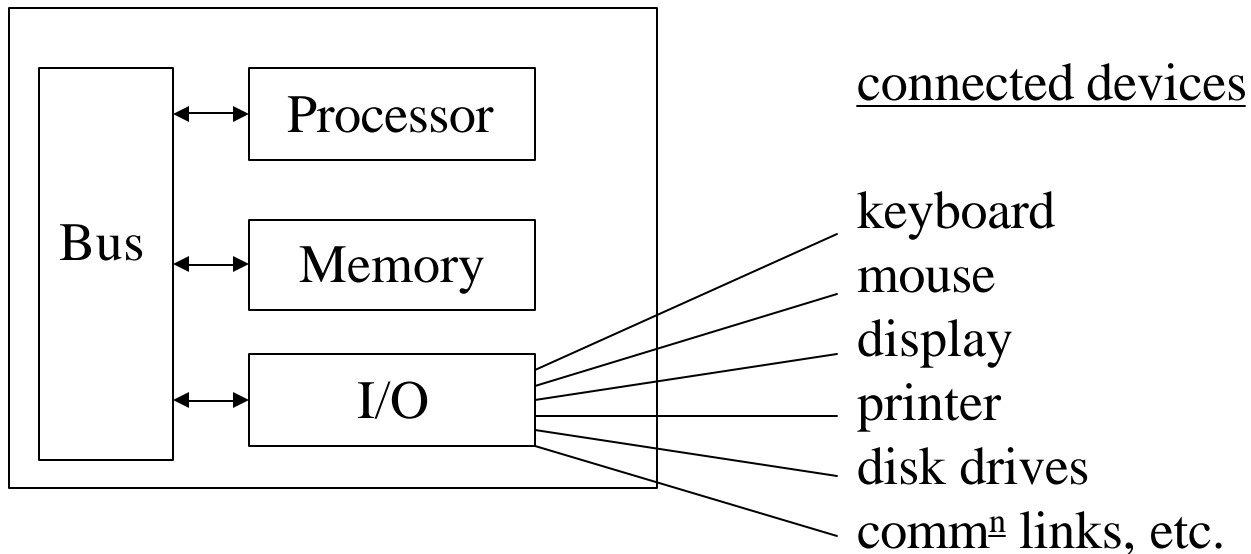


Parallel Input/Output

Basic Concepts of I/O

- **Input/Output** is the information exchange between CPU and (external) connected devices
- Block Diagram of a Simple Computer System

