# **CARLETON UNIVERSITY** Department of Systems and Computer Engineering

## SYSC 4600 – Digital Communications – Fall 2012

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Full mark: 115 points - closed-book, one-page aid-sheet and calculators are allowed - 80 mins

### **Question 1 (40 pts) – Short Questions**

- (5 pts) State the two major impairments in a digital communications system.
- (5 pts) Explain what "impulse response" means.
- (5 pts) Write the impulse response of an ideal channel.
- (5 pts) Sketch the power spectral density (PSD) of white noise.
- (10 pts) There is a linear time-invariant (LTI) channel with impulse response h(t). The input and output of the channel are denoted by x(t) and y(t), respectively. Write the output in terms of the input and channel
  - o in time domain,
  - o in frequency domain.

If the input is a random process with PSD  $S_X(f)$ , write the output PSD,  $S_Y(f)$ .

• (10 pts) We have two signals x(t) and y(t); the former one is a baseband signal and the latter a bandpass signal. The Fourier transforms of these signals, X(f) and Y(f), are given as follows:

 $X(f) = \begin{cases} \alpha, & -3MHz \le f \le 3MHz \\ 0, & elsewhere \end{cases} \text{ and } Y(f) = \begin{cases} \beta, & -200MHz \le f \le -150MHz \\ \beta, & 150MHz \le f \le 200MHz \\ 0, & elsewhere \end{cases}$ 

Find the bandwidths of these two signals.

#### Question 2 (50 pts) – Probability of Error Analysis

Consider binary signalling with AWGN (power spectral density =  $N_0/2$ ), in the presence of a shortcircuit channel. The information bits are equally-likely; the transmission rate is R = 1/T bits/sec. The transmitter filter and the matched receiver filter impulse responses are given below:

$$h_{TX}(t) = \begin{cases} A, & 0 \le t \le T \\ 0, & elsewhere \end{cases} \text{ and } h_{RX}(t) = h_{TX}(T-t) = \begin{cases} A, & 0 \le t \le T \\ 0, & elsewhere \end{cases}$$

The receiver filter is followed by a sampler (which samples at every T sec), which is followed by a threshold detector.

We will compare two signalling schemes in which the information bits 0 and 1 are mapped to binary *a* values differently to amplitude-modulate the transmitter filter.

• The first scheme, Scheme I, uses antipodal signalling. This scheme has been extensively studied in the class: The information bits 0 and 1 are mapped to -1 and 1, respectively;  $0 \rightarrow a = -1$ i.e.,  $1 \rightarrow a = 1$ 

In this scheme, the optimum threshold value of the detector is  $\lambda_{th,I} = 0$ . It can be shown that the average bit energy is  $E_{b,av,I} = A^2T$ , and the corresponding probability of error is

$$P_{e,I} = \frac{1}{2} \operatorname{erfc}\left(\sqrt{\frac{A^2T}{N_0}}\right) = \frac{1}{2} \operatorname{erfc}\left(\sqrt{\frac{E_{b,av,I}}{N_0}}\right)$$

- In Scheme II, the amplitude-modulation is performed through the following mapping:  $0 \rightarrow a = -0.5$  $1 \rightarrow a = 1.5$
- (a) By inspection, find the optimum threshold value in Scheme II:  $\lambda_{th,II}$ . Substantiate your decision.
- (b) Find  $P_{e,II}$  in terms of A, T, and  $N_0$ . Then, express  $P_{e,II}$  in terms of  $E_{b,av,II}$  and  $N_0$ .
- (c) Discuss which of the two schemes is better in terms of error performance by how many dBs.

Note: 
$$erfc(u) = \frac{2}{\sqrt{\pi}} \int_{u}^{\infty} e^{-z^2} dz$$
.

### Question 3 (25 pts) – Rate versus Reliability

The probability of error (bit error rate) for the binary antipodal system denoted as Scheme I in Question 2 is given by  $P_e = \frac{1}{2} erfc \left( \sqrt{\frac{A^2T}{N_0}} \right) = \frac{1}{2} erfc \left( \sqrt{\frac{E_b}{N_0}} \right)$ ; this expression is plotted below.



For the proper running of an application, it is required that  $P_e < 2x10^{-4}$ . If the received pulse amplitude is  $A = 1x10^{-6}$ , find the maximum possible bit rate.

Note: The noise PSD is  $N_0 = k \ge 7$  and  $N_0 = k \ge 7$  by Joules, where k is the Boltzmann constant ( $k = 1.38 \ge 10^{-23}$  J/K) and *Temp* is the temperature in Kelvin (assume *Temp* = 293 K, which corresponds to the room temperature).