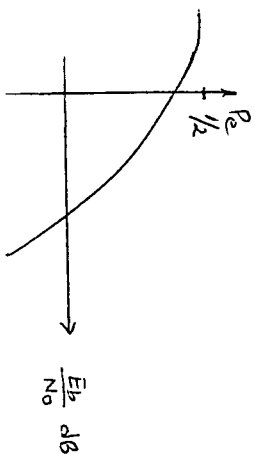


$$P_F = \int_0^{\infty} \frac{1}{\sqrt{2\pi\sigma_n^2}} e^{-\frac{(y+E_b)^2}{2\sigma_n^2}} dy$$

$$\frac{y+E_b}{\sqrt{2}\sigma_n} = u \rightarrow P_F = \frac{1}{\sqrt{\pi}} \int_0^{\infty} e^{-u^2} du = \frac{1}{2} \operatorname{erfc}\left(\frac{E_b}{\sqrt{2}\sigma_n}\right)$$

$$\sigma_n^2 = \frac{N_0}{2} E_b$$

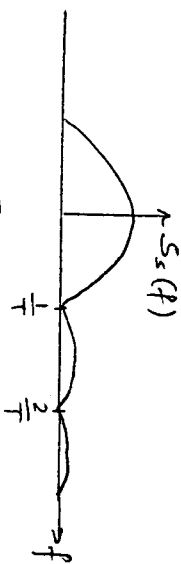
$$P_e = \frac{1}{2} \operatorname{erfc}\left(\sqrt{\frac{E_b}{N_0}}\right)$$



Observations

(44)

- 1) For NRZ, instead of the matched filter, we could have used an integrate-and-dump ckt; performance should be the same (CHECK!)
- 2) Performance depends on E_b/N_0 ; all pulse shapes that have the same energy will yield the same performance.
- 3) Note that $S_S(f) \propto |G(f)|^2$



$$\text{Average Signal Power} = \frac{E_b}{T} = A^2$$

$$\text{Signal BW} \approx \frac{1}{T}$$

$$\text{Noise Power in signal BW} = \frac{N_0}{2} \times 2 \times \frac{1}{T} = \frac{N_0}{T}$$

$$\frac{\text{signal power}}{\text{noise power in signal BW}} = \frac{A^2}{N_0/T} = \frac{A^2 T}{N_0} = \frac{E_b}{N_0} = \text{SNR}$$

- 4) Performance improves if
 - a) E_b is increased
 - b) bandwidth is decreased (for a given power)

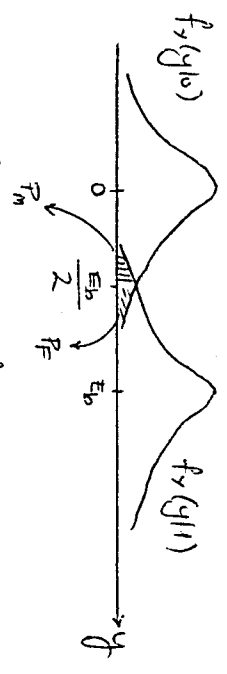
- 5) Performance improves drastically with a moderate increase in E_b . If the quantization error is unnoticeable, the original analog signal can be reconstructed by almost no error. (Regenerative repeaters)
- Note that this cannot be said for analog communications.

Noise performance for OOK (Prob. 7.4)

(45)

- Same structure with $a_k \in \{0, 1\}$

$$y = \begin{cases} E_b + n \\ n \end{cases}$$



$$P_F = \int_{E_b/2}^{\infty} \frac{1}{\sqrt{2\pi\sigma_n^2}} e^{-\frac{y^2}{2\sigma_n^2}} dy$$

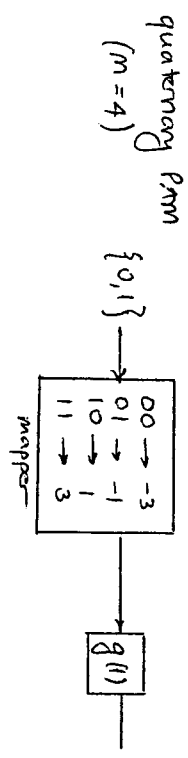
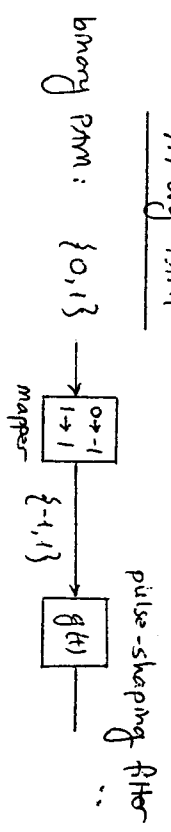
$$u = \frac{y}{\sqrt{2}\sigma_n} \rightarrow P_F = \int_{\frac{E_b}{2\sqrt{2}\sigma_n}}^{\infty} \frac{1}{\sqrt{\pi}} e^{-u^2} du$$

$$P_e = \frac{1}{2} \operatorname{erfc}\left(\frac{E_b}{2\sqrt{2}\sigma_n}\right) = \frac{1}{2} \operatorname{erfc}\left(\frac{1}{2}\sqrt{\frac{E_b}{N_0}}\right)$$

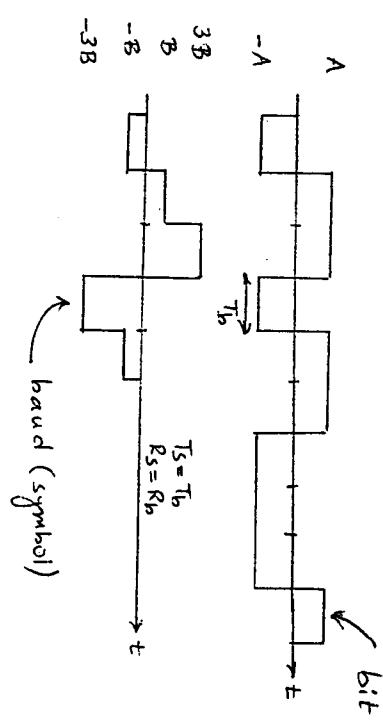
In order that OOK and NRZ schemes have the same error performance, $E_{b,OOK} = 4 E_{b,NRZ}$

M-ary PPM

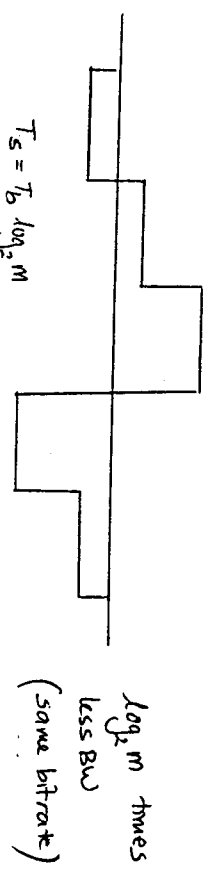
(46)



0110110001



1 hand = $\log_2 m$ bits



$$T_s = T_b \log_2 m$$

$$R_s = R_b \frac{1}{\log_2 m}$$

In order to have the same performance as binary PPM, the transmit power must be increased by a factor of $m^2 / \log_2 m$ in an M-ary PPM scheme.