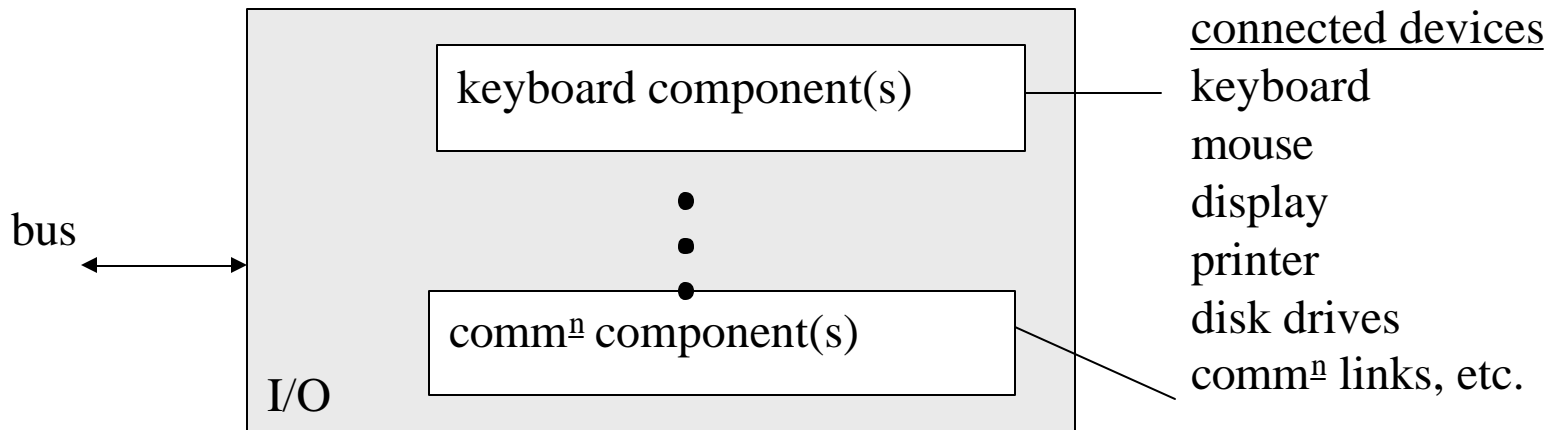


Basic Concepts of I/O

- Interfacing and programming I/O devices: different from our previous programs
 - Electrical characteristics different from CPUs
 - Analog devices, power, current drive
 - I/O devices operate **asynchronously** from the CPU (and the program being run)
 - Transfer data: processor and I/O device **synchronize** or “handshake” to exchange information

Basic Concepts of I/O

- Independent I/O **components** associated with each connected device.



- I/O components: interfaces that “electrically” connect external device to computer’s internal bus.
 - Bus connection allows CPU to read and/or write device

I/O Ports

- Port: allows exchange of information between bus (connected to CPU and memory) and I/O components (connected to devices)
- 3 kinds of Ports:
 - **Control**: write values to these – control behaviour of component/device
 - **Status**: read values from these – find out about current state of component/device
 - **Data**: read and/or write values of these – exchange application information
- Some ports: read-only, write-only or read&write.
- Ports: often bit-mapped.

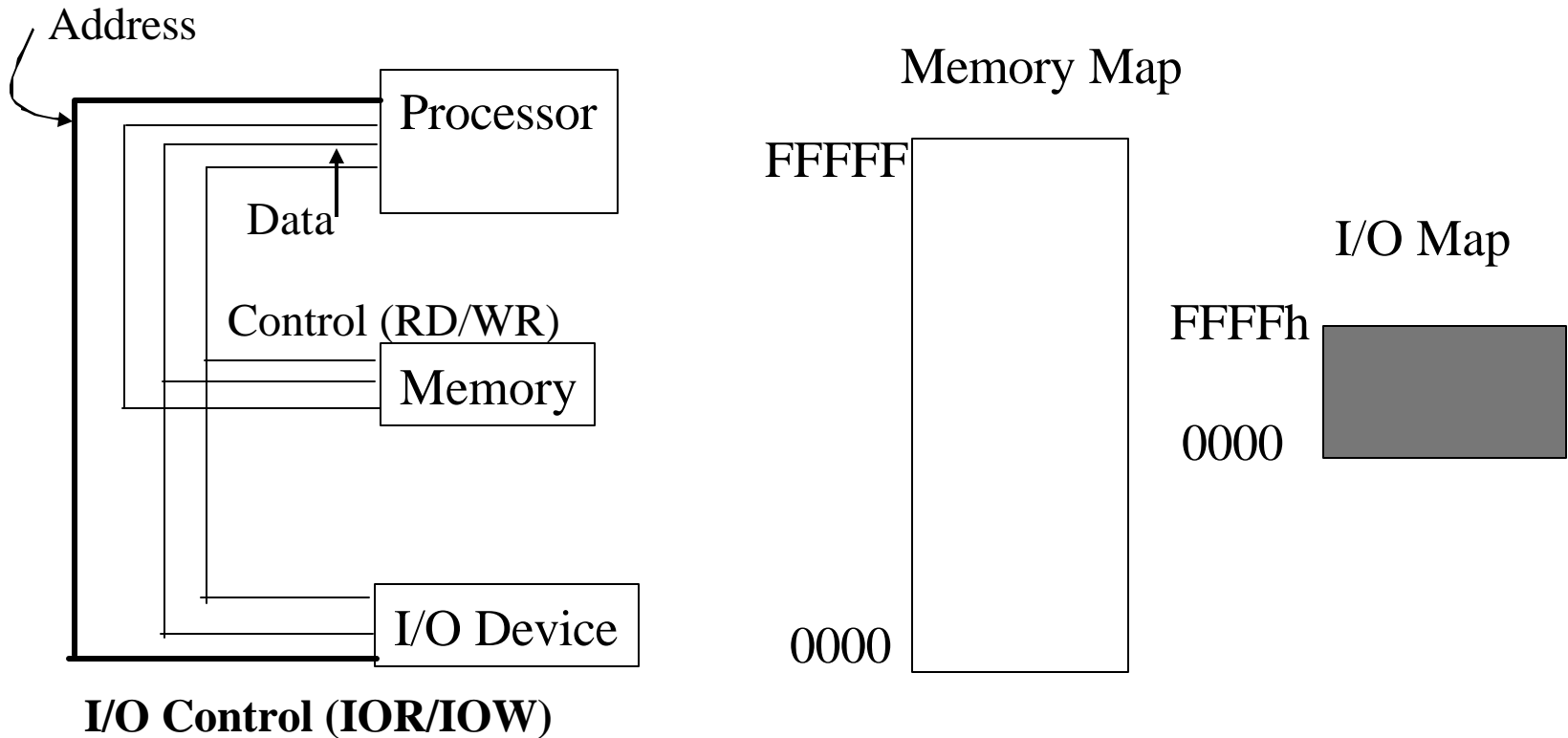
I/O Addresses

- When connected to a computer system, each port is assigned an I/O address
 - Device (port) identified by its **I/O addresses**
 - CPU read/write from/to I/O address to receive/send data from/to device
- Microprocessor architectures: two kinds of I/O addresses
 1. Isolated I/O
 2. Memory-Mapped I/O

Concept !

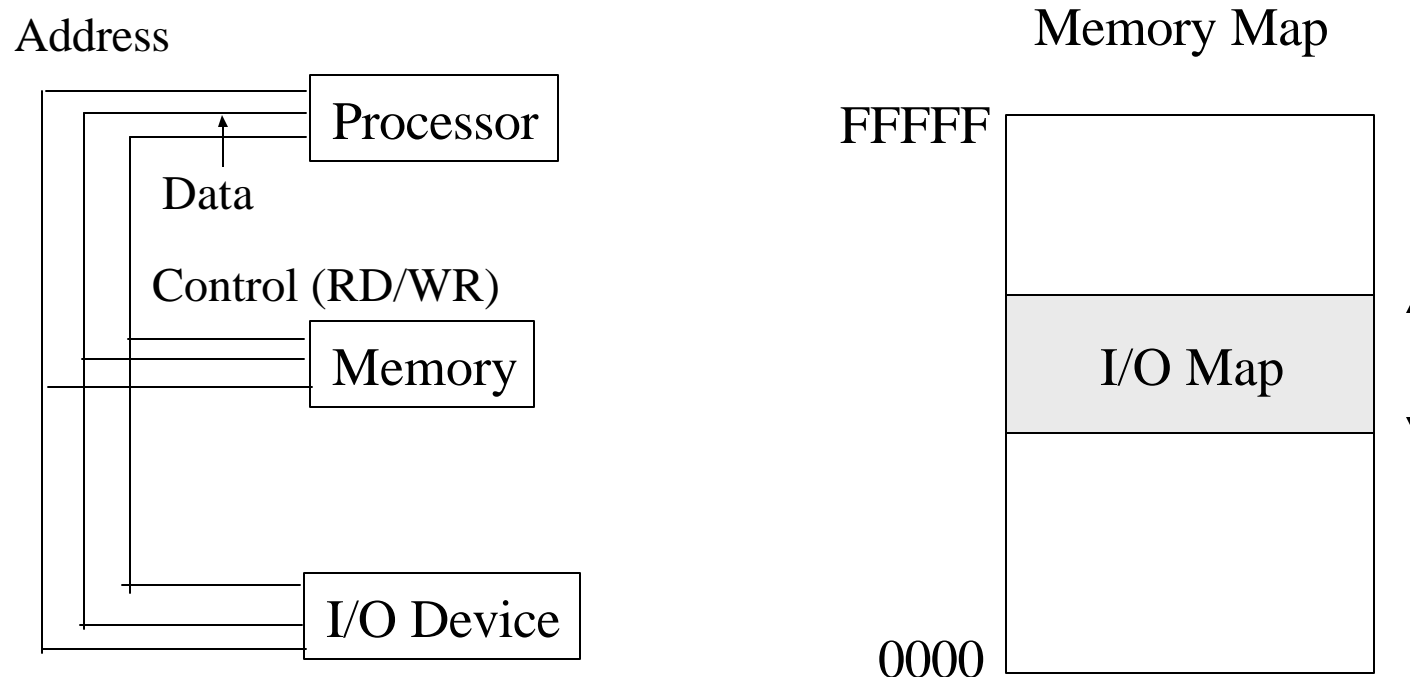
I/O Addressing Schemes : Isolated I/O

- Microprocessor: **dedicated instructions** for I/O operations.
- Separate address space for I/O devices.



I/O Addressing Scheme : Memory Mapped I/O

- Microprocessor: same instruction set to perform **memory and I/O** operations.
- I/O devices and memory components resident in same memory space.



Intel *Uses* Isolated I/O

Implementation
of a Concept

- 80x86 family, I/O addresses range 0-FFFFh
- PC: devices assigned standard I/O addresses (used by all manufacturers of PCs)
 - Keyboard 60h
 - Speaker 61h
 - Parallel Printer (LPT1) 3BCh-3BFh

I/O ports ¹ memory cells

- Memory transfers : `MOV AL, [61h]`
- I/O transfers :
`IN AL, 61h`
`OUT 61h, AL`

Intel 8086 IN Instruction

Mnemonic : IN

Semantics : Read from I/O port

Syntax :

IN AL, imm8 ← 8-bit read

IN AX, imm8 ← 16-bit read

– imm8: 8-bit I/O address in the range 00h-FFh

IN AL, DX

IN AX, DX

– DX: 16-bit I/O address in the range 0000h-FFFFh

Legacy of 8085
which had an 8-bit
I/O space

Addressing Modes are different!

Intel 8086 OUT Instruction

Mnemonic OUT

Semantics : Write to I/O port

Syntax :

Destination looks like immediate!

OUT imm8 , AL ← 8-bit write

OUT imm8 , AX ← 16-bit write

OUT DX , AL

OUT DX , AX

I/O Example

- We have a display device for ASCII characters
- Programmer's model: one write-only data port at I/O
Address = 04E9H
 - Display “cursor driven”: ASCII character written to data port displayed at current cursor position
 - Cursor position maintained by the display device
 - When a character is written, cursor position is “advanced”
 - Advancement handles new lines and scrolling too.
- Write a code fragment showing the display of the character ‘A’

I/O Example

Solution : Write a code fragment showing the display of the character 'A'

```
MOV    DX, 04E9H
```

```
MOV    AL, 41h
```

```
OUT    DX, AL
```

```
...
```

A character is a byte

This port address is 16 bits.
Must load it into DX first
(Immediate only for 8-bit port
addresses)

Question :

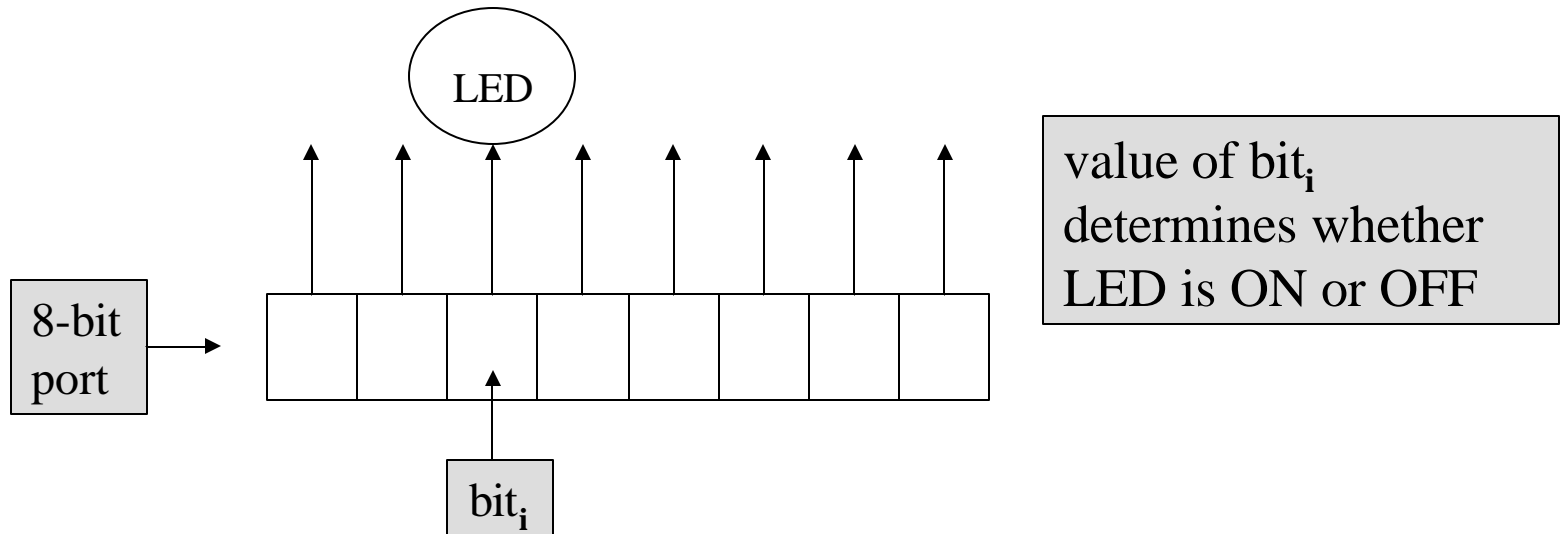
```
...
```

```
IN      AL, DX
```

Will AL contain 41H ?

Lab PC's LED/Switch Box

- Labs: I/O Box attached to PCs
 - 5 LEDs (Light Emitting Diodes) – each either ON or OFF
 - 5 switches – each either ON or OFF
- **LEDs** connected to bits of an 8-bit **output** parallel port
 - Each LED driven by a particular bit in the port



Programmer's Model for the Lab LEDs

- LED data port address: 378 H
- Bit configuration: LEDs are labelled 1 .. 5
 - [bit 7 = most significant ; bit 0 = least significant]
- | | | | | | | | |
|-------|---|---|---|---|---|---|---|
| bit 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| LED x | x | x | 5 | 4 | 3 | 2 | 1 |

 - 1 through 5 indicate bits for LEDs 1 through 5
 - x indicates unused (don't care what value is written)
- To turn LED ON: set bit associated with the LED
 - i.e.: write 8-bit value to port; bit associated with LED = 1
- To turn LED OFF: clear bit associated with LED

Programming the LEDs

- LED's interface: 8-bit port.
 - If we want to set/clear a particular bit, we must write an entire byte to the LED port.
 - Writing any value to the LED port affects all LEDs !
 - Modify the state of one LED: must know state of all LEDs, but ...
- Reading port is meaningless (write-only port)
 - We cannot read LED port to get the current state of all LEDs.

Programming the LEDs

- To manipulate LEDs individually, program must keep state of LEDs as a variable
 - updated each time a value is written to the LED port

```
LED_State      DB  ?      ; current state of LEDs
; To turn on LED x
    ; set appropriate bit in LED_State
    ; write LED_State to LED port
; To turn off LED x
    ; Clear the appropriate bit in LED_State
    ; Write LED_State to the LED port
```

Lab Switches

- 5 switches on the I/O box connected to 5 bits of 8-bit input parallel port
 - One bit (in port) per switch
 - Read-only port used to get current setting of all switches
 - A write to the port has no effect
 - Switch is ON, its bit is set (i.e. "1")
 - Switch is OFF, its bit is clear (i.e. "0")
 - Switches labelled "A" through "E"

- Switch data port address: 379 H

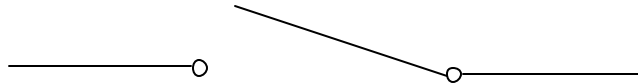
Bit config: [bit 7 = most signif ; bit 0 = least signif]

bit	7	6	5	4	3	2	1	0
Switch	E	D	C	B	A	x	x	x

- x indicates unused (undefined)

Switch de-bouncing

- Switch: mechanical device
 - Moving switch position: opens/closes circuit
 - Switches: metal contacts completing circuit when joined



- Switches in the lab: spring-loaded to hold open/closed position
 - When position change, contacts can bounce
- Program reading switch port, “value” of switch output will oscillate (open/closed) until bouncing stops
 - Program must filter out oscillations so that program only “sees” one switch state change per position change.
This is called de-bouncing.

Simple De-Bouncing

- Write a loop that polls the switch until first change is seen
- Waste “enough” time (do-nothing-loop) until sure switch stopped bouncing
- Questions :
 - How much is “enough” time?
 - What if the program waits longer than necessary?
 - What if the program does not wait long enough ?

Adaptive De-Bouncing

In a loop, poll the switch until first change is seen

Set a loop counter to an `init_value`

Repeat {

 Poll switch

 If (switch has changed state again) {

 loop counter = `init_value`

 } else {

 decrement loop counter

 }

} until loop counter == 0

Explain why this approach is “adaptive” ?

Remaining Issue : Decide on the `init_value